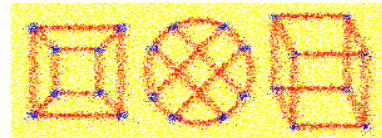


# Complexity of the Planar Slope Number Problem

Utrecht Seminar · 8th June 2021  
Paul Jungeblut



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## On the Complexity of the Planar Slope Number Problem

*Udo Hoffmann*

Université libre de Bruxelles (ULB)

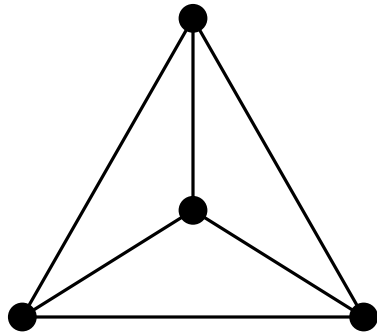
### Abstract

The *planar slope number* of a planar graph  $G$  is defined as the minimum number of slopes that is required for a crossing-free straight-line drawing of  $G$ . We show that determining the planar slope number is hard in the *existential theory of the reals*. We discuss consequences for drawings that minimize the planar slope number.

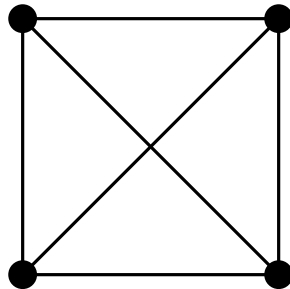
# Slope Number - Definition

## Slope Number

Given a graph  $G$ . The *slope number* is the minimum number of slopes needed in a straight-line drawing of  $G$ .



6 slopes



4 slopes

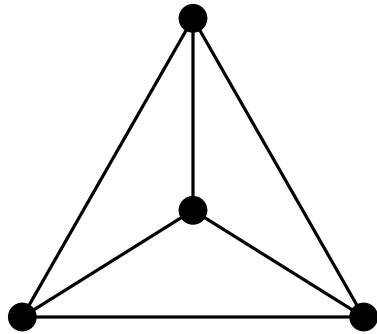
## Planar Slope Number

↪ only consider planar drawings

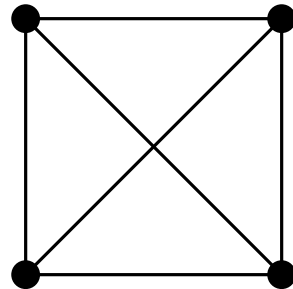
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## Complete Graphs

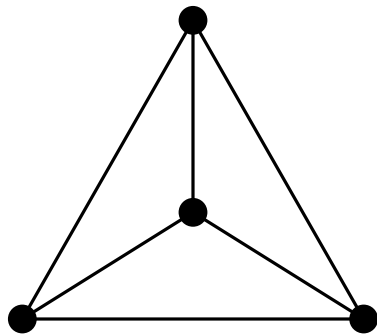
- $K_n$  requires exactly  $n$  slopes.  
Wade, Chu '94



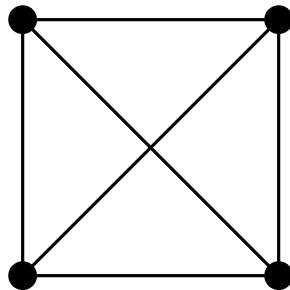
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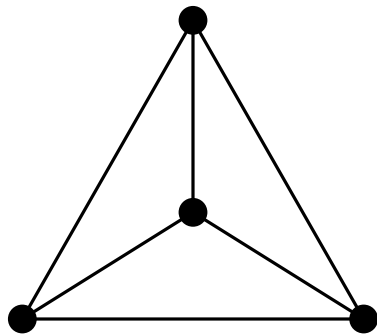
## Maximum Degree $\Delta$

- Lower bound:  $\frac{\Delta}{2}$   
At most two edges incident to each vertex can have the same slope.
- $\Delta = 3$ : 4 slopes are enough.  
Mukkamala, Szegedy '09
- $\Delta = 5$ : unbounded  
Barát, Matoušek, Wood '06  
Pach, Pálvölgyi '06
- $\Delta = 4$ : unknown

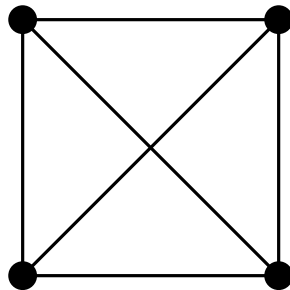
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## Planar Graphs

- Exponential in the maximum degree  $\Delta$ .  
Keszegh, Pach, Pálvölgyi '11
- Decision problem  $\exists\mathbb{R}$ -complete.  
Hoffmann '17

**Theorem:** (Hoffmann '17)

Deciding whether a graph  $G$  has planar slope number  $k$  is in NP for each fixed  $k$ .

**Theorem:** (Hoffmann '17)

Deciding whether the planar slope number is exactly  $\frac{\Delta}{2}$  is  $\exists\mathbb{R}$ -complete.

## Definition: Existential Theory of the Reals

The *existential theory of the reals (ETR)* consists of all true sentences of the form

$$\exists X_1, \dots, \exists X_n : \Phi(X_1, \dots, X_n)$$

where  $\Phi$  is a quantifier free formula of polynomial (in)equalities with integer coefficients.

$$\exists X_1 \exists X_2 : X_1^2 + 3 \cdot X_2 = 7 \wedge X_1 > X_2$$

Solutions:  $(X_1, X_2) = (2, 1), (-5, -6), \dots$

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## Definition: $\exists\mathbb{R}$

The class  $\exists\mathbb{R}$  contains all decision problems that can be reduced to ETR in polynomial time.

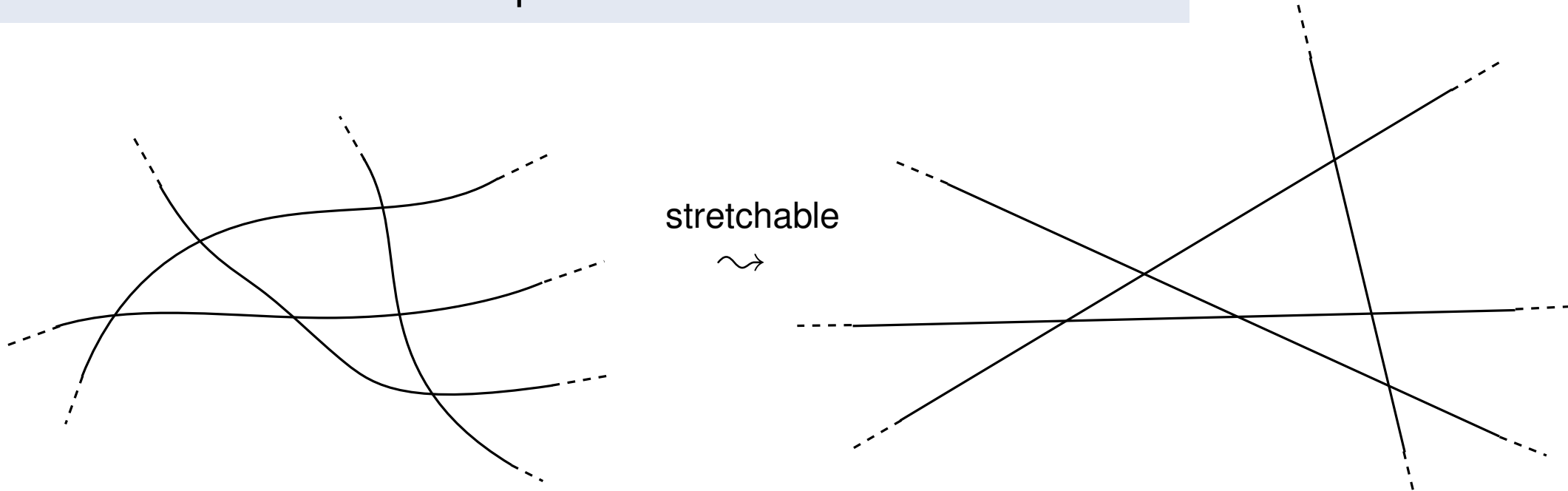
$$\text{NP} \subseteq \exists\mathbb{R} \subseteq \text{PSPACE}$$

# Stretchability

**Problem:** STRETCHABILITY

**Input:** Arrangement of pseudolines  $L$ .

**Question:** Is  $L$  *stretchable*? I.e. is there a line arrangement with the same intersection pattern?

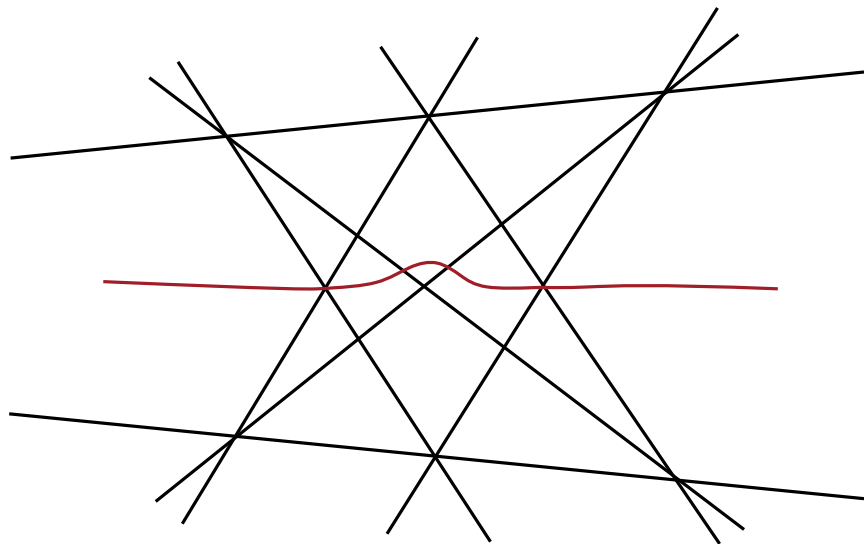


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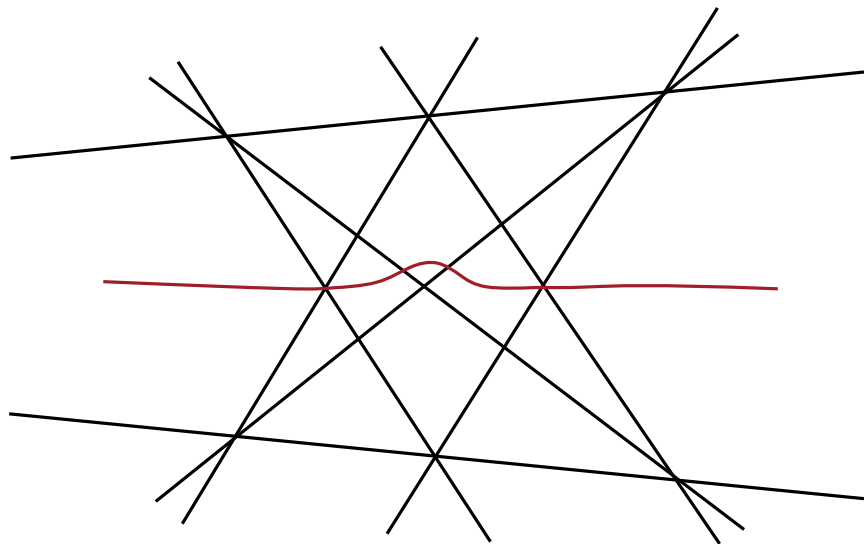
not stretchable  
(by Pappu's Hexagon Theorem)

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**Theorem:** (Mnëv '88)

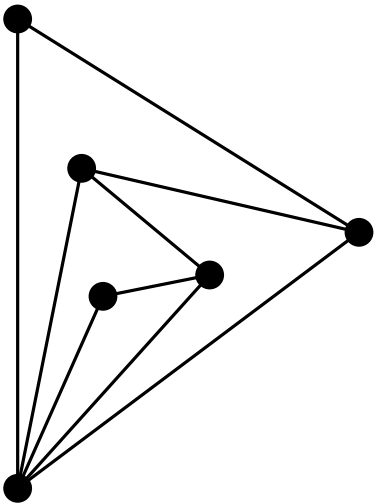
STRETCHABILITY is  $\exists\mathbb{R}$ -complete.



# $k$ -Slope Drawings - Fixed $k$

**Theorem:** (Hoffmann '17)

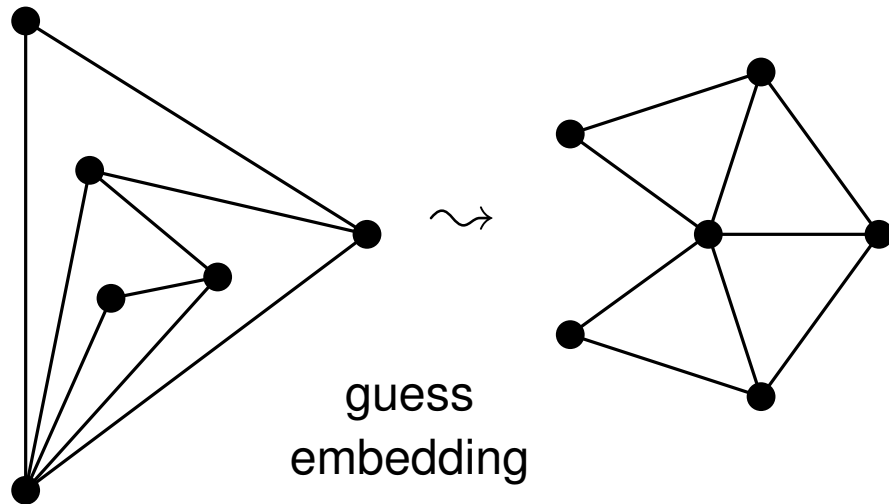
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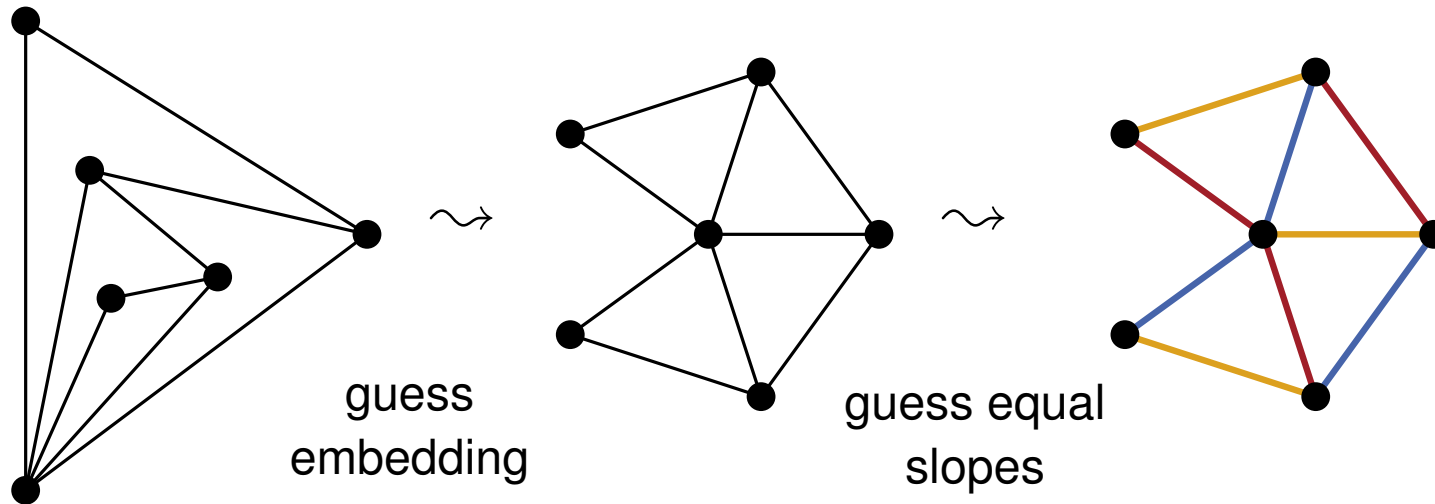
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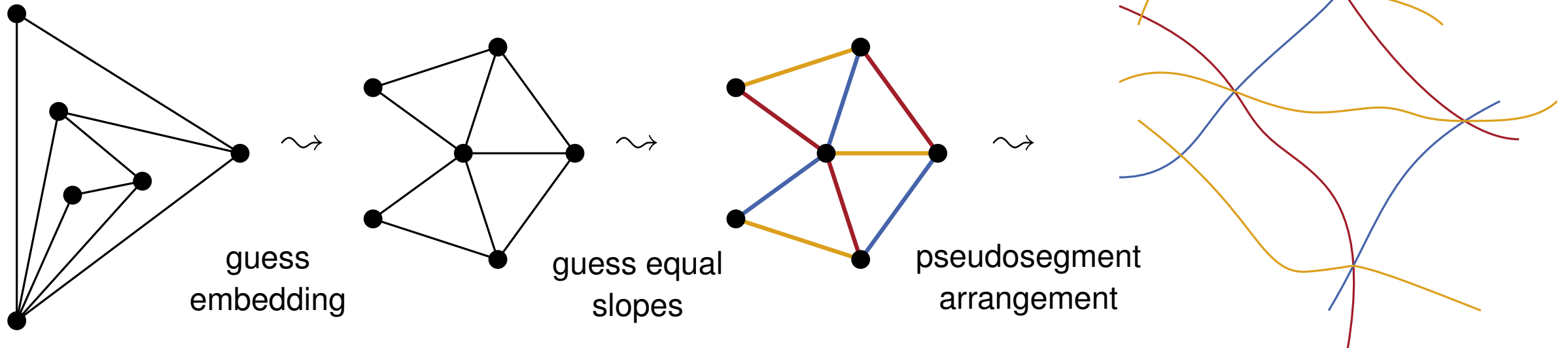
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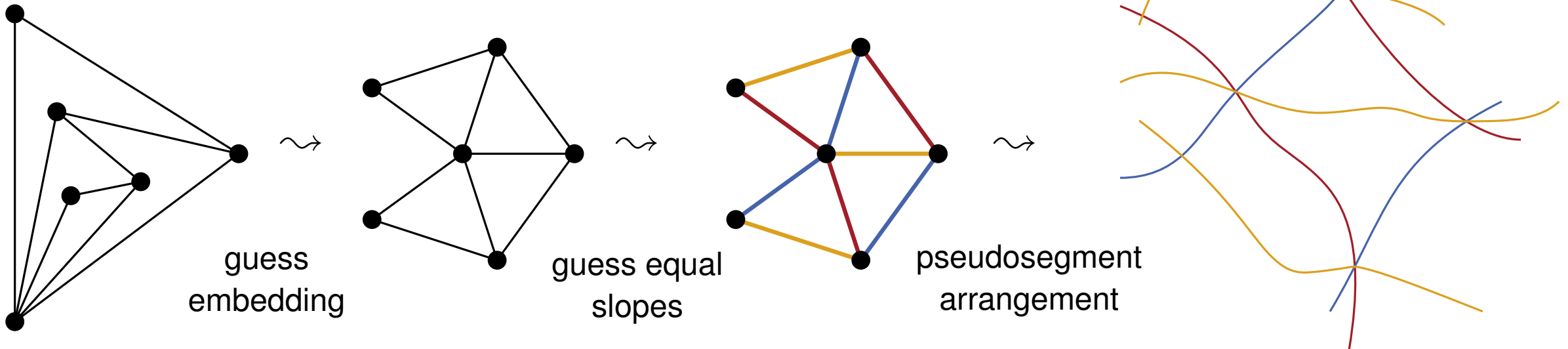
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**Theorem:** (Kratochvíl, Matoušek '94)

STRETCHABILITY of a pseudosegment arrangement with at most  $k$  slopes is in NP. ( $k$  fixed)



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## $\exists\mathbb{R}$ -Membership:

- Poly-time verification algorithm in the real RAM model.  
Erickson, Hoog, Miltzow 2020
- Given a drawing (coordinates of the vertices):  
Compute and count slopes.

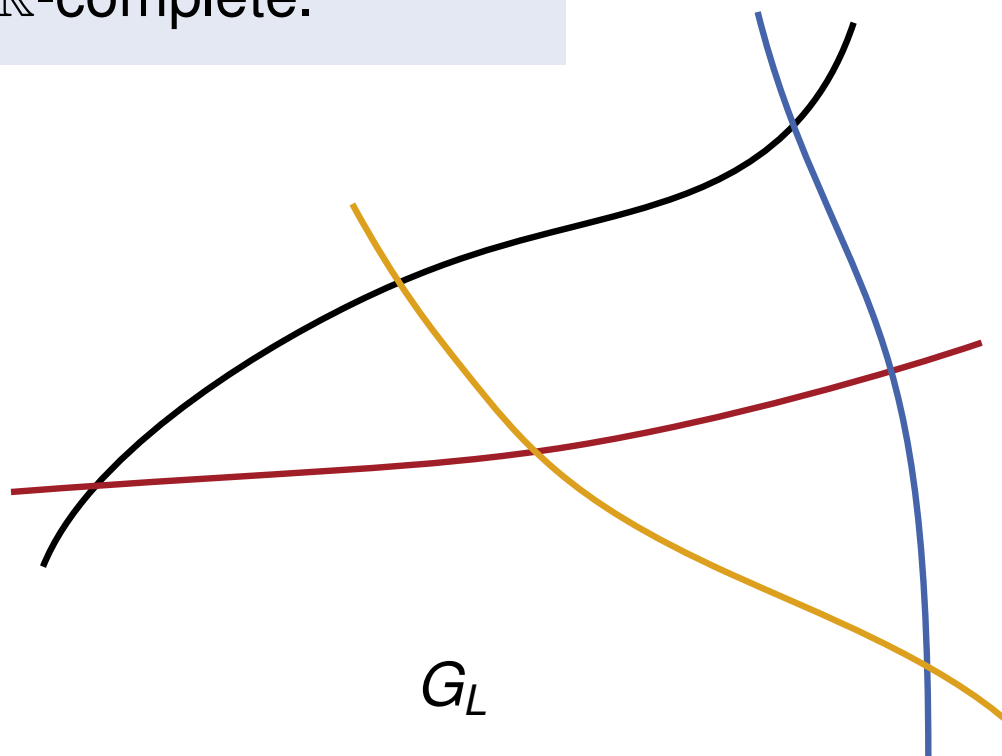
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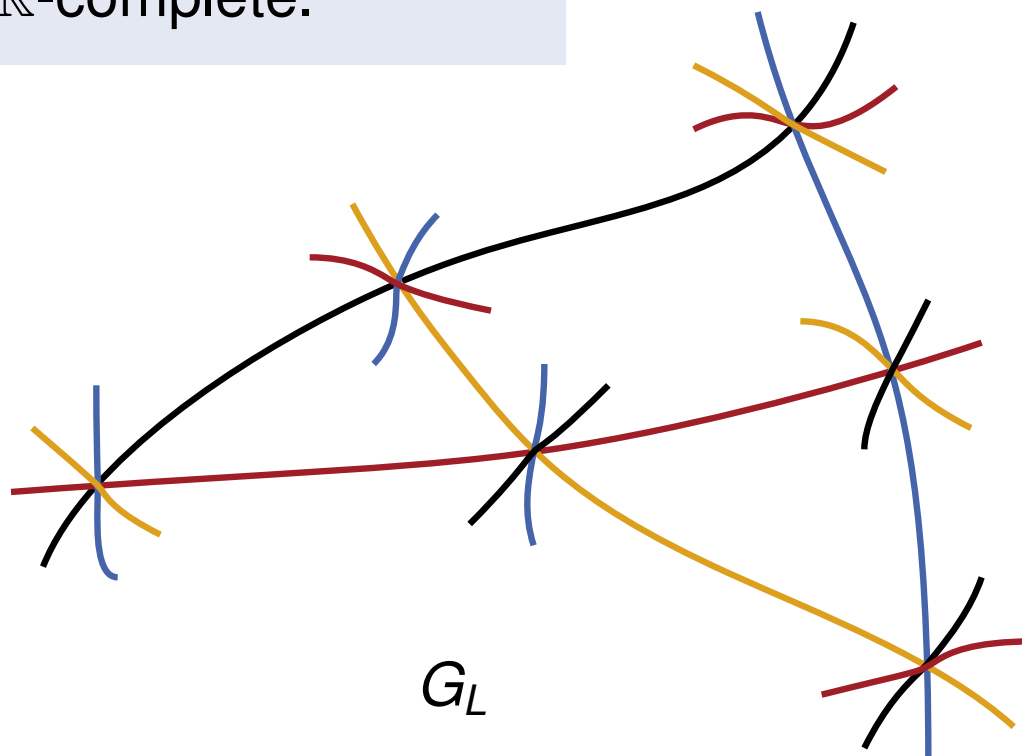
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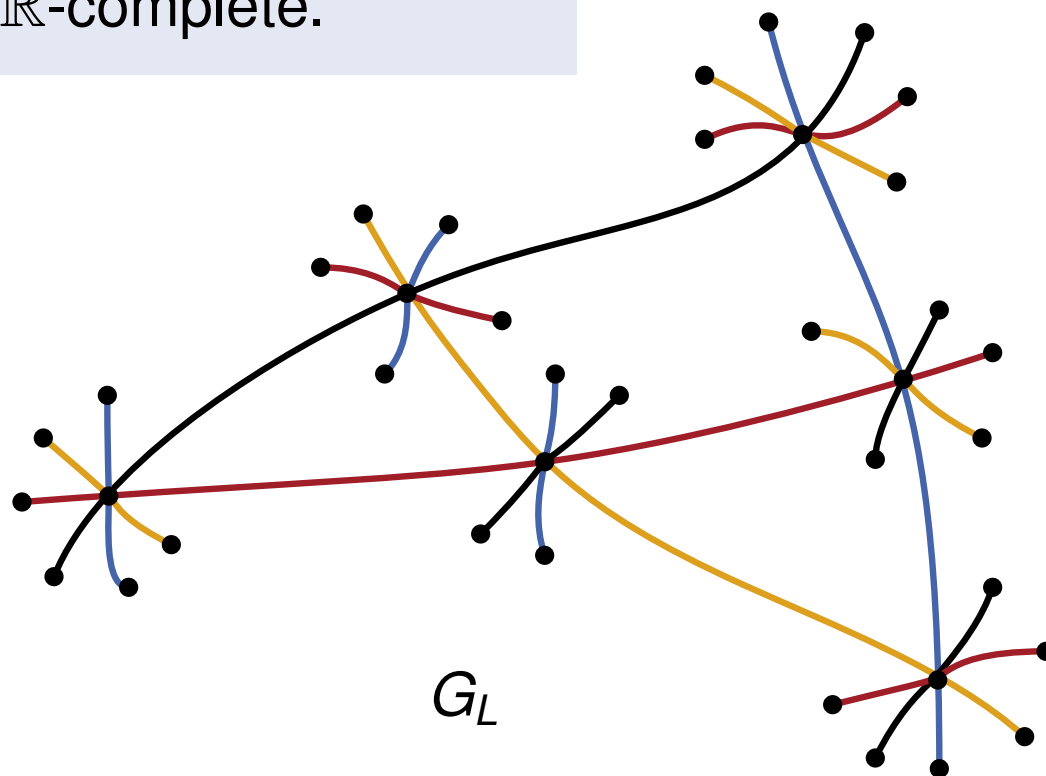
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$L$  stretchable  $\Rightarrow n = \frac{\Delta}{2}$  slopes



Only if we fix the planar embedding!

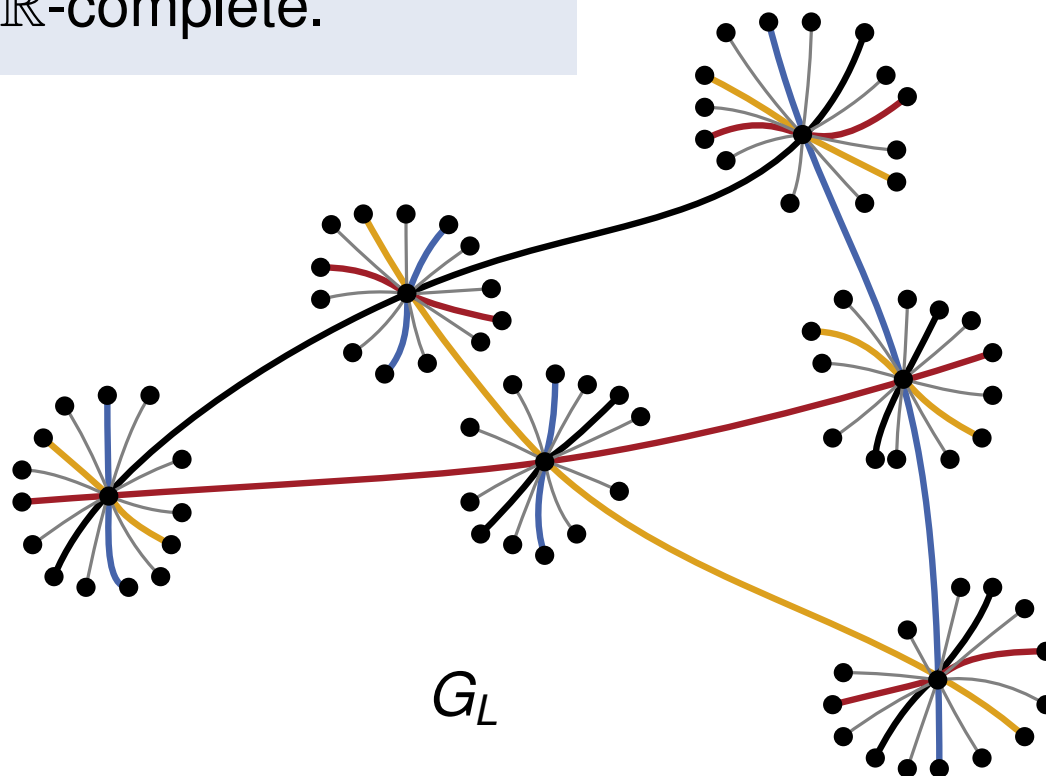
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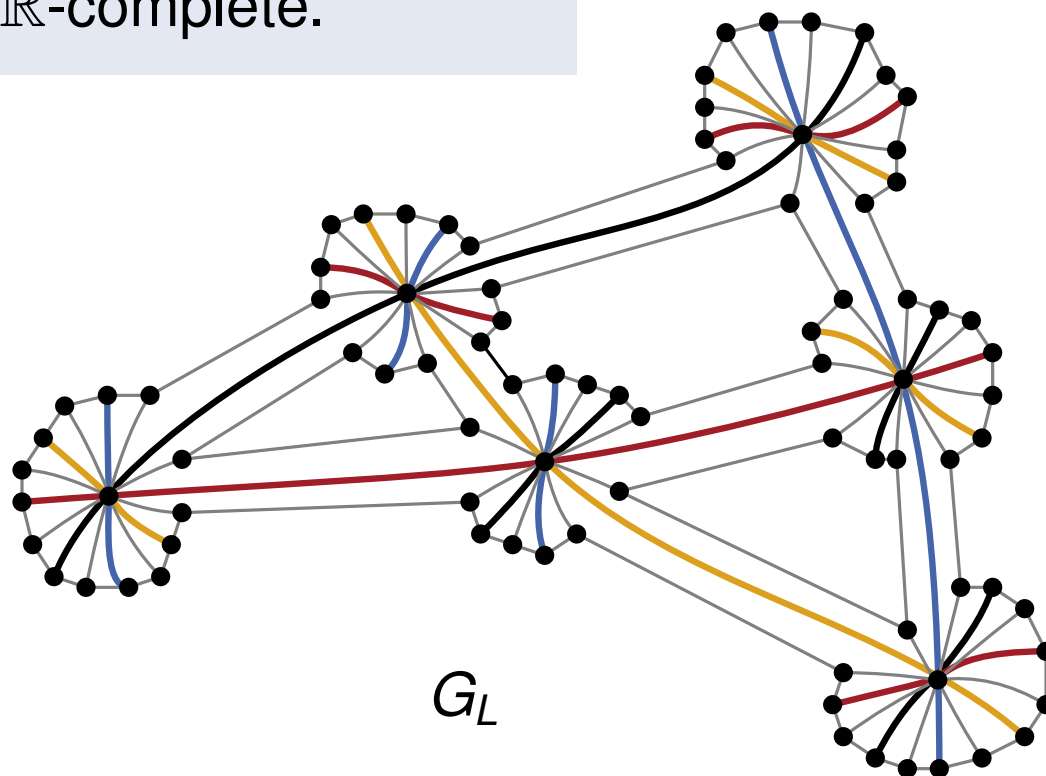
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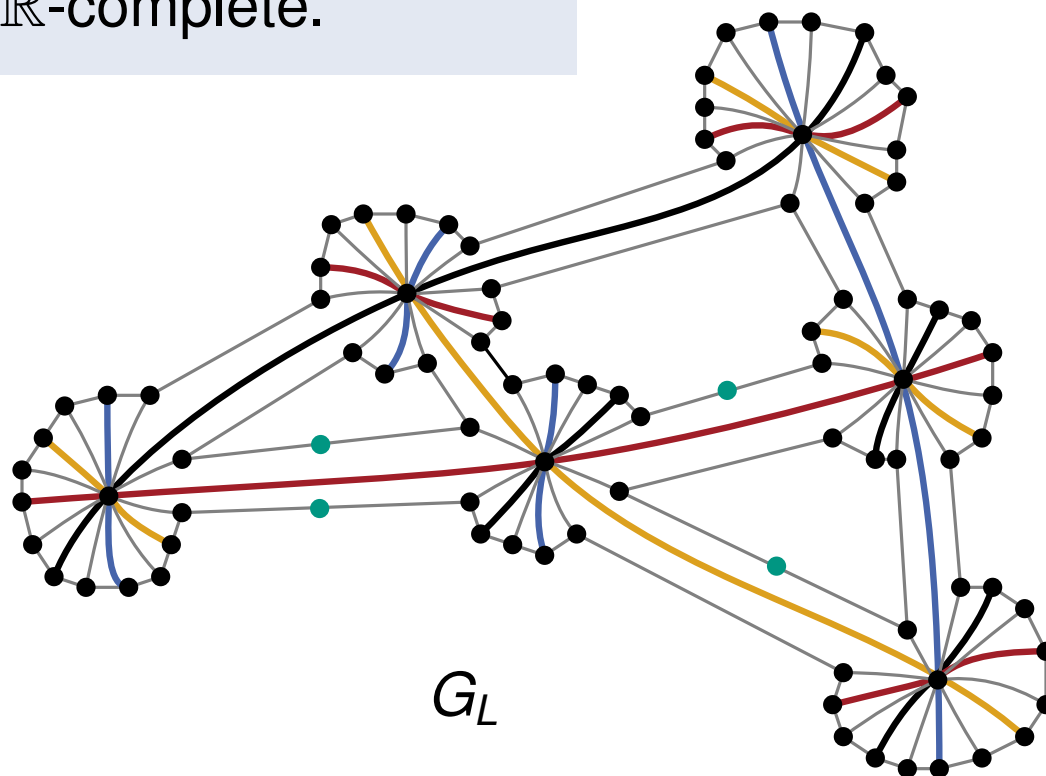
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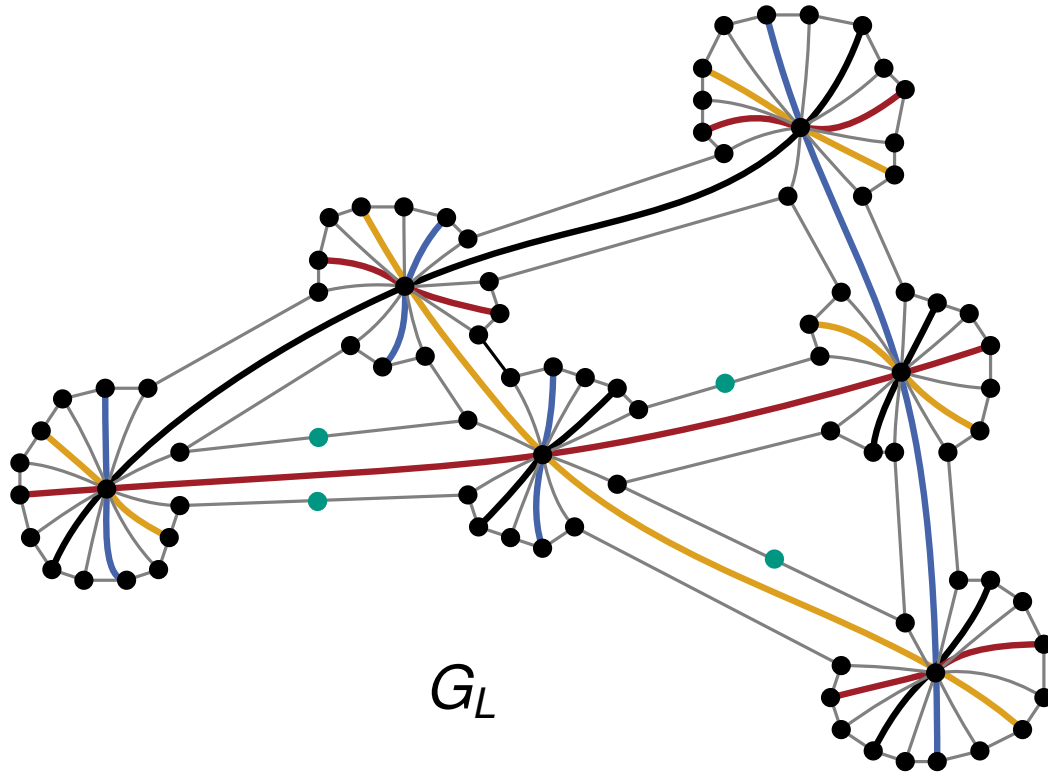


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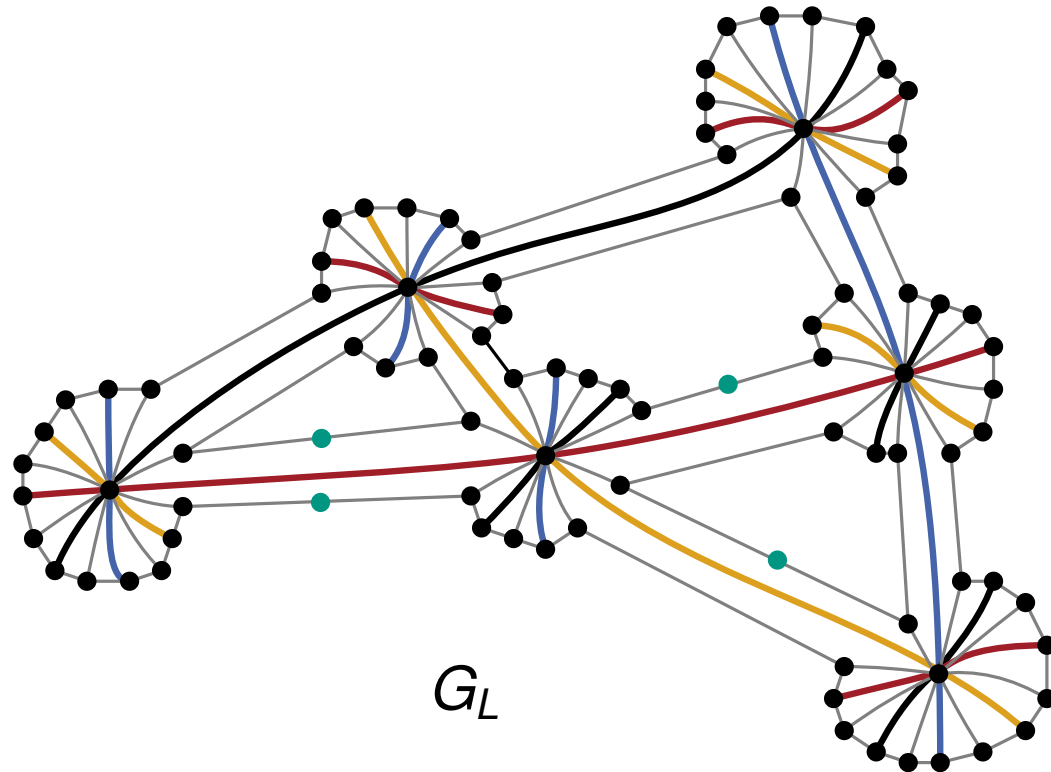
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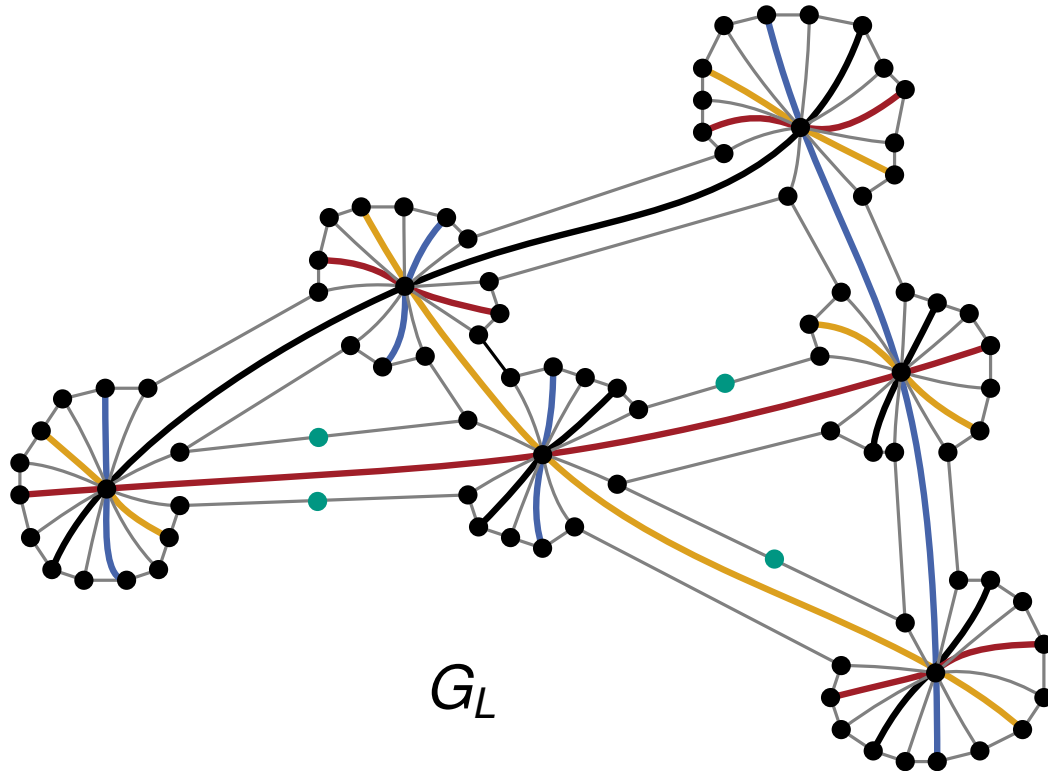


# Drawing $\Rightarrow$ Stretchable



$D$ : Straight-line drawing of  $G_L$   
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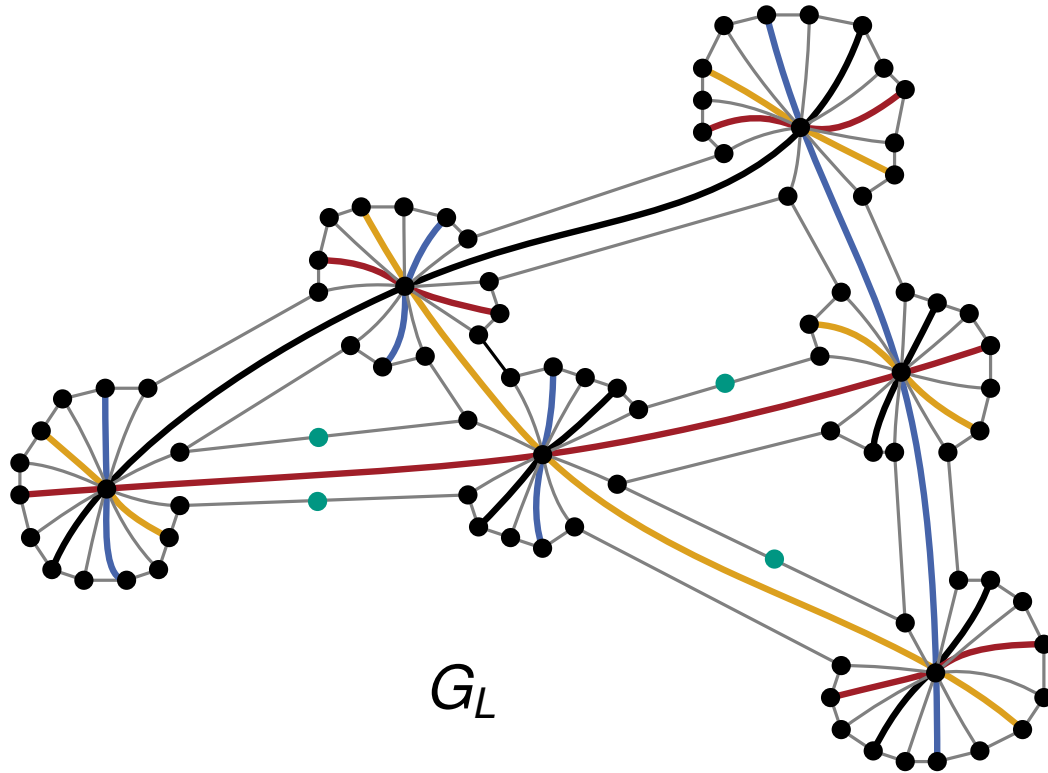


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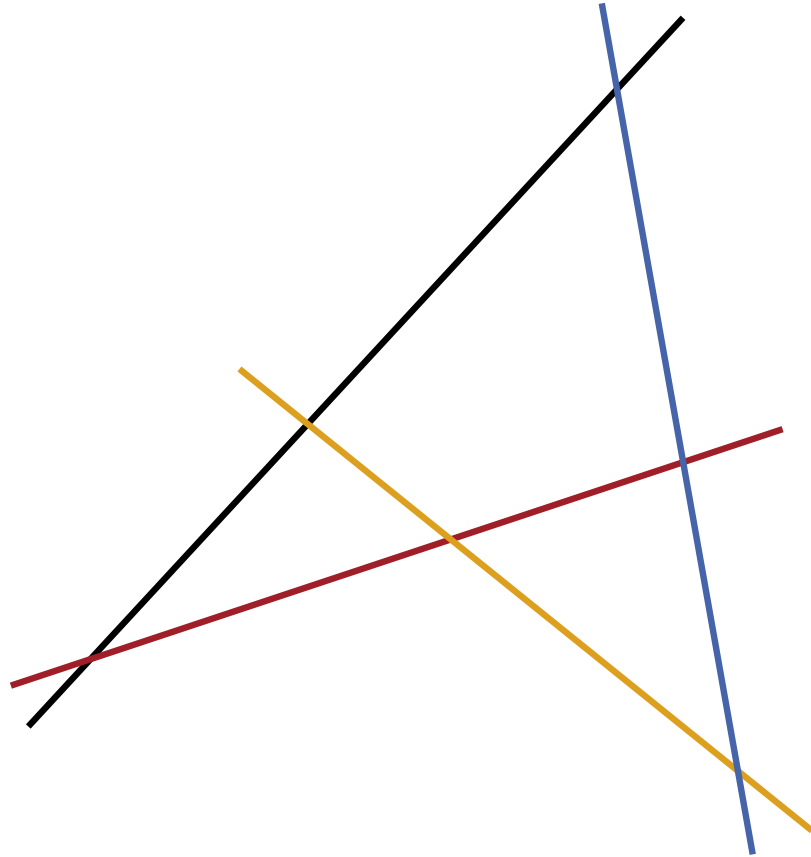


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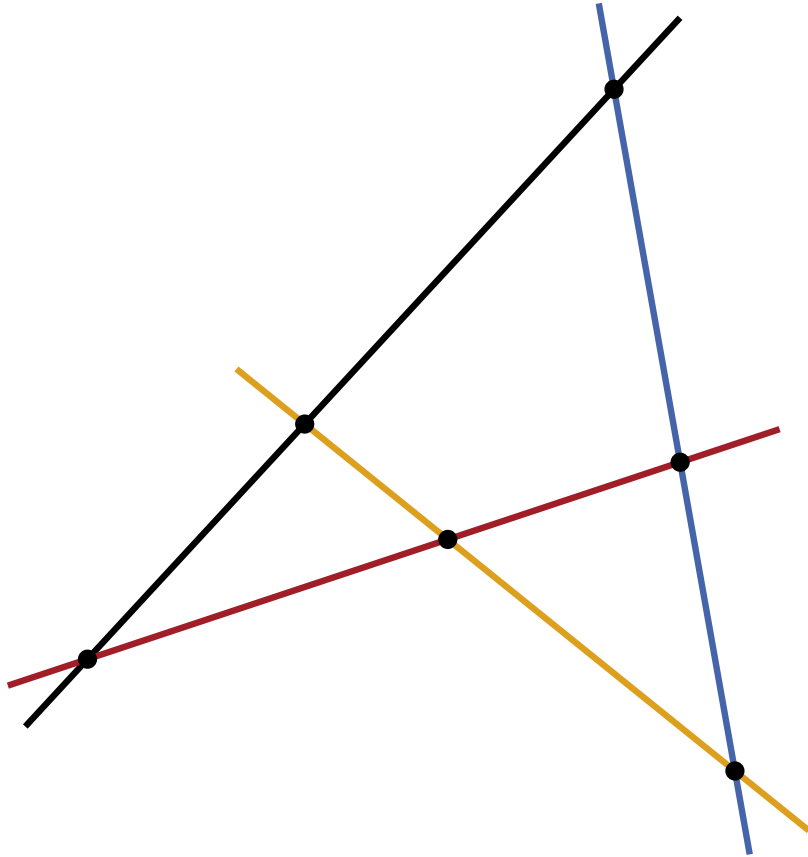
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for  $v \in V$  with  $\deg(v) = \Delta$ :  
 $\Rightarrow$  opposite edges have equal slopes  
 $\Rightarrow L$  is stretched

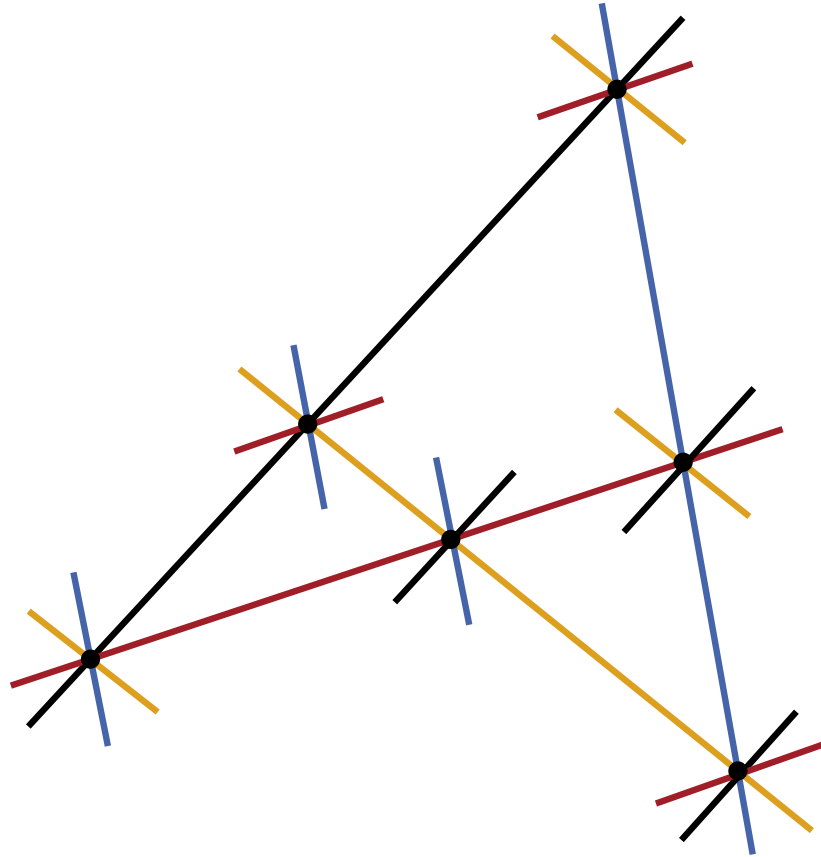
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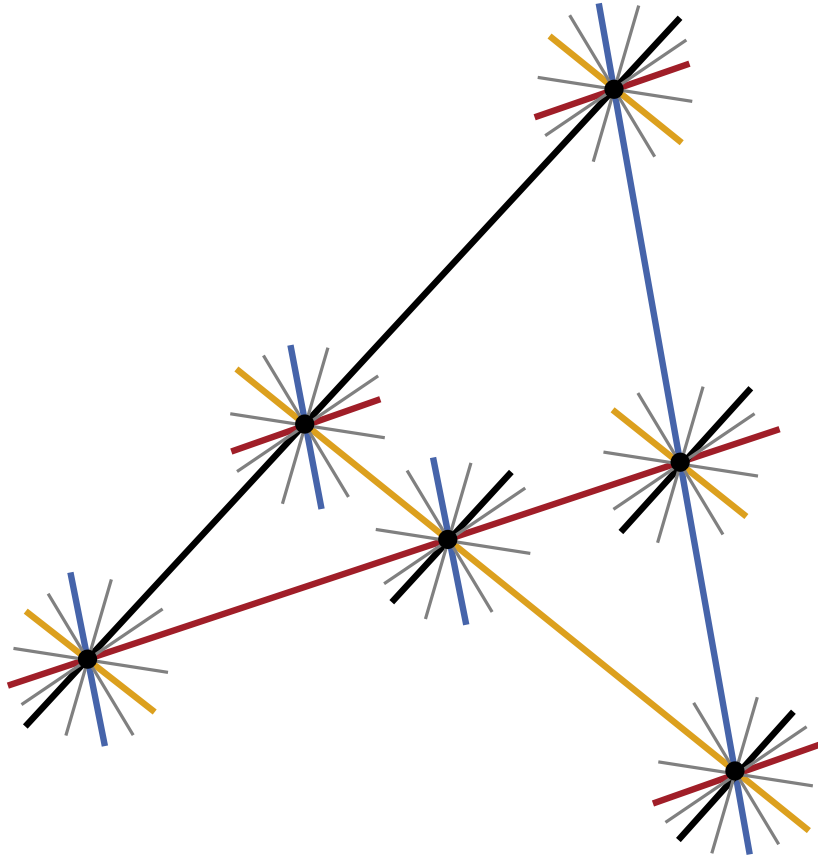
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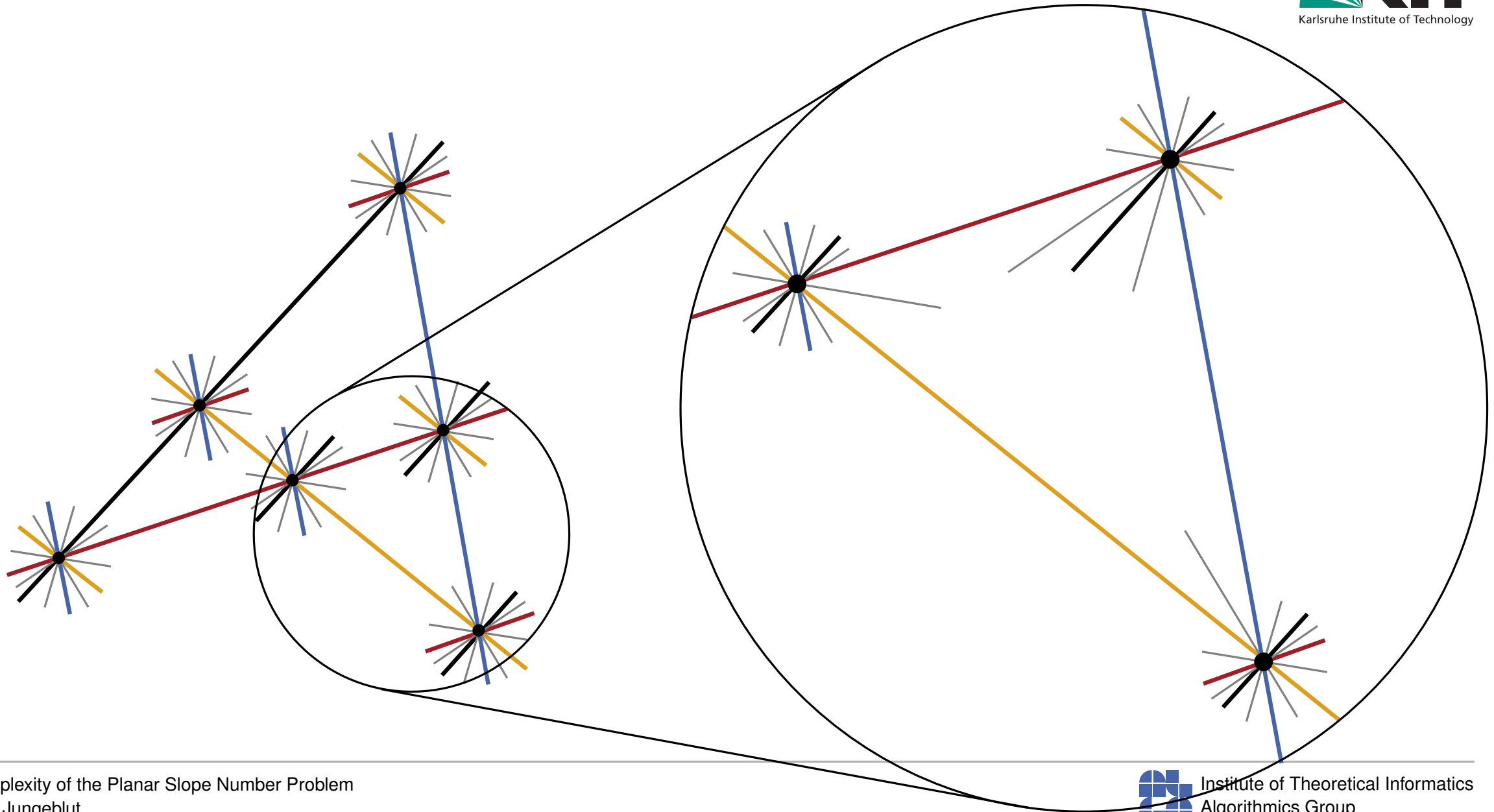
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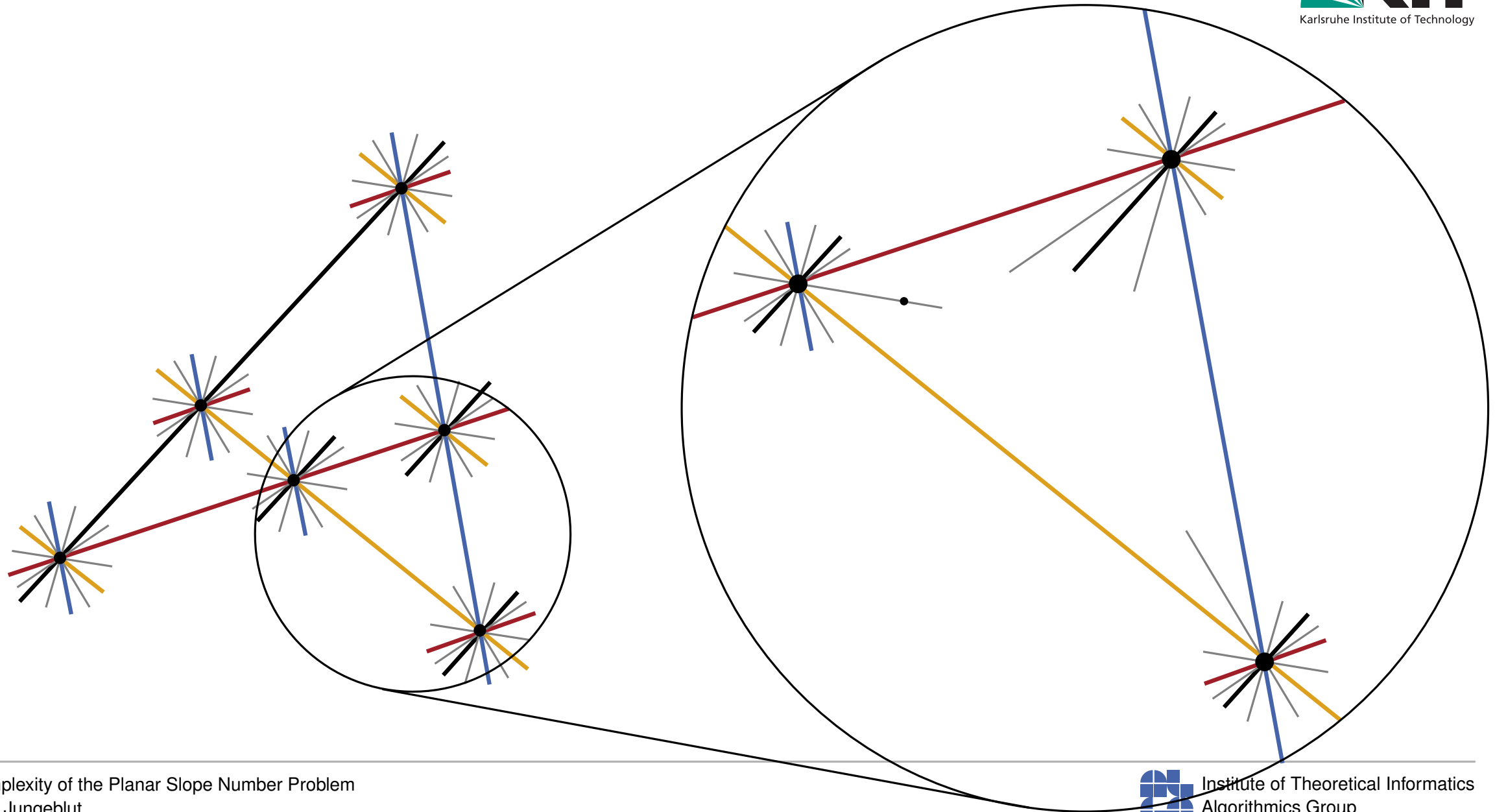
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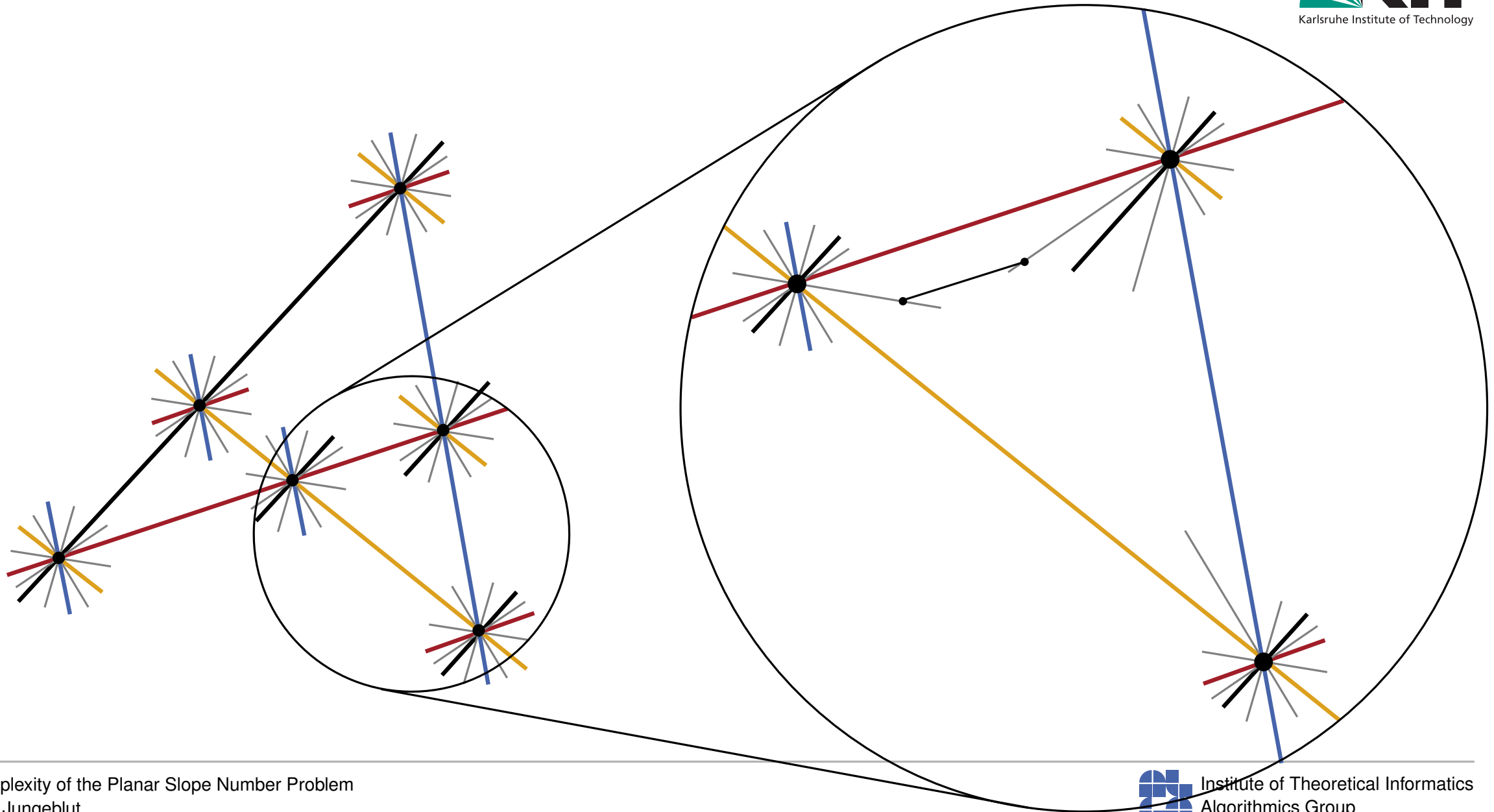
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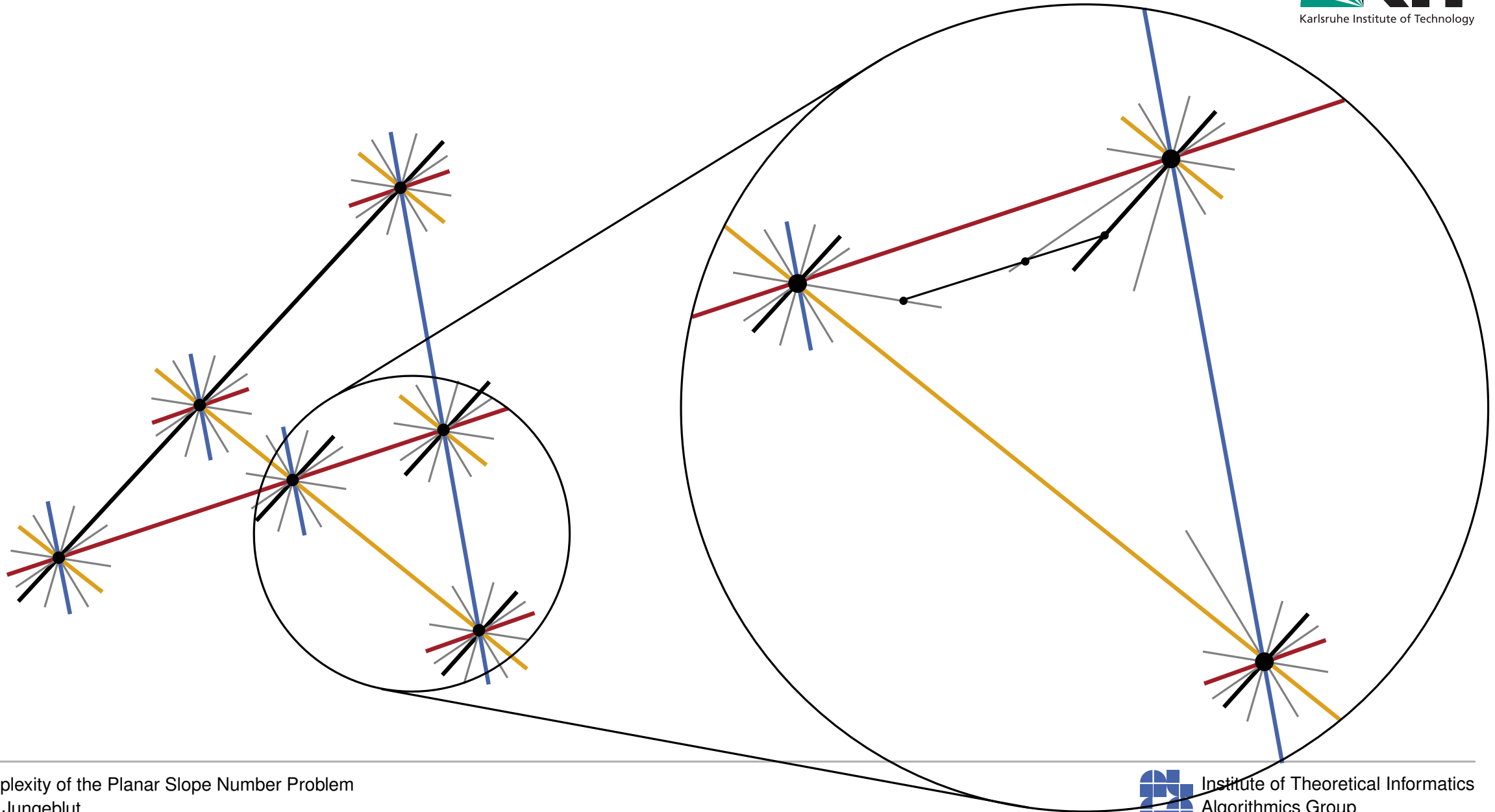


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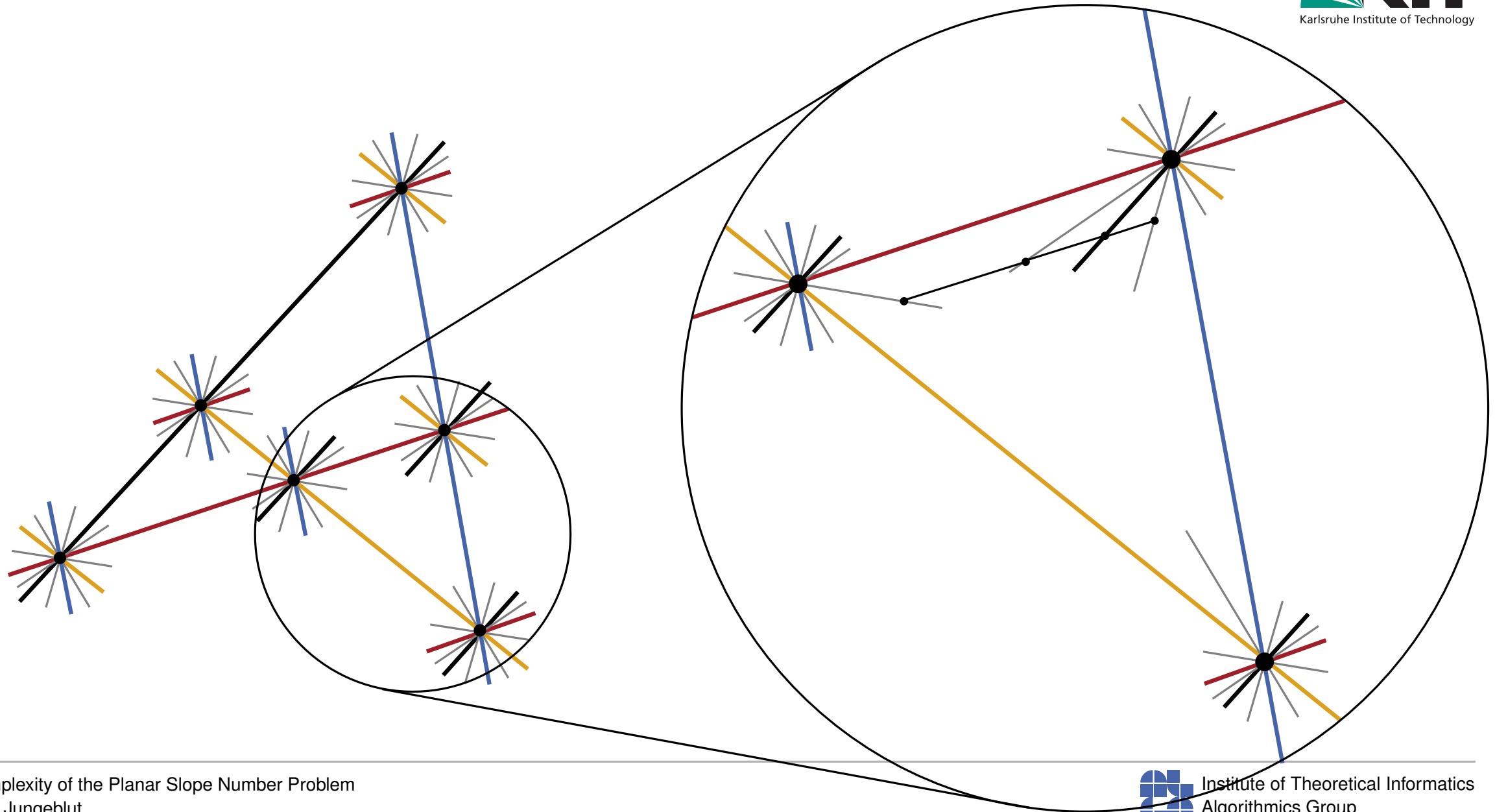




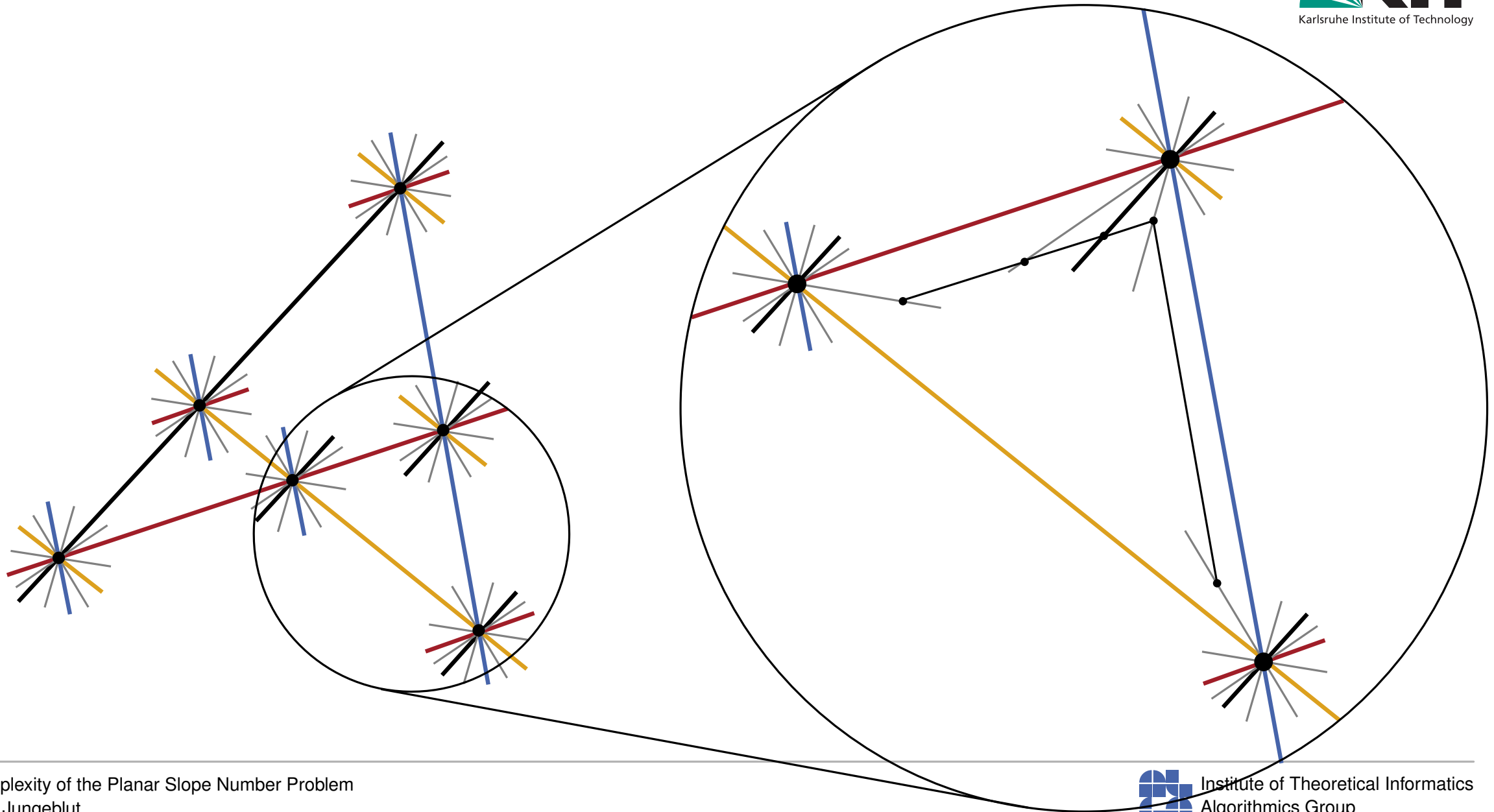
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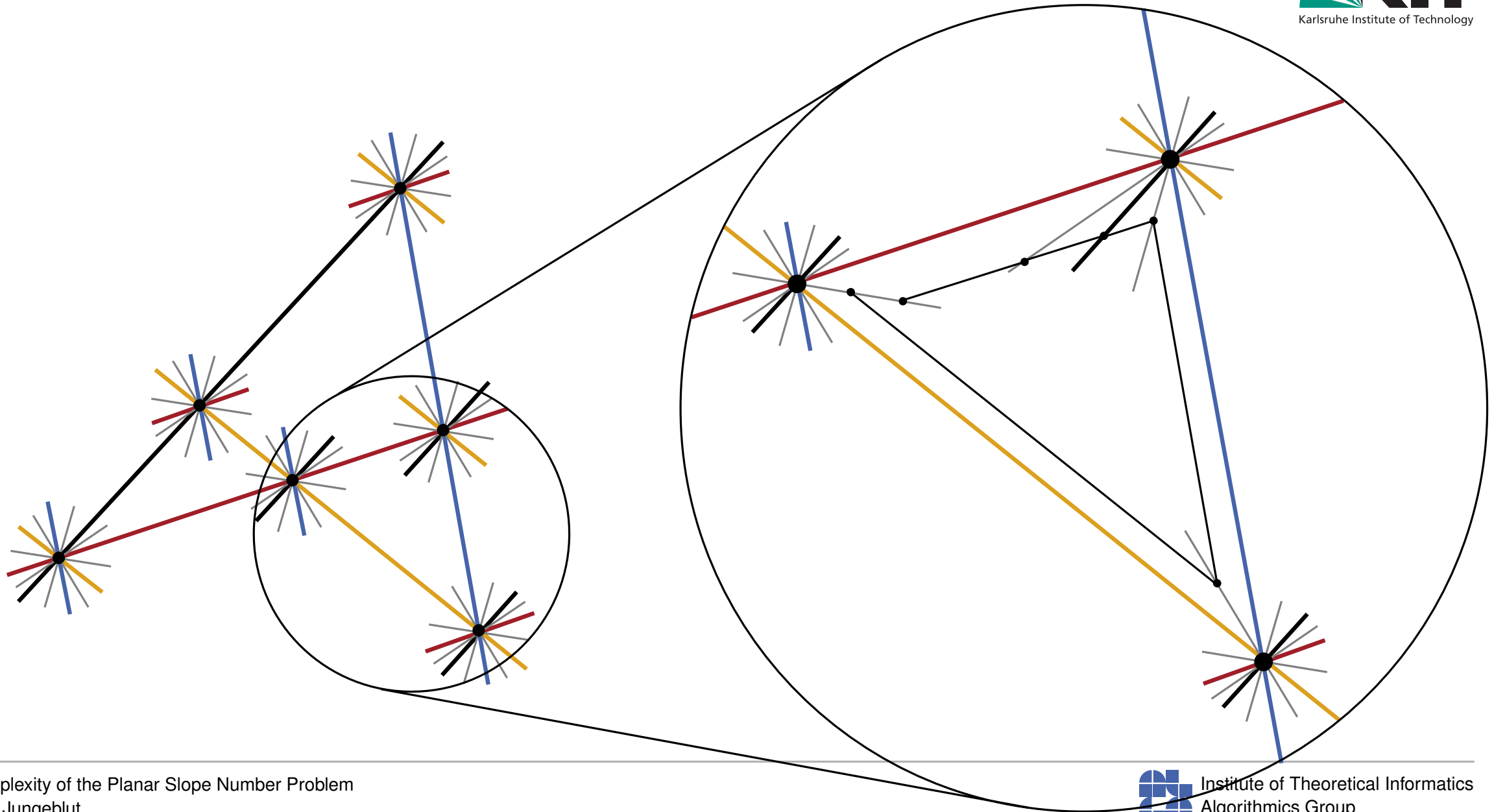
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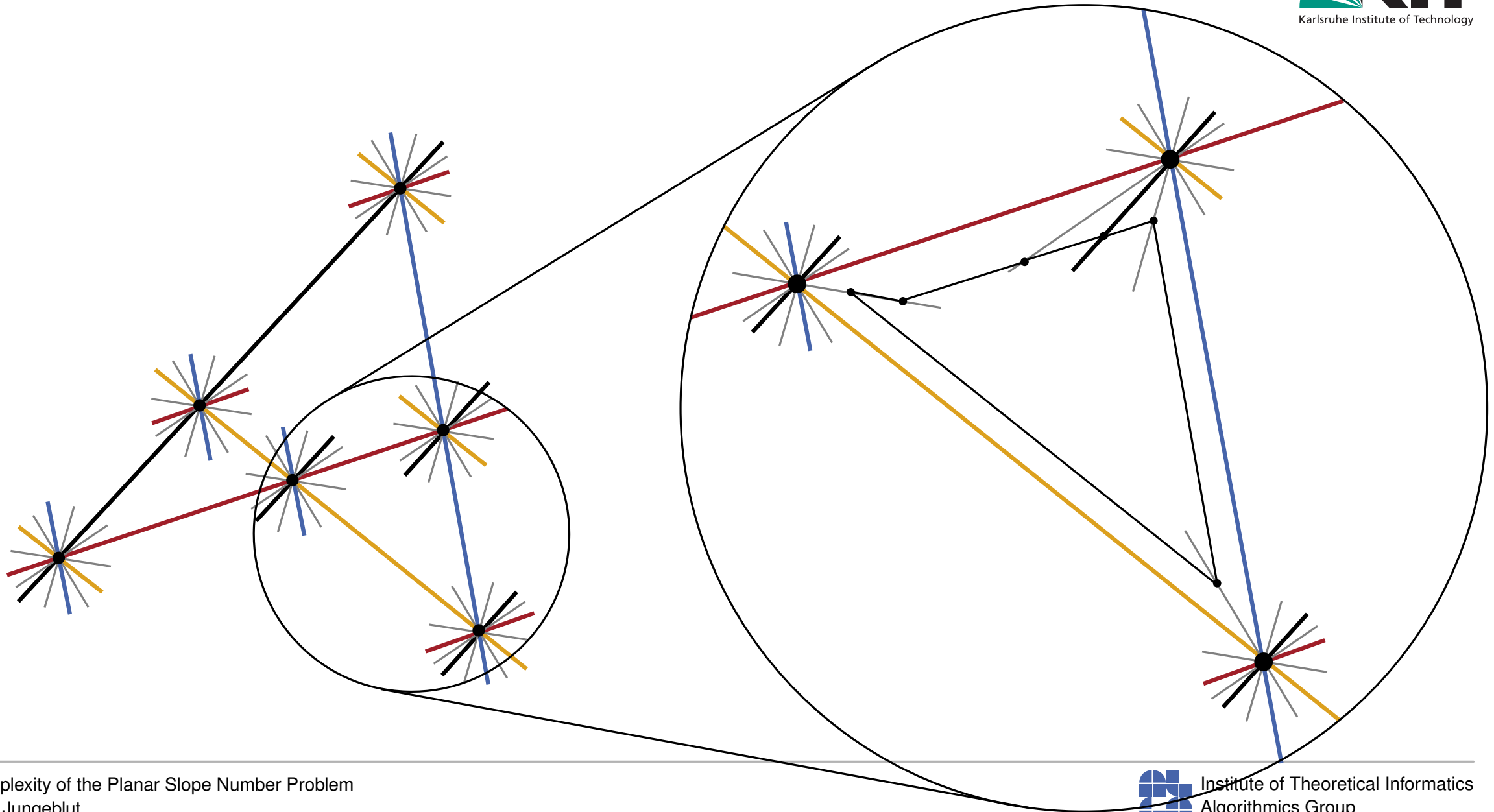
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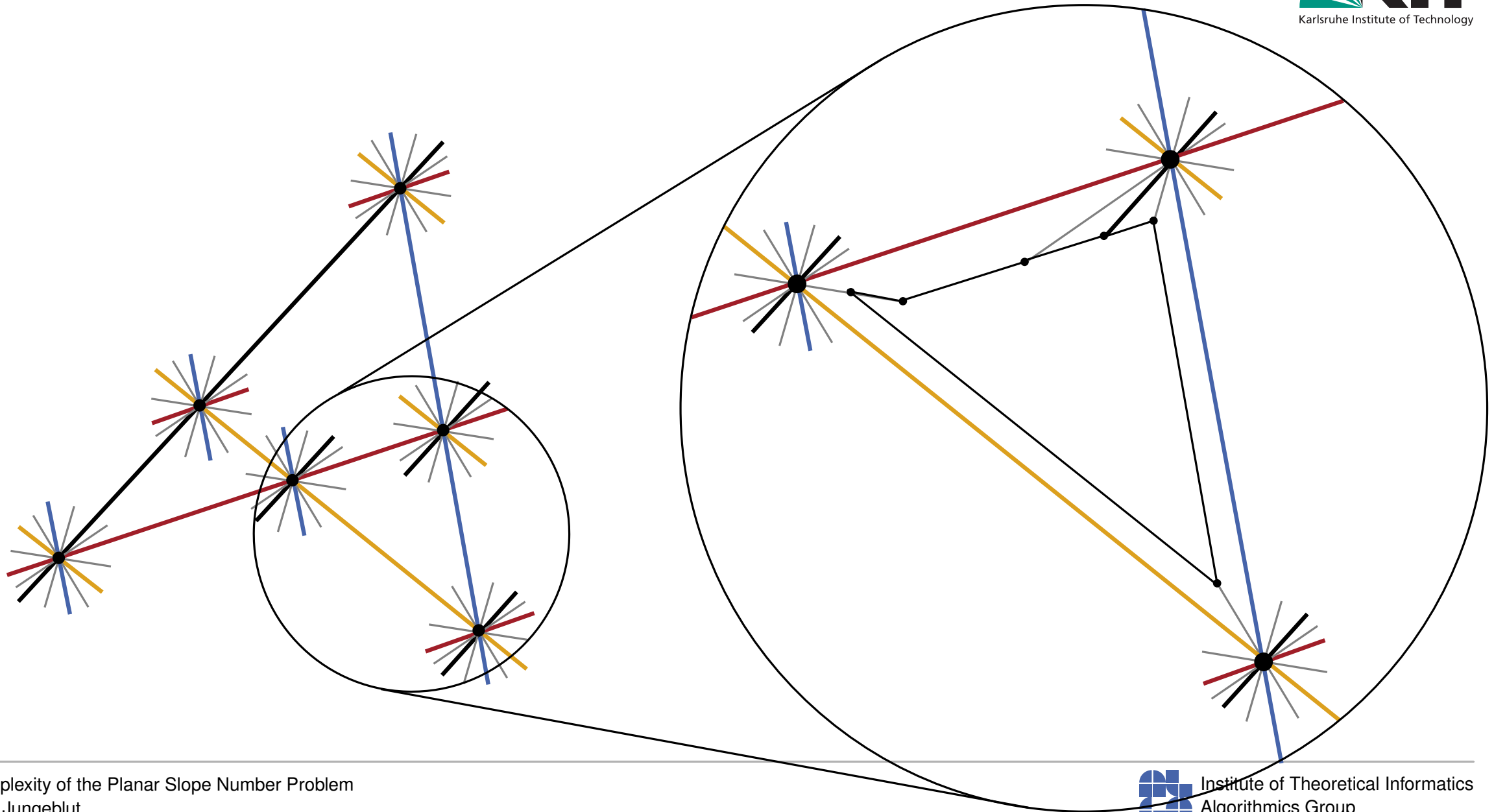
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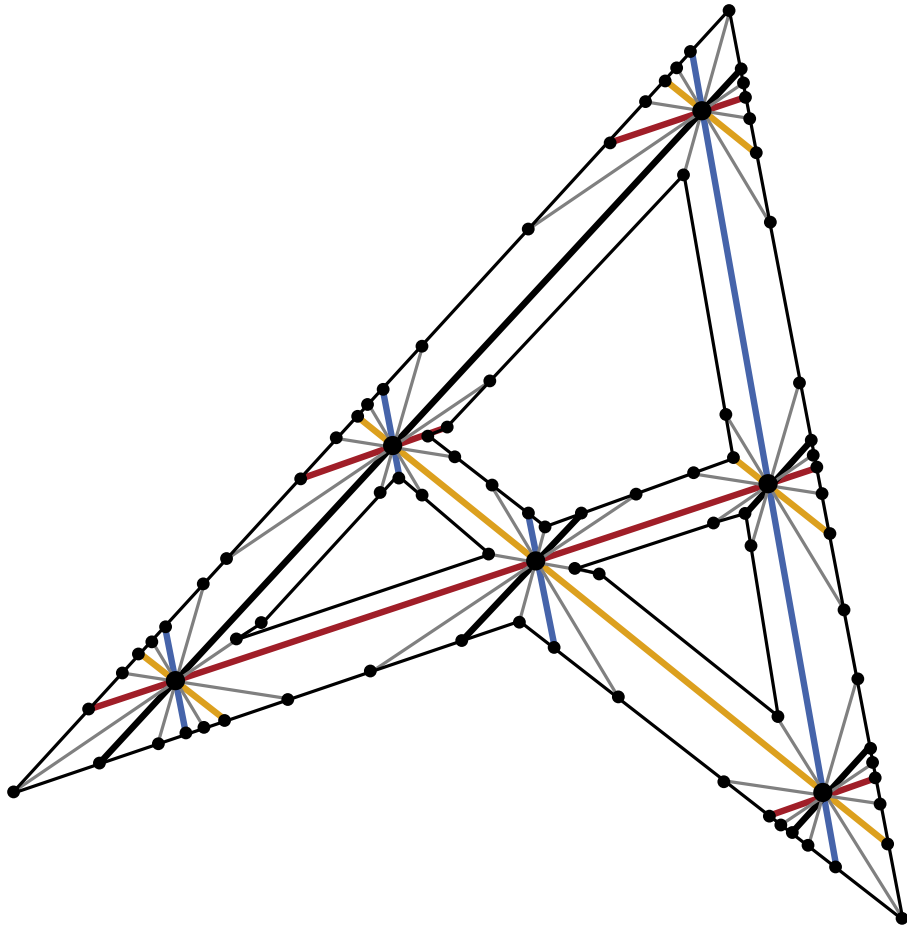
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straight-line drawing with  
exactly  $\frac{\Delta}{2}$  slopes

# Open Problems

## Non-planar Graphs:

What is the complexity of the slope number problem for non-planar graphs?

## Directed Graphs:

What is the (planar) slope number of directed/upward planar graphs?

## Bounded Degree:

What is the slope number of graphs with  $\Delta = 4$ ?

**Thank you very much!**



# Stretchability with $k$ Slopes, $k$ fixed

**Question:** Can we realize a pseudoline arrangement  $L = \{\ell_1, \dots, \ell_n\}$  with  $k$  slopes?

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└─ unknown offset  
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On pseudoline  $\ell_p$ :

Intersection

with  $\ell_q$  left of  $\ell_r$ .

$$\rightsquigarrow \frac{b_q - b_p}{a_p - a_q} < \frac{b_r - b_p}{a_p - a_r} \rightsquigarrow \text{polynomial inequality}$$

(Because we know the signs of the denominators.)

# Stretchability with $k$ Slopes, $k$ fixed

Write system of inequalities (fixing the order of intersections) in matrix form:

$$A \cdot \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix} > 0$$

Matrix where each entry  
is a linear polynomial  
in  $a_1, \dots, a_k$ .

# Stretchability with $k$ Slopes, $k$ fixed

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Components of  $b$  corresponding to columns of  $C$ .

If system has a solution, it has a *basic solution*:  
Regular square submatrix  $C$  of  $A$ , such that  $C \cdot b^- = \varepsilon \cdot \mathbf{1}$ .

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Cramer's Rule:

Components of  $b^-$  can be expressed as:

$$b_i^- = \frac{\det A_i}{\det A} \quad \text{where } A_i \text{ is } A \text{ with the } i\text{-th column replaced by } \varepsilon \cdot \mathbf{1}.$$

# Stretchability with $k$ Slopes, $k$ fixed

Write system of inequalities (fixing the order of intersections) in matrix form:

$$A \cdot \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix} \geq \varepsilon \cdot \mathbf{1} \quad \text{for some } \varepsilon > 0$$

Matrix where each entry is a linear polynomial in  $a_1, \dots, a_k$ .

Components of  $b$  corresponding to columns of  $C$ .

If system has a solution, it has a *basic solution*:  
Regular square submatrix  $C$  of  $A$ , such that  $C \cdot b^- = \varepsilon \cdot \mathbf{1}$ .

## Cramer's Rule:

Components of  $b^-$  can be expressed as:

$$b_i^- = \frac{\det A_i}{\det A}$$

where  $A_i$  is  $A$  with the  $i$ -th column replaced by  $\varepsilon \cdot \mathbf{1}$ .

$\det A = p_0(a_1, \dots, a_k, \varepsilon)$  w.l.o.g. positive at solution  
 $\det A_i = p_i(a_1, \dots, a_k, \varepsilon)$

# Stretchability with $k$ Slopes, $k$ fixed

## Summarizing:

$A \cdot b > 0$  solvable  $\Leftrightarrow \exists$  polynomials  $p_0(a_1, \dots, a_k, \varepsilon), p_1(a_1, \dots, a_k, \varepsilon) \dots, p_n(a_1, \dots, a_k, \varepsilon)$   
with  $\{p_0, p_1, \dots, p_n\}$  bounded by a fixed polynomial in  $n$   
and  
real numbers  $\varepsilon > 0, a_1, \dots, a_k$  such that

- $p_0(a_1, \dots, a_k, \varepsilon) > 0$
- $b$  with  $b_j = \frac{p_j(a_1, \dots, a_k, \varepsilon)}{p_0(a_1, \dots, a_k, \varepsilon)}$  is a solution

# Stretchability with $k$ Slopes, $k$ fixed

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guess non-deterministically



Now  $A \cdot b > 0$  is a system of polynomial inequalities with a fixed number of variables.  
Can be solved in polynomial time.