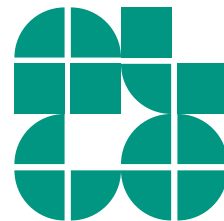


Computational Geometry – Exercise

Range Searching

LEHRSTUHL FÜR ALGORITHMIK I · INSTITUT FÜR THEORETISCHE INFORMATIK · FAKULTÄT FÜR INFORMATIK

Guido Brückner
06.07.2018



Orthogonal Range Queries for $d = 2$

Given: Set P of n points in \mathbb{R}^2

Find: A data structure that efficiently answers queries of the form $[a_1, b_1] \times \cdots \times [a_d, b_d]$

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Solutions:

- *one* search tree, alternate search for x and y coordinates
→ ***kd-Tree***
- *primary* search tree on x -coordinates,
several *secondary* search trees on y -coordinates
→ **Range Tree**

Orthogonal Range Queries for $d = 2$

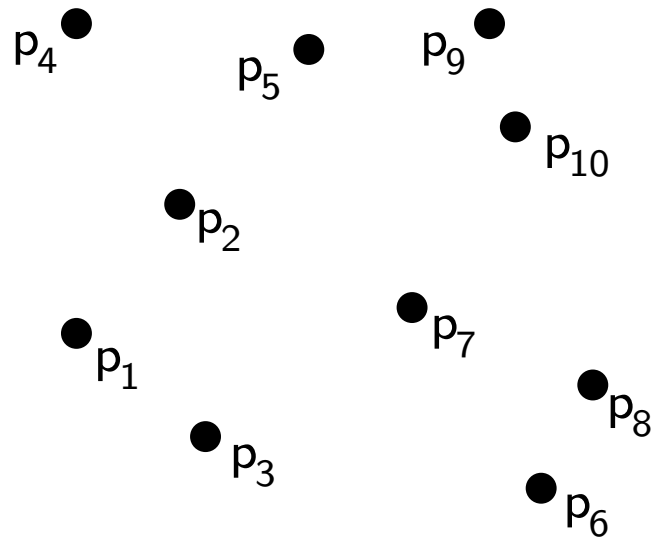
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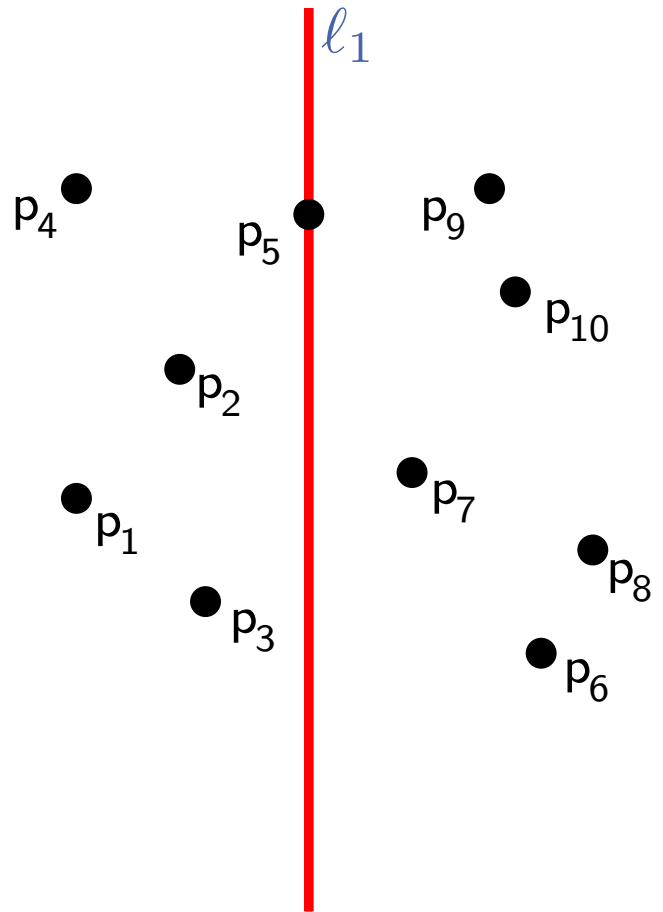
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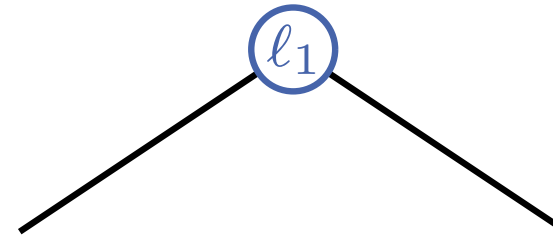
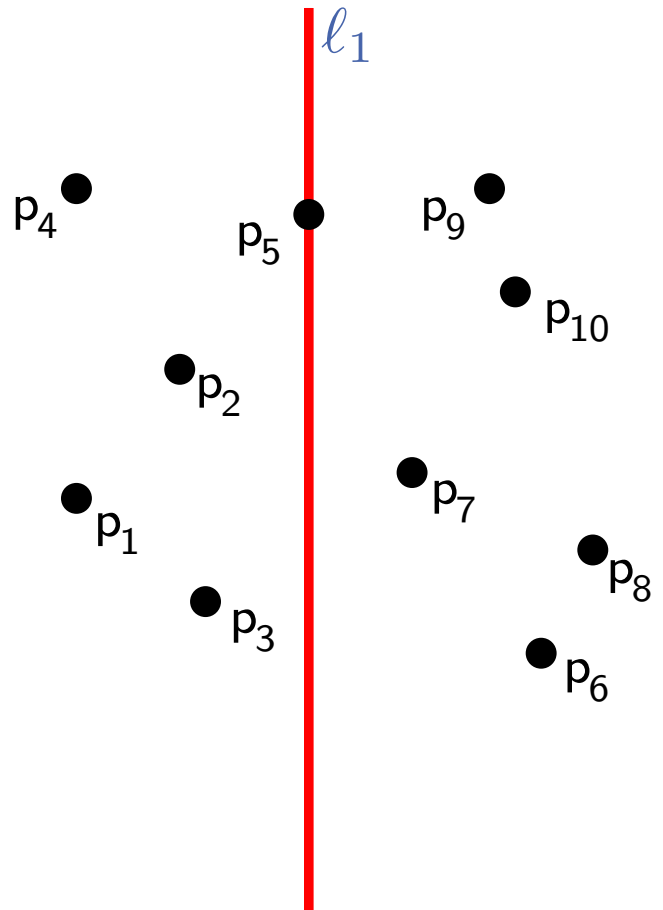
kd-Trees: Example



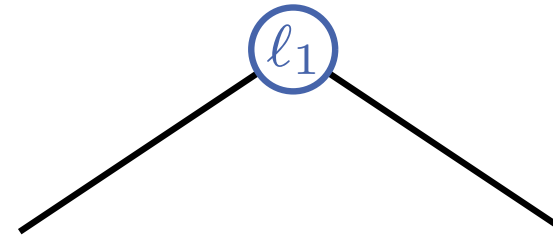
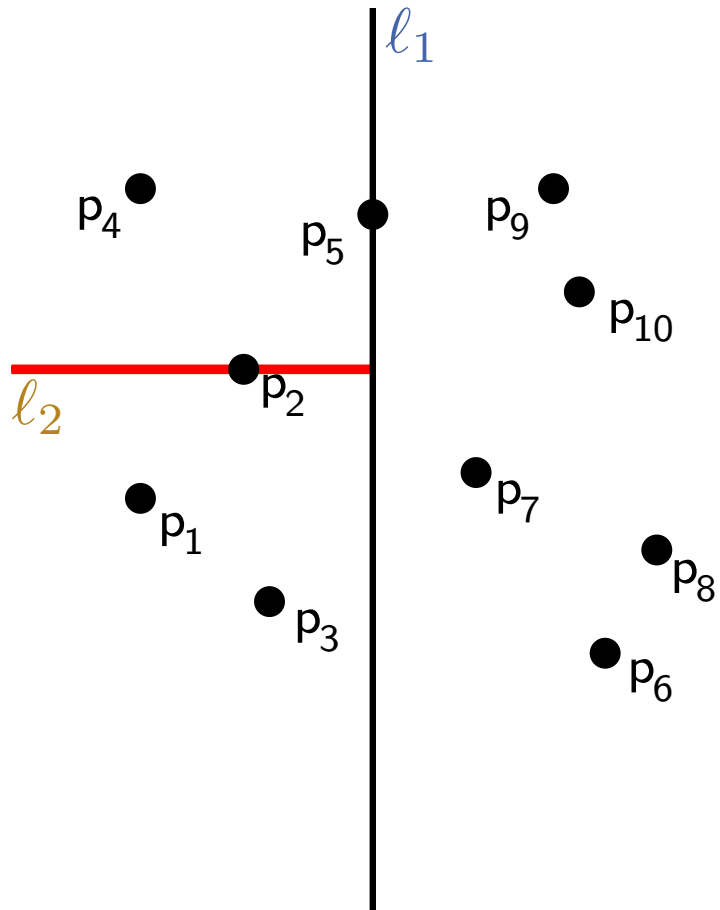
kd-Trees: Example



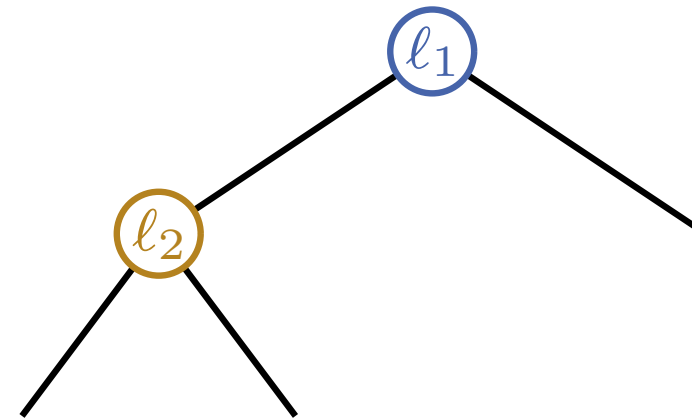
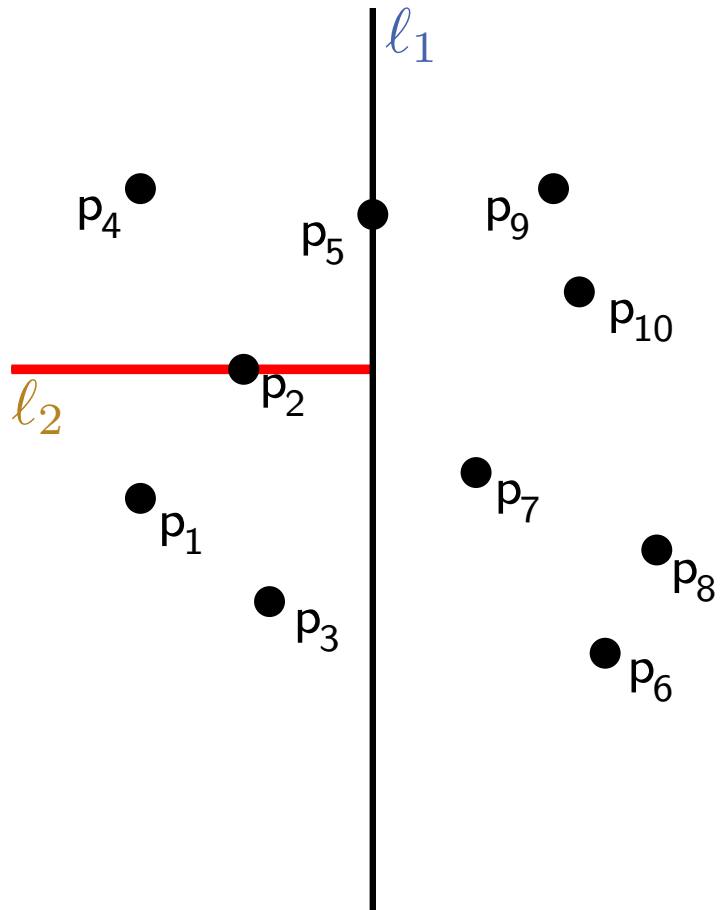
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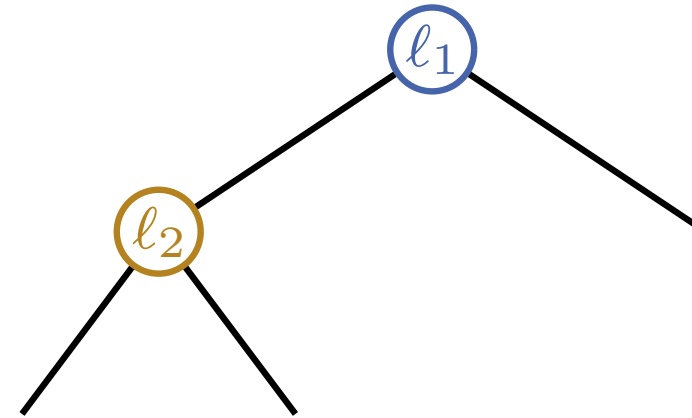
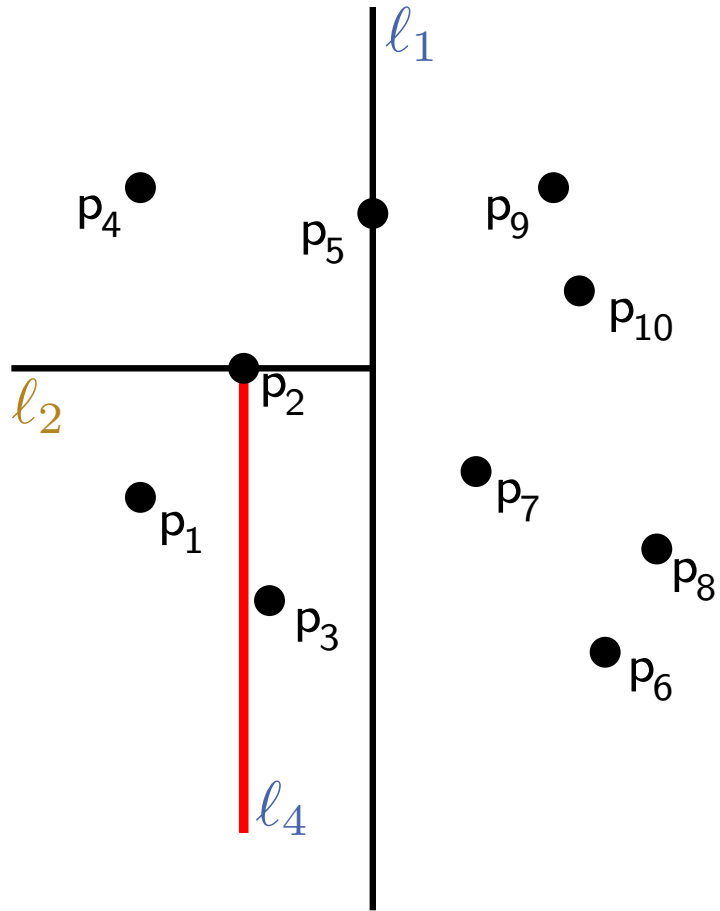
kd-Trees: Example



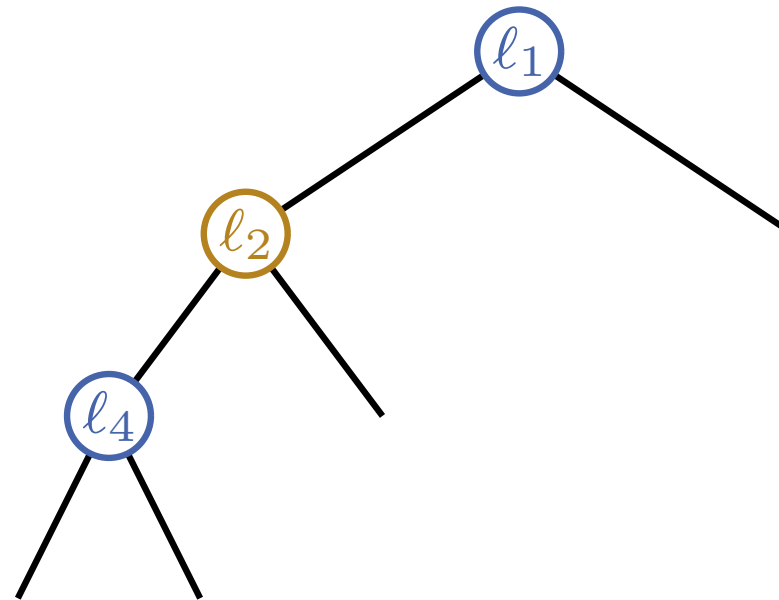
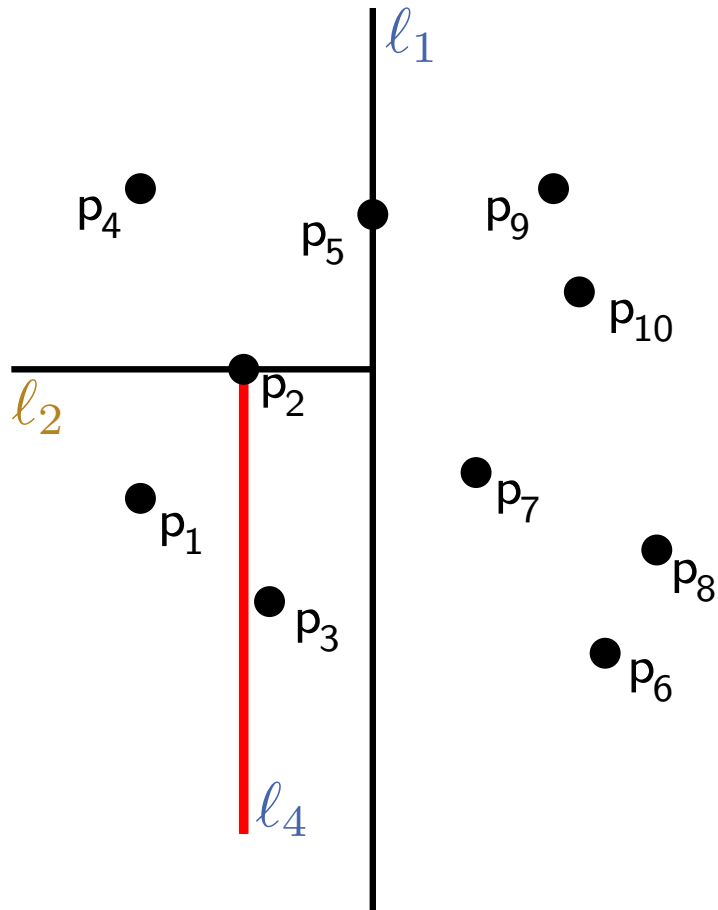
kd-Trees: Example



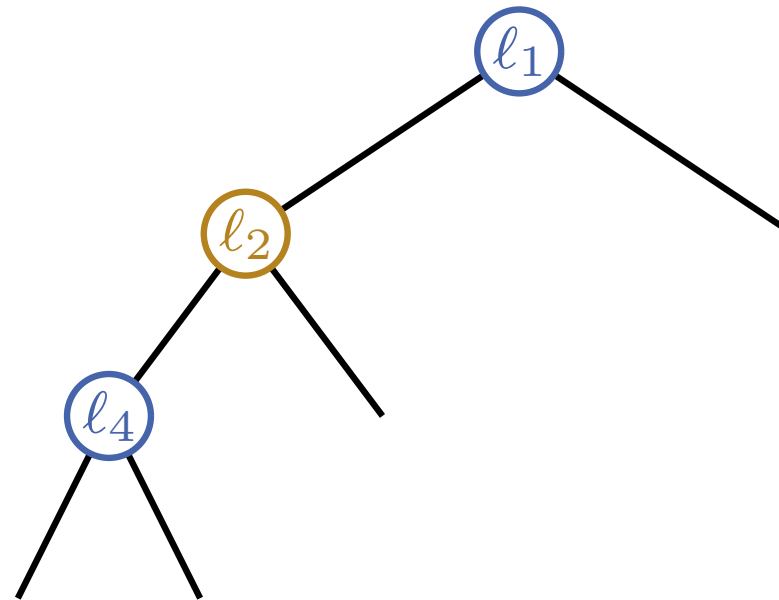
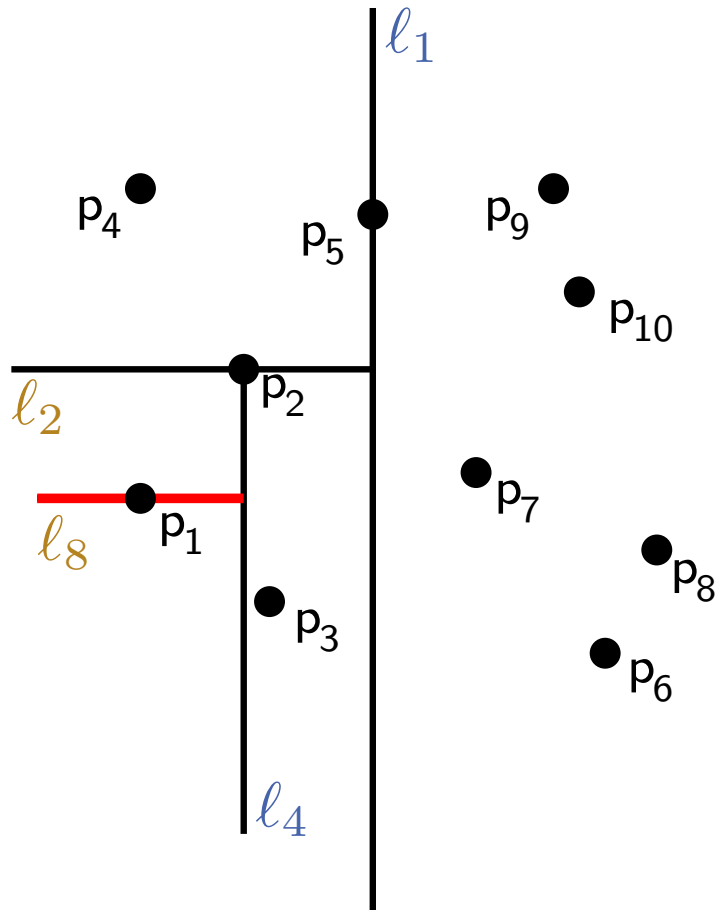
kd-Trees: Example



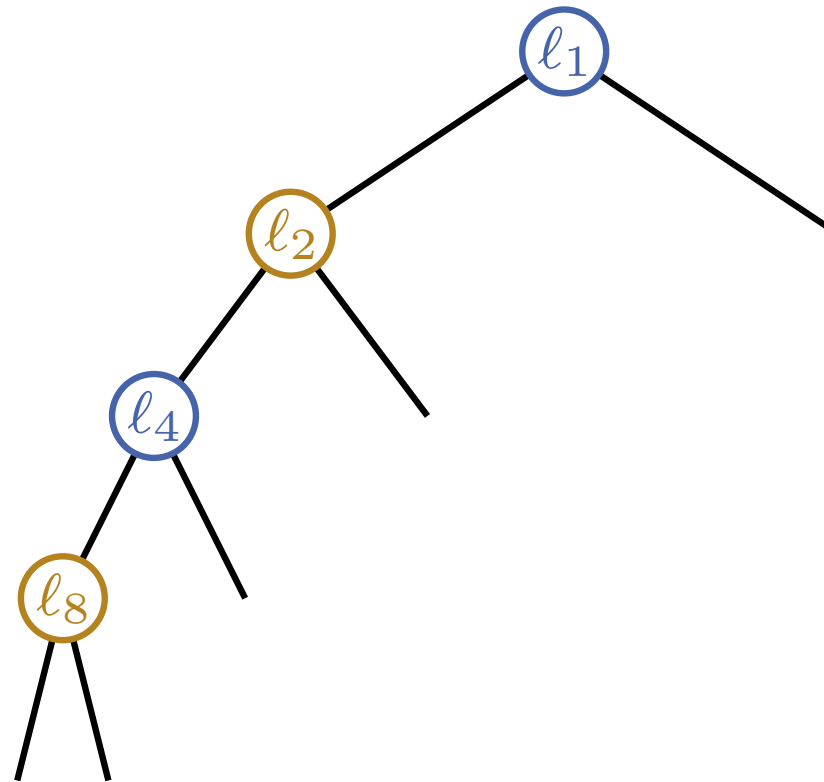
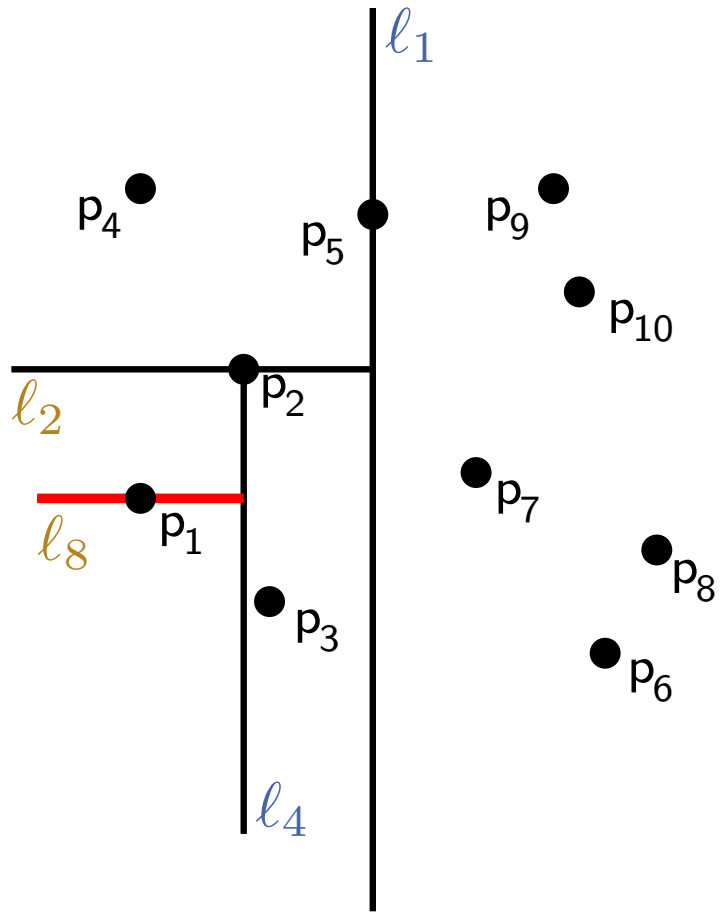
kd-Trees: Example



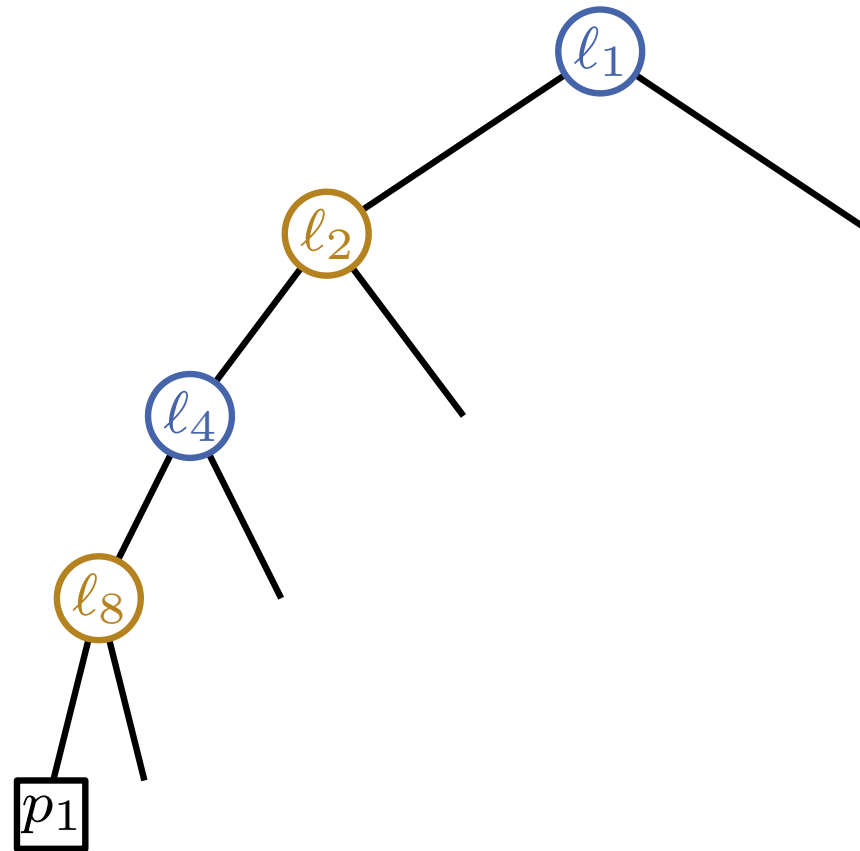
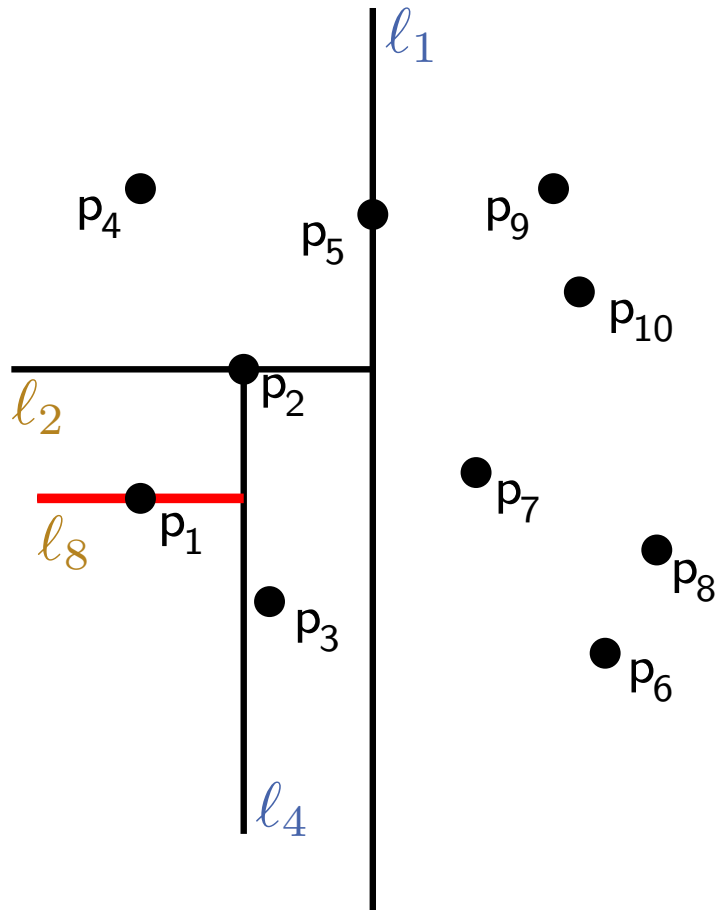
kd-Trees: Example



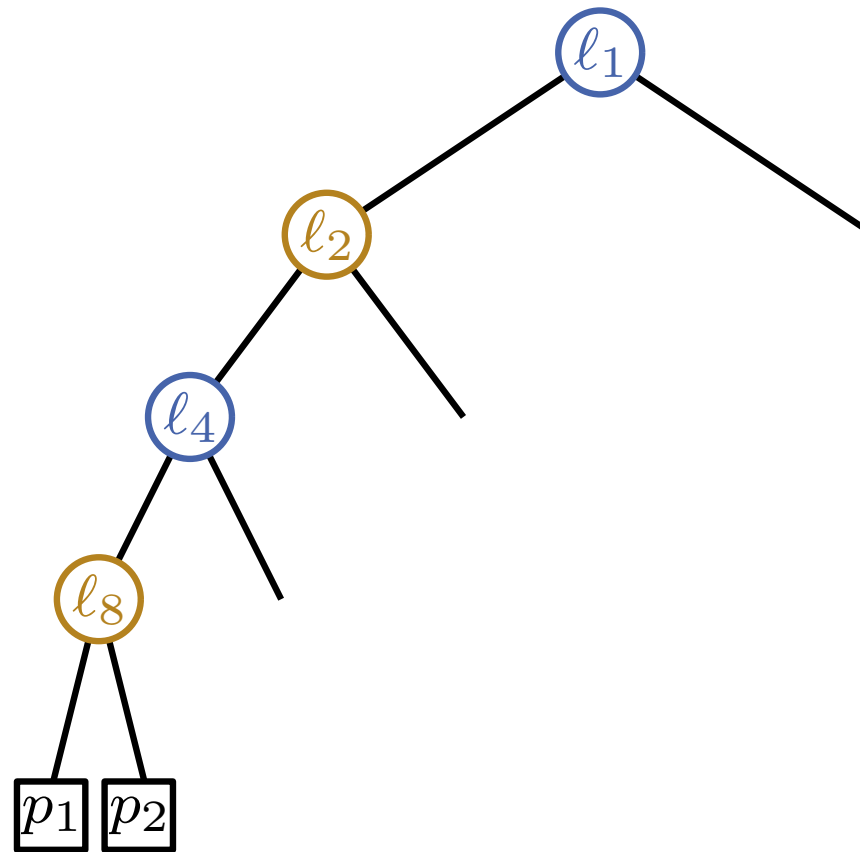
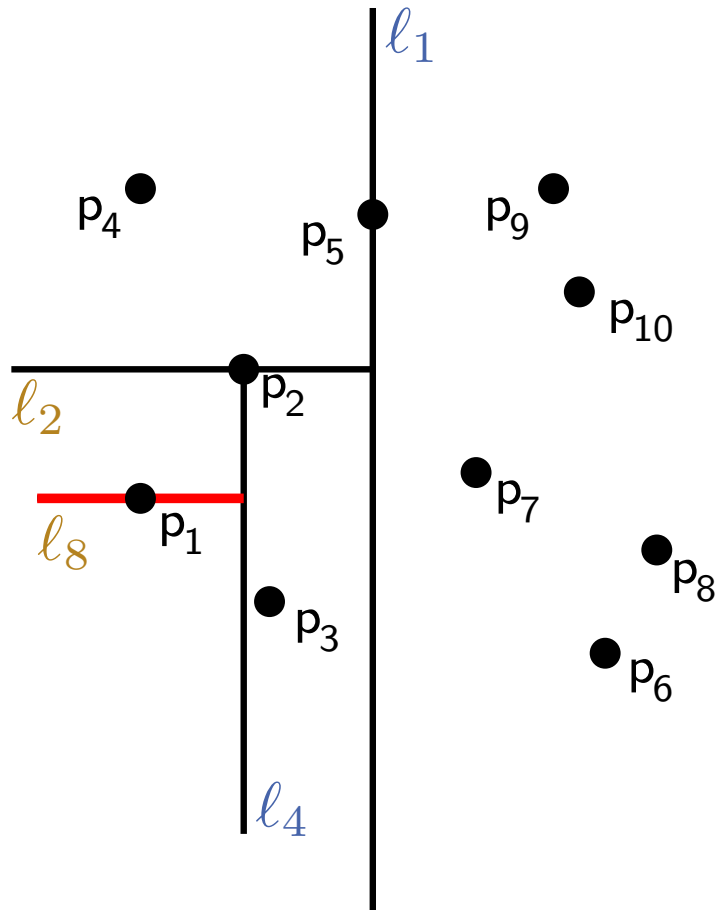
kd-Trees: Example



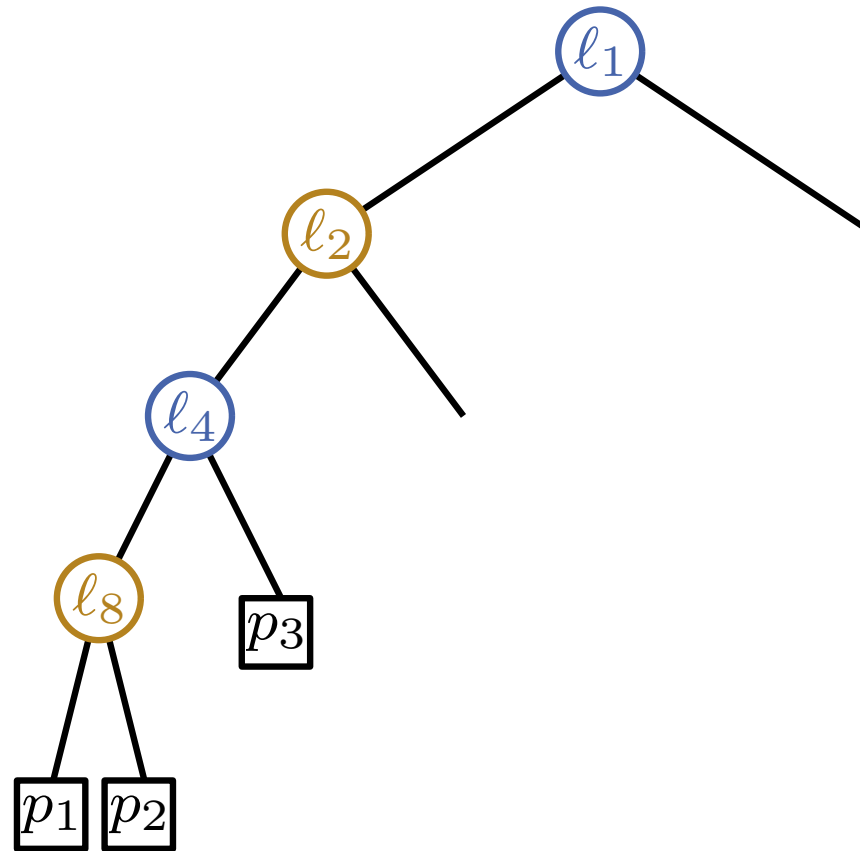
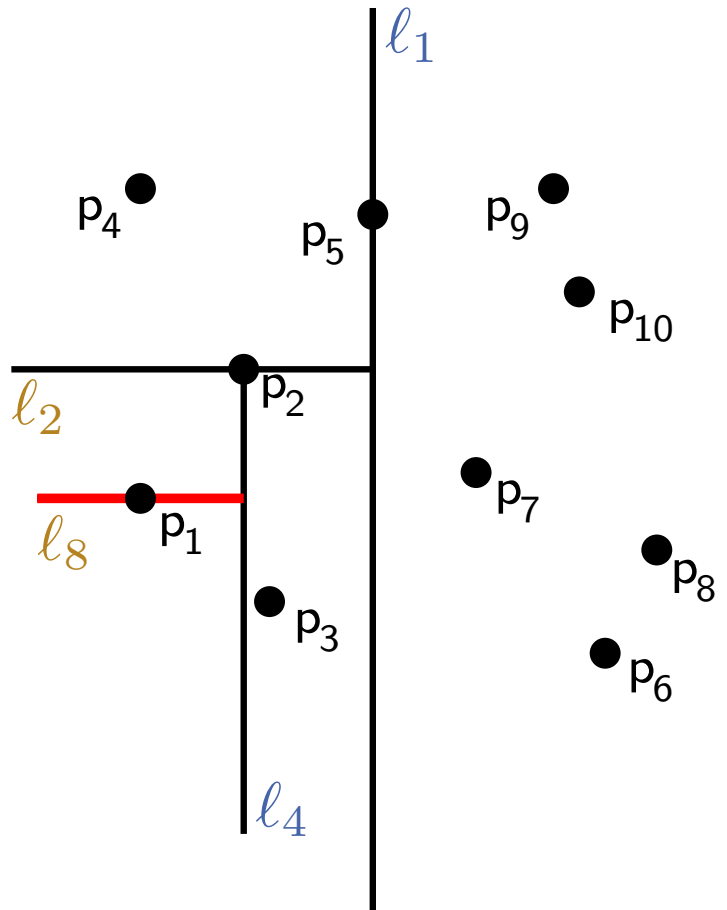
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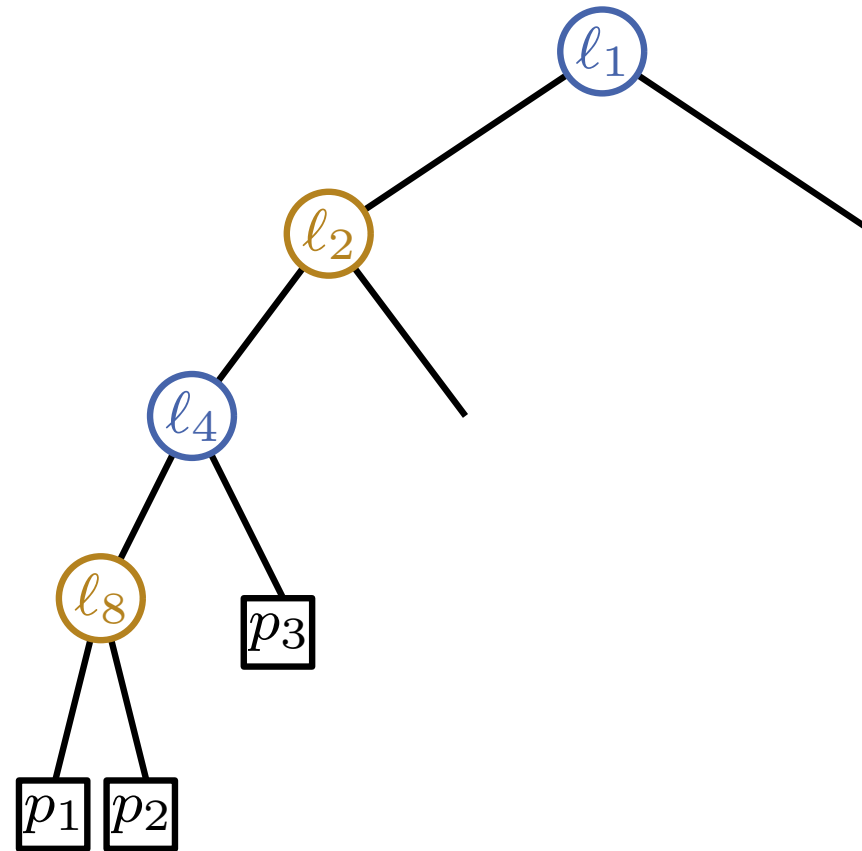
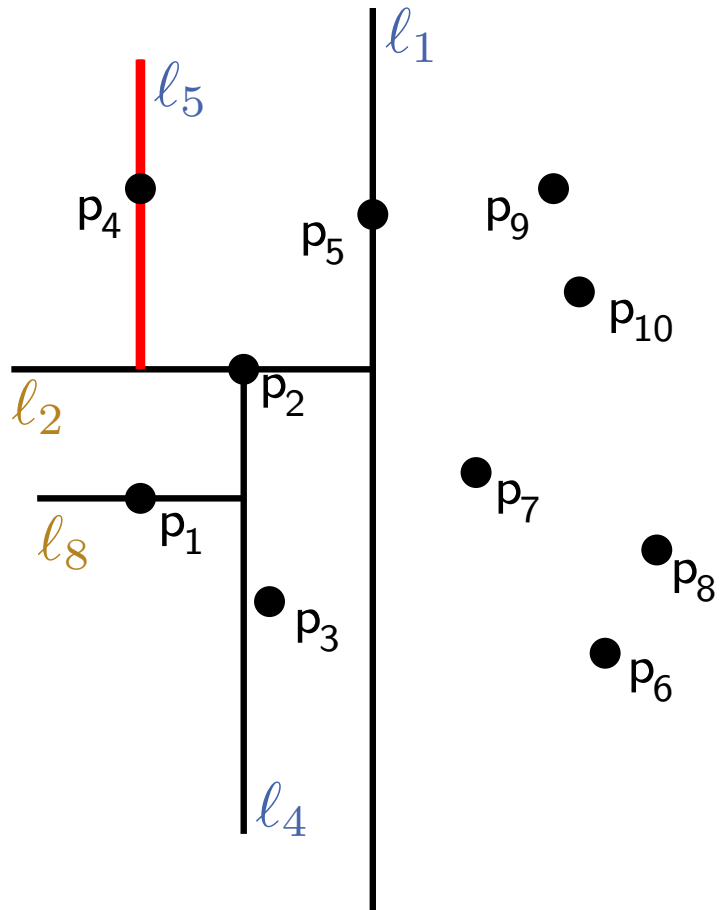
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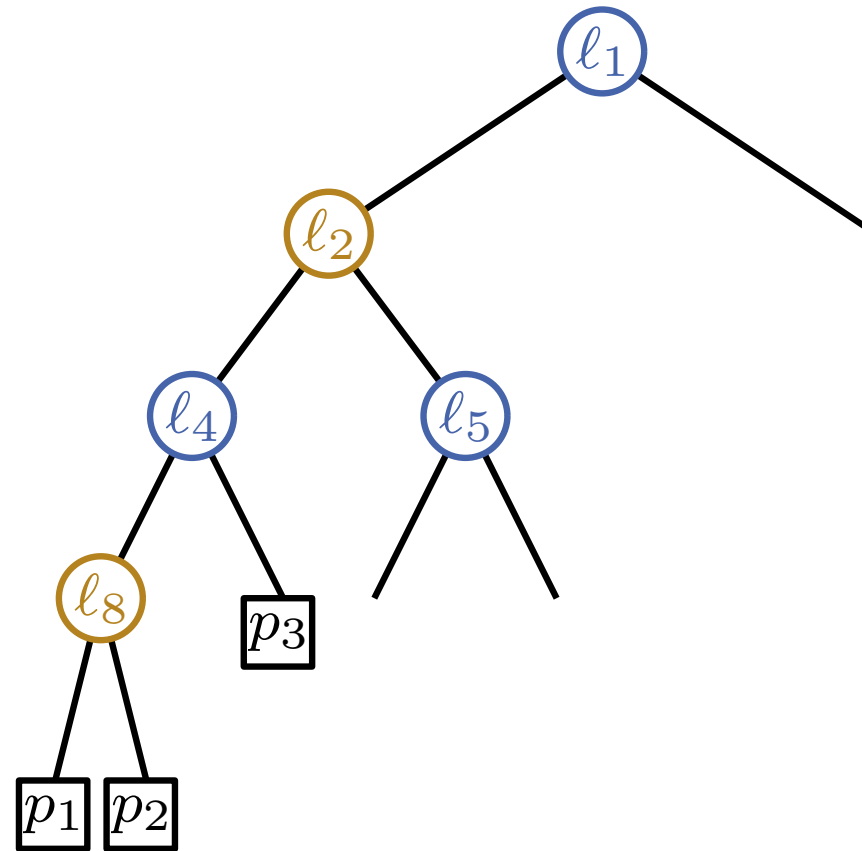
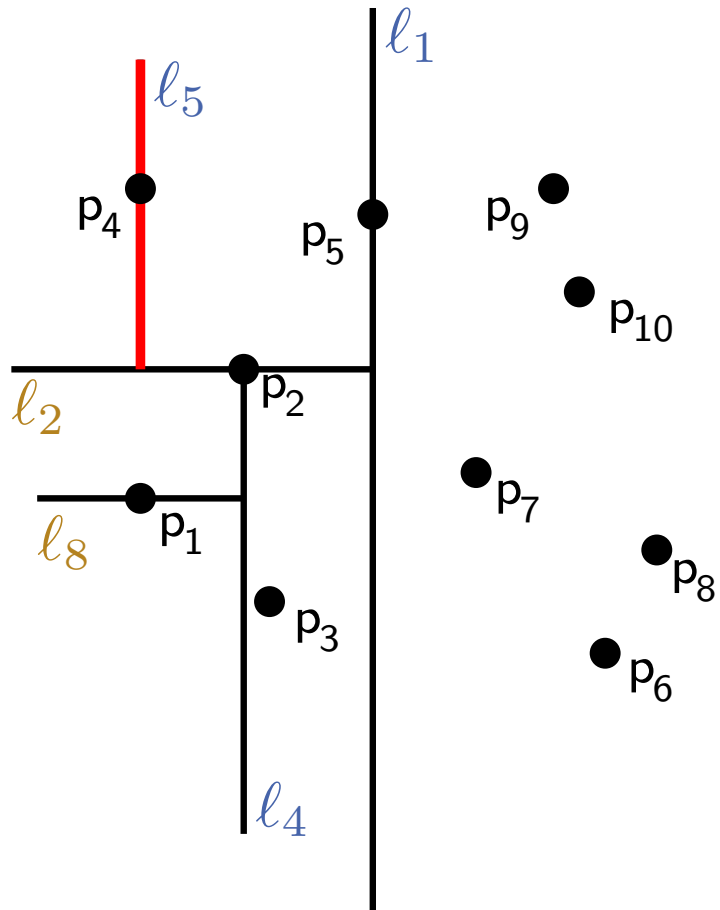
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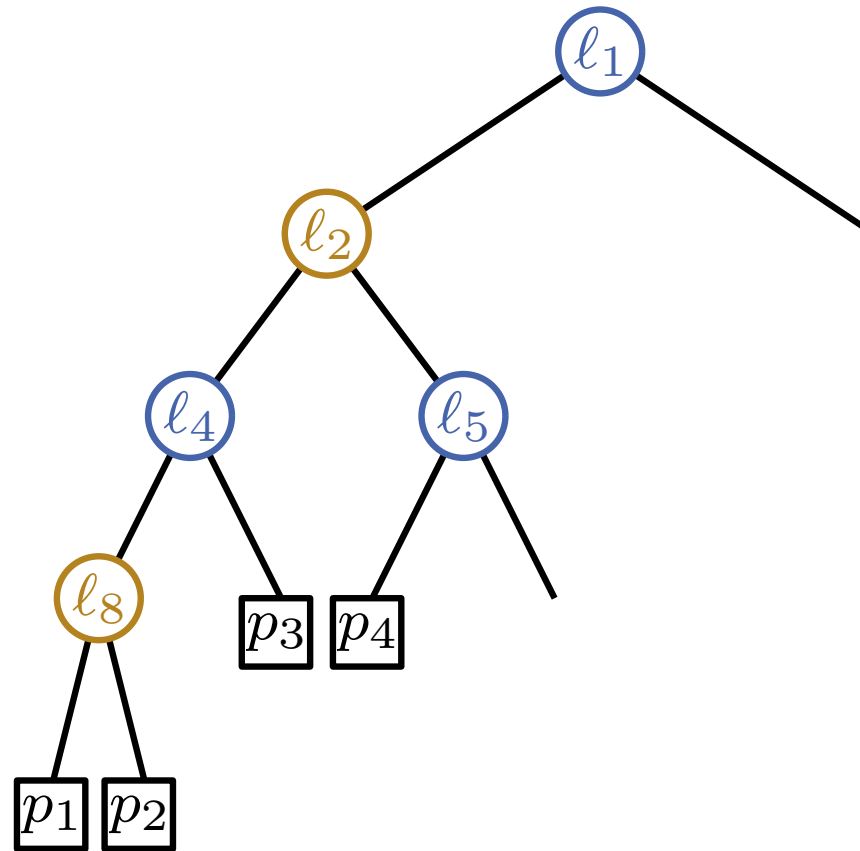
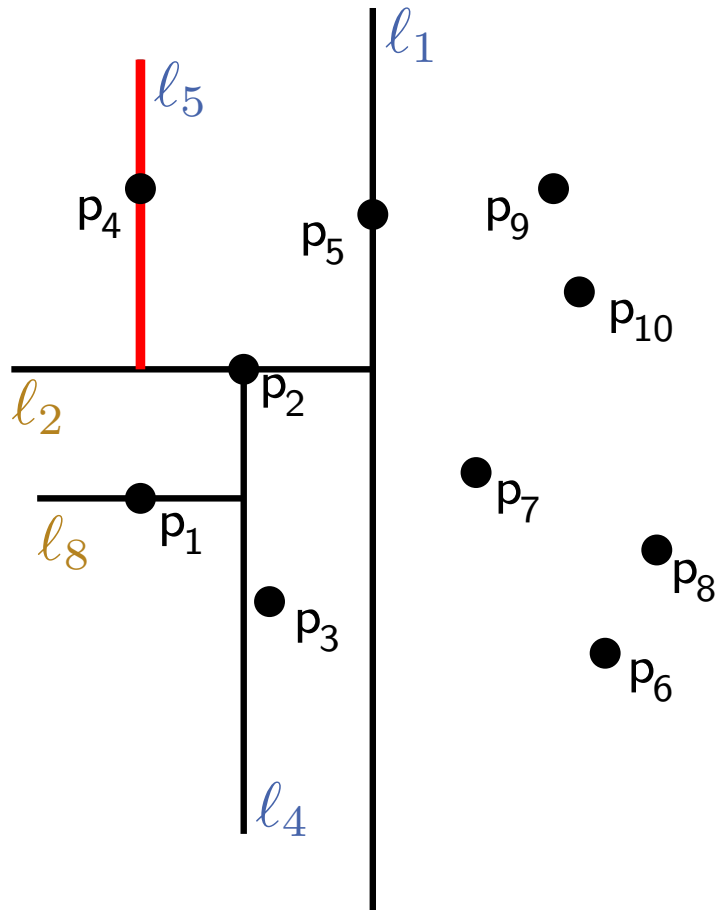
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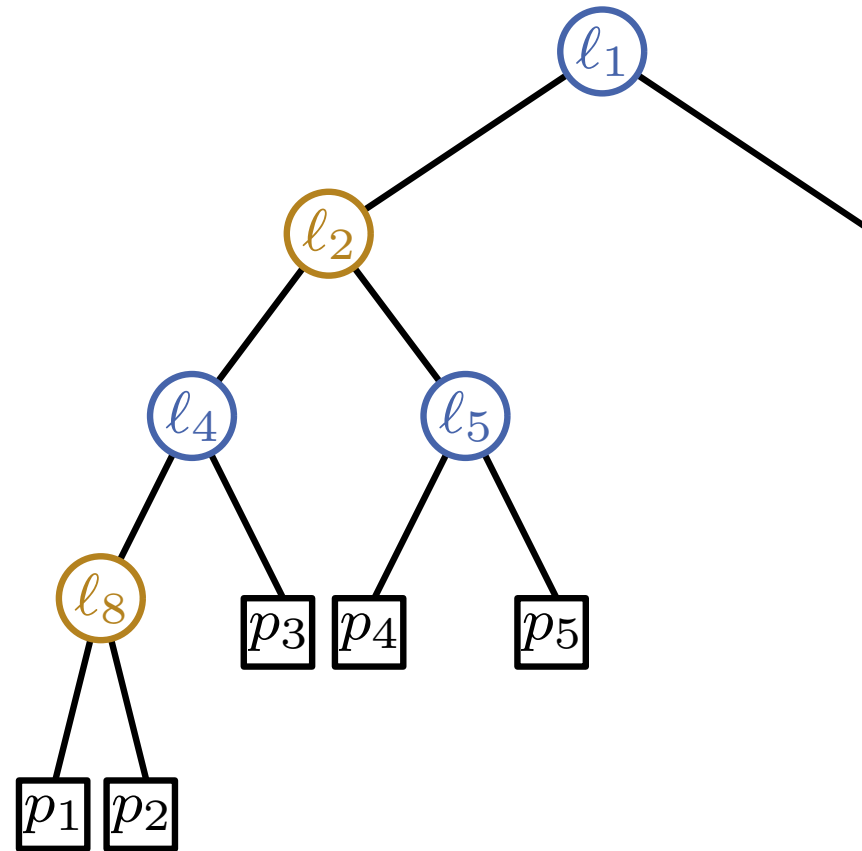
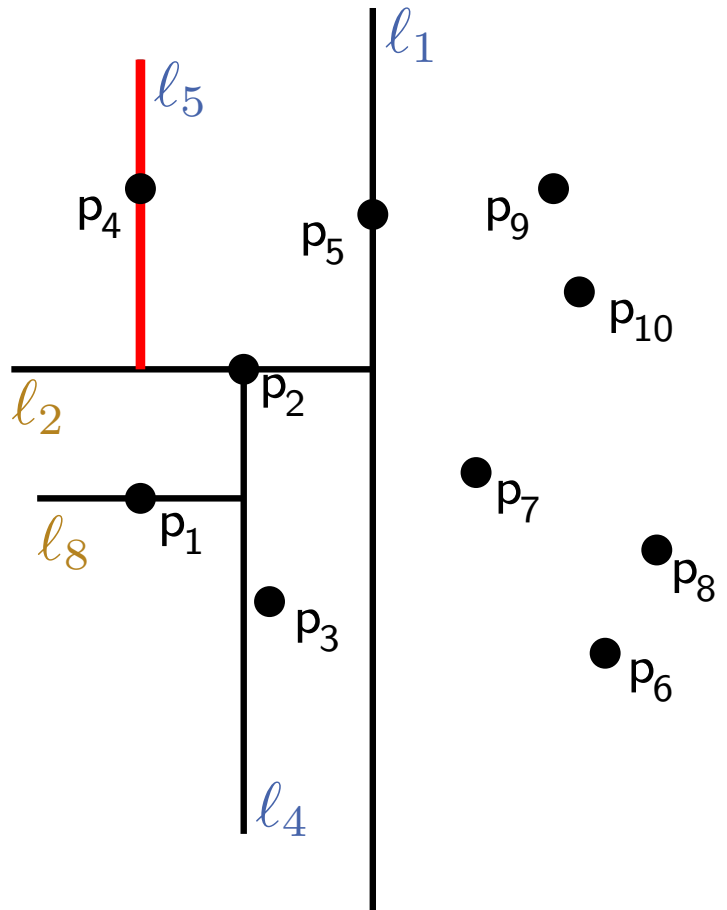
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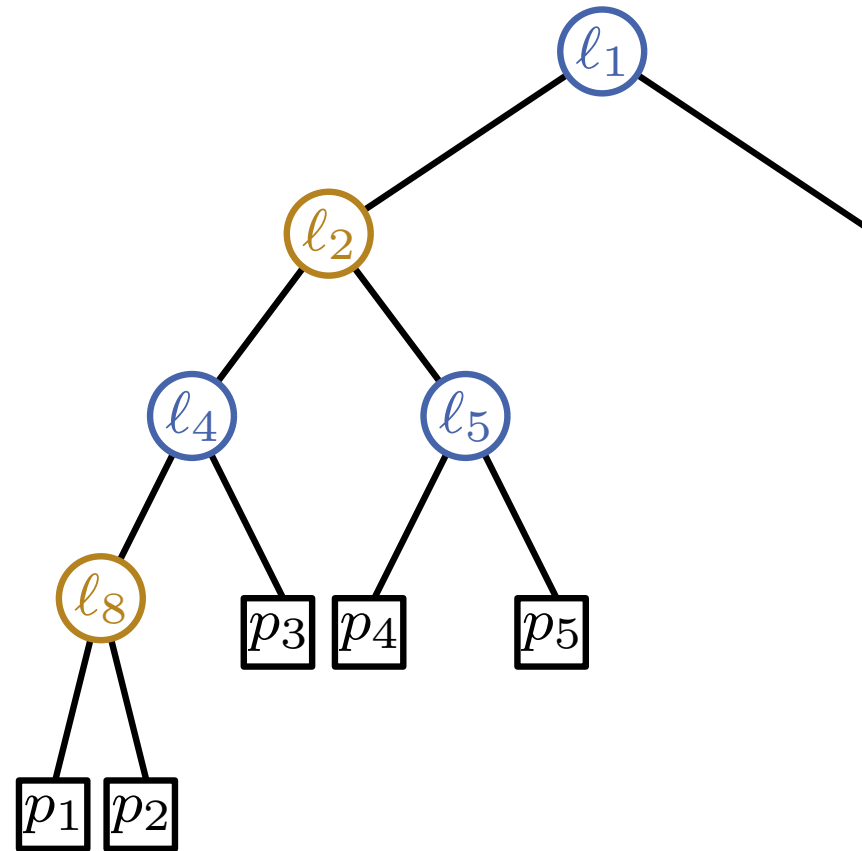
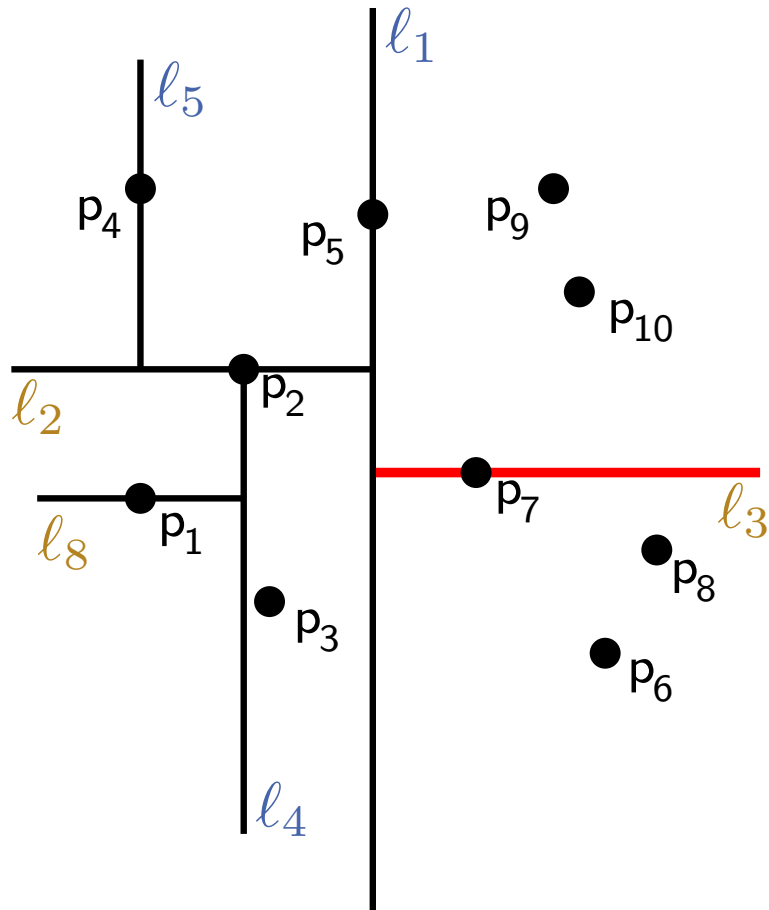
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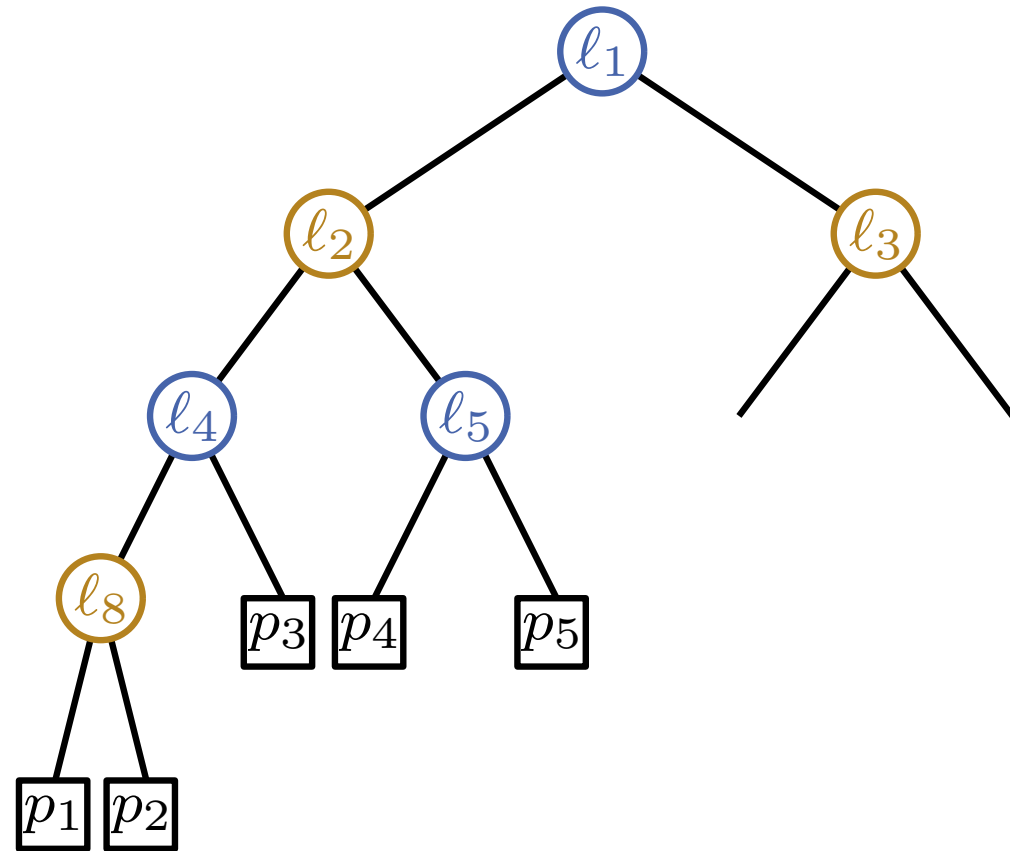
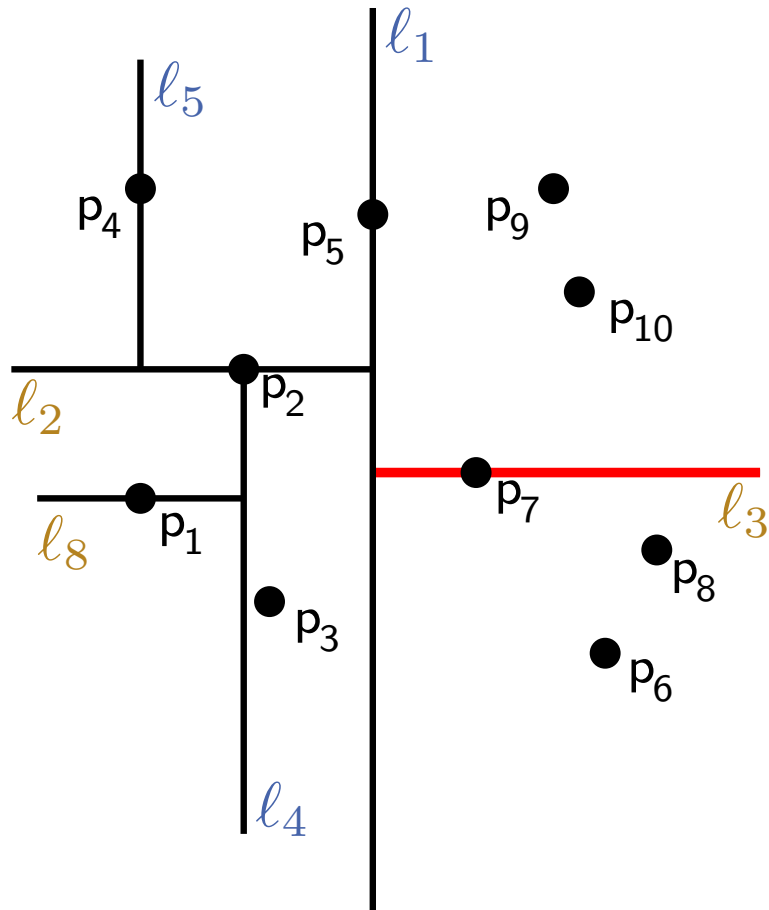
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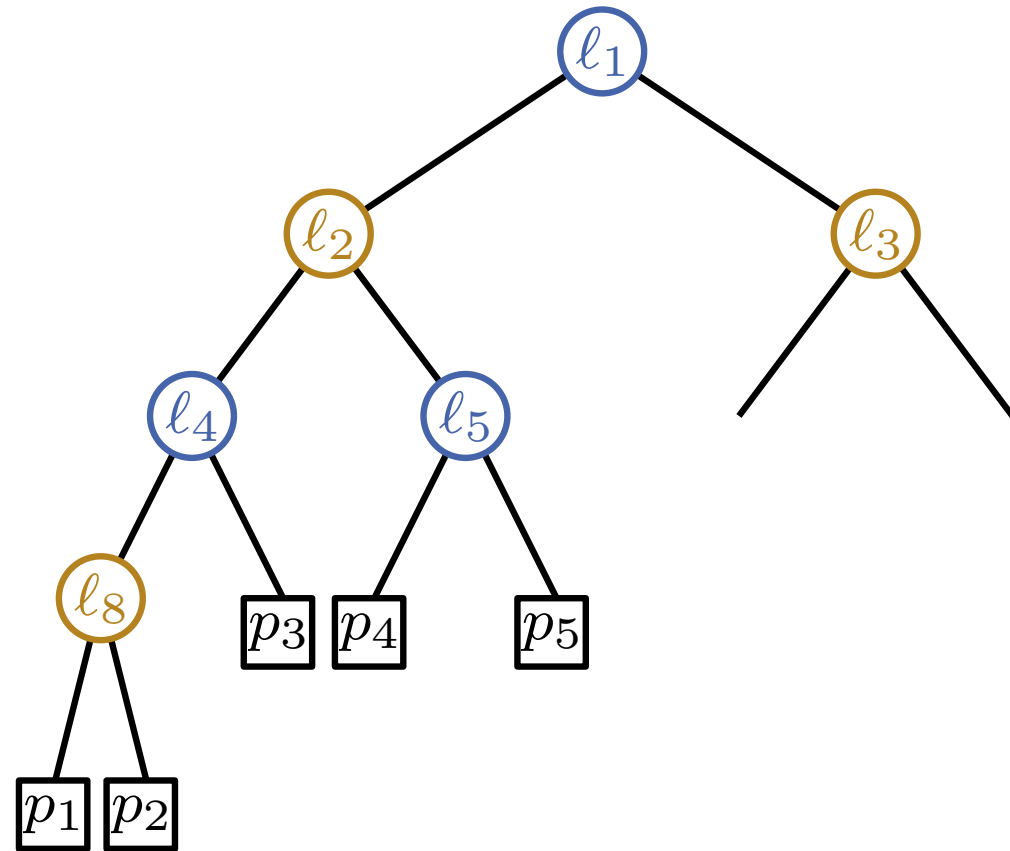
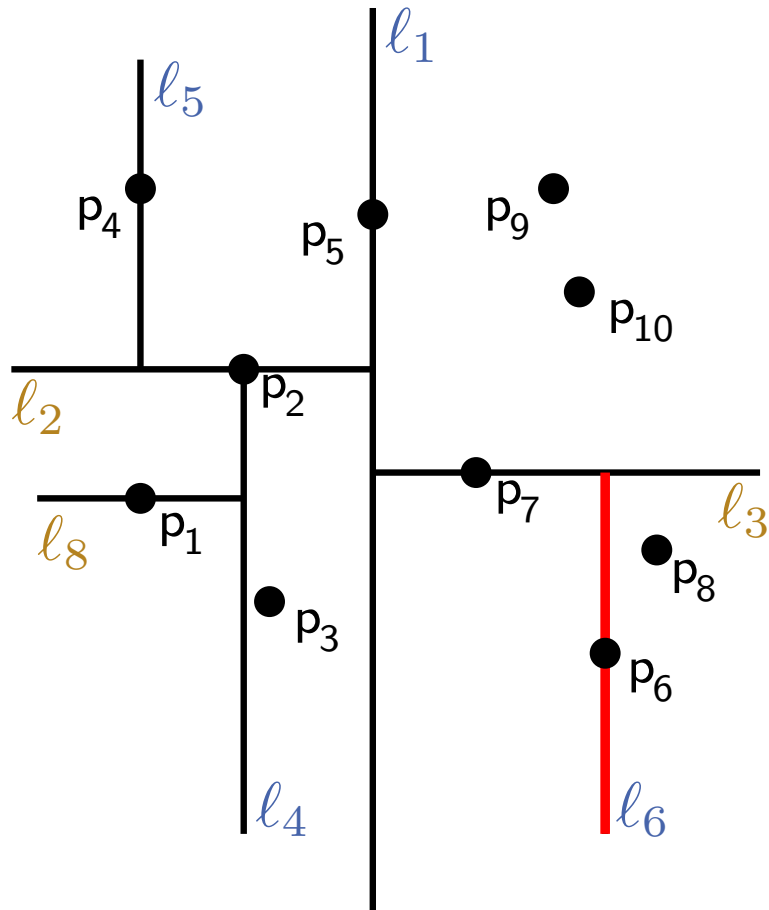
kd-Trees: Example



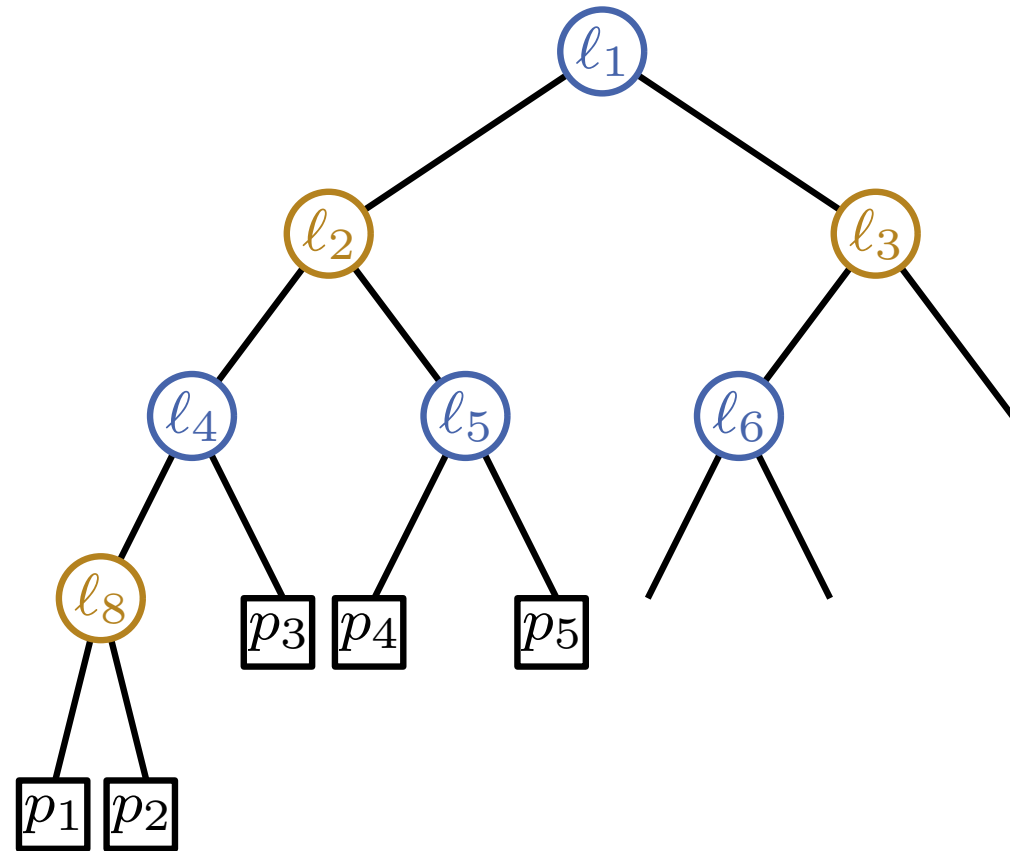
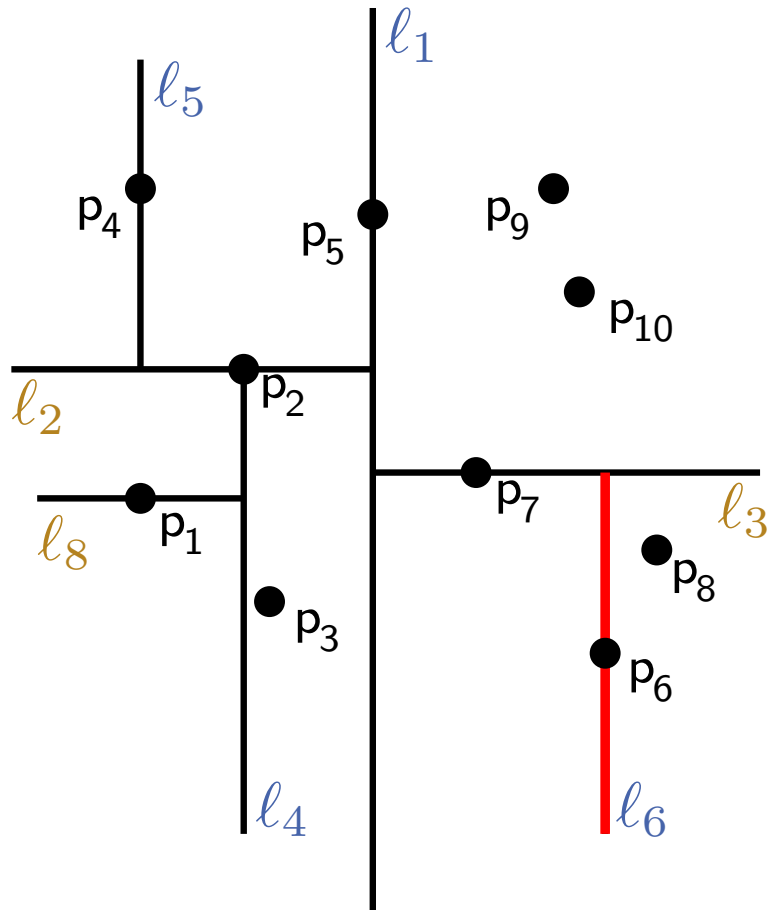
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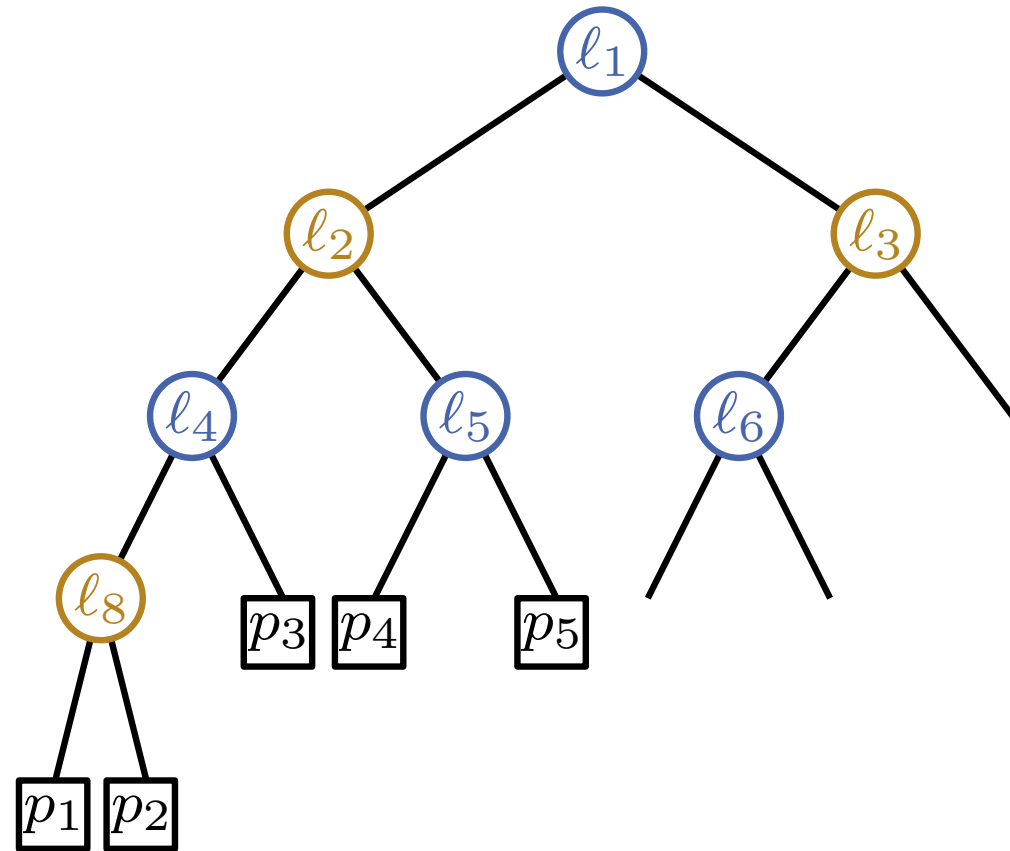
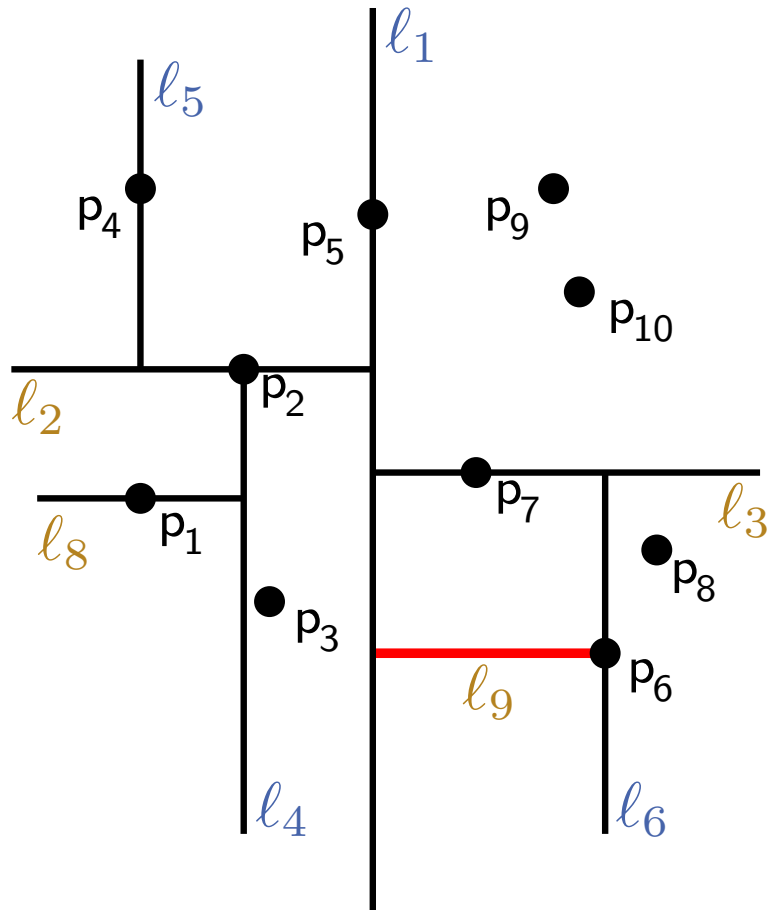
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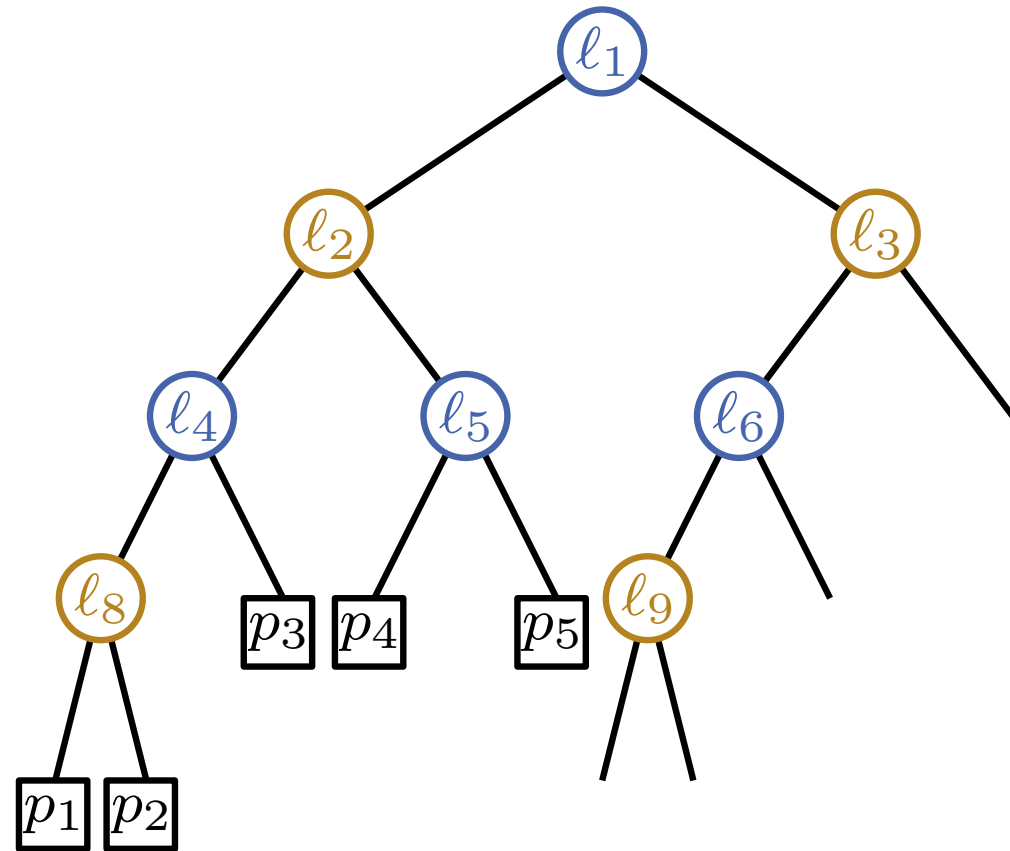
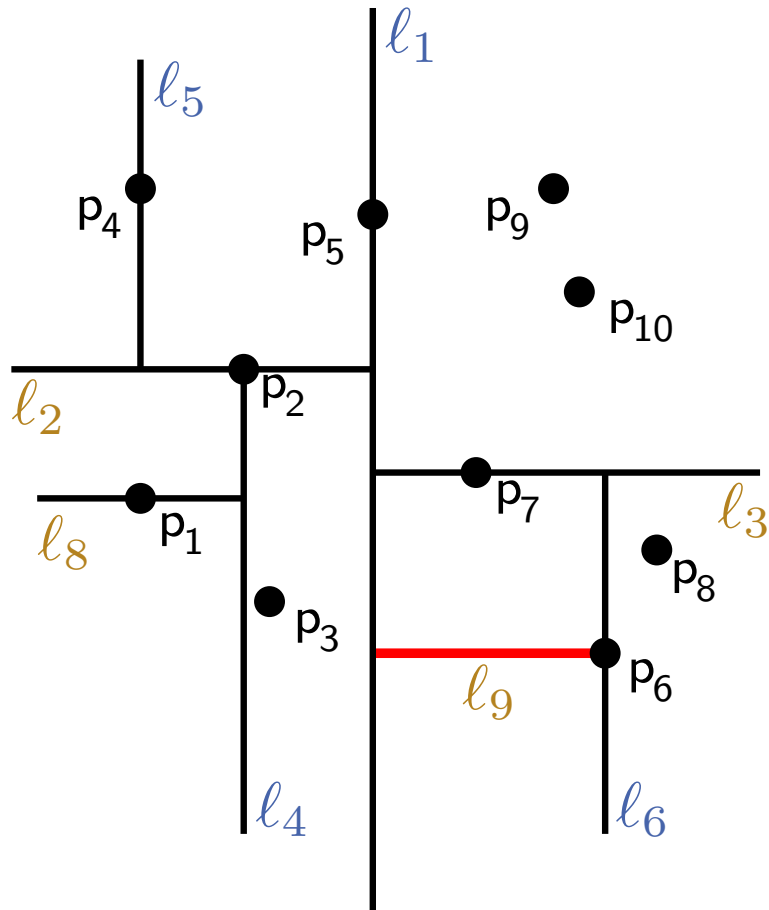
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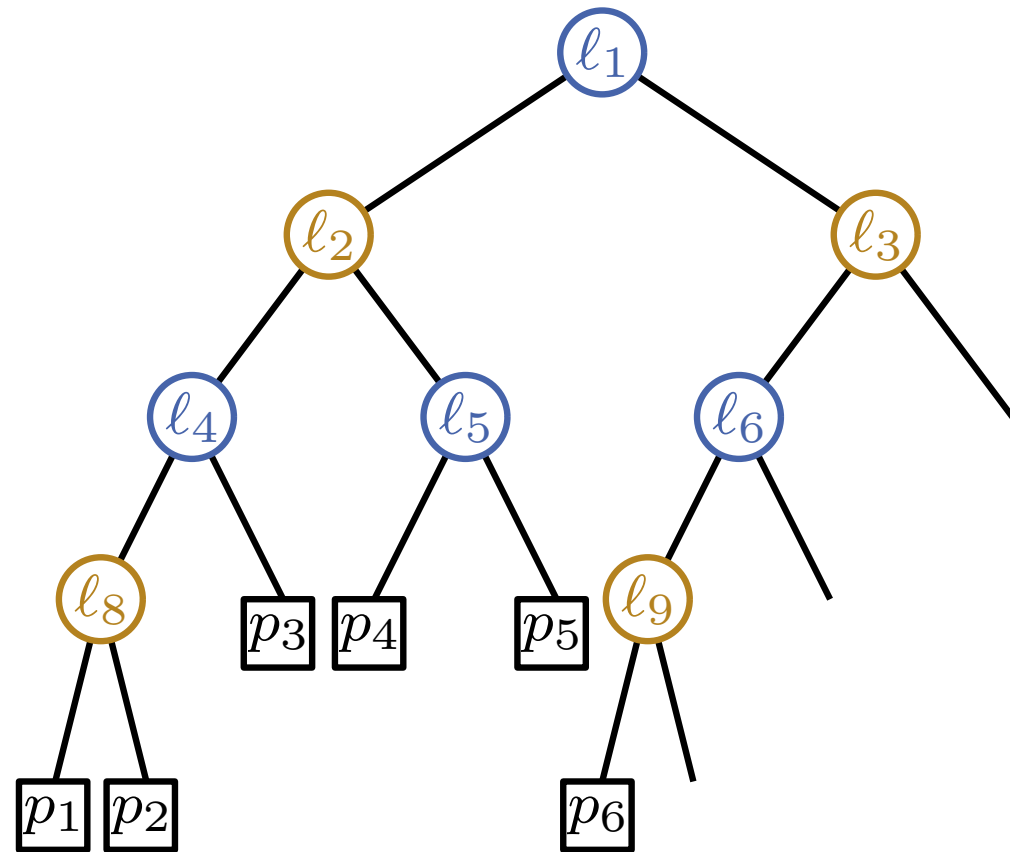
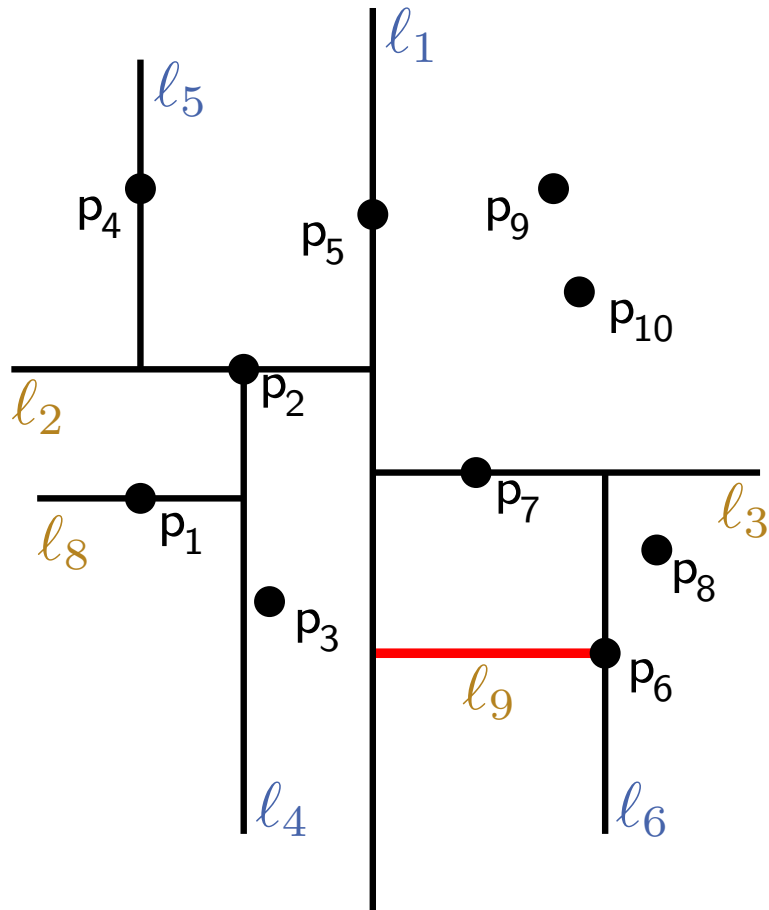
kd -Trees: Example



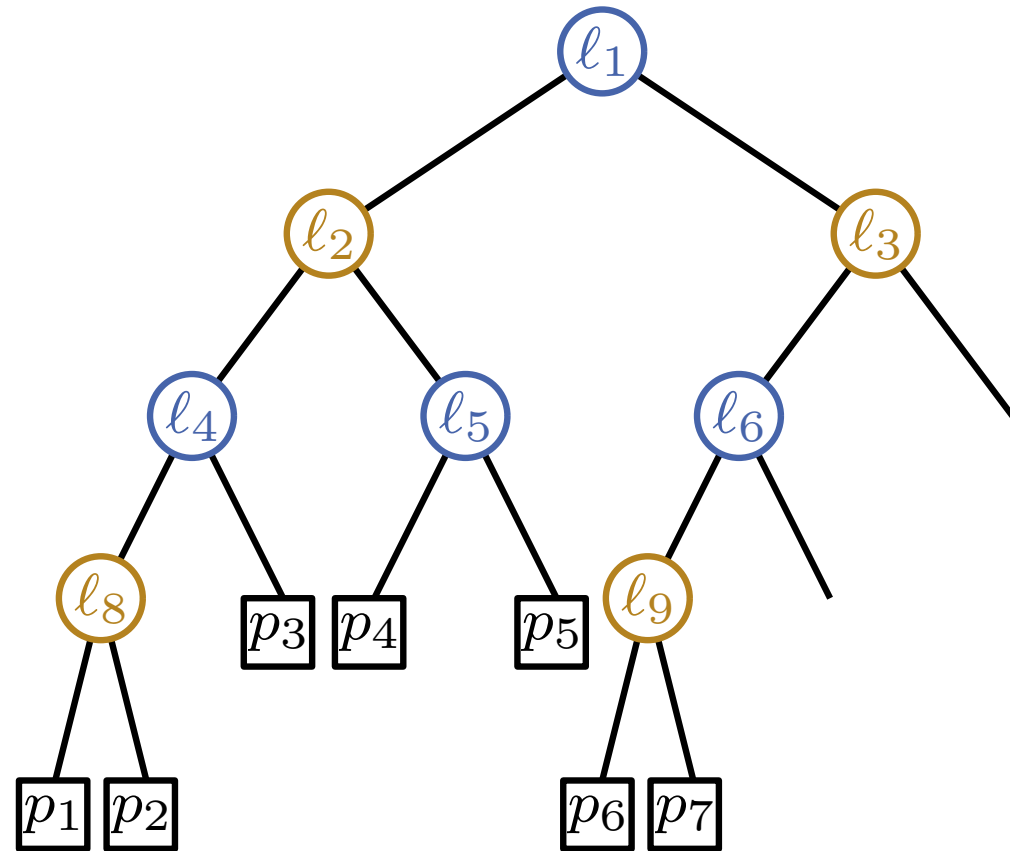
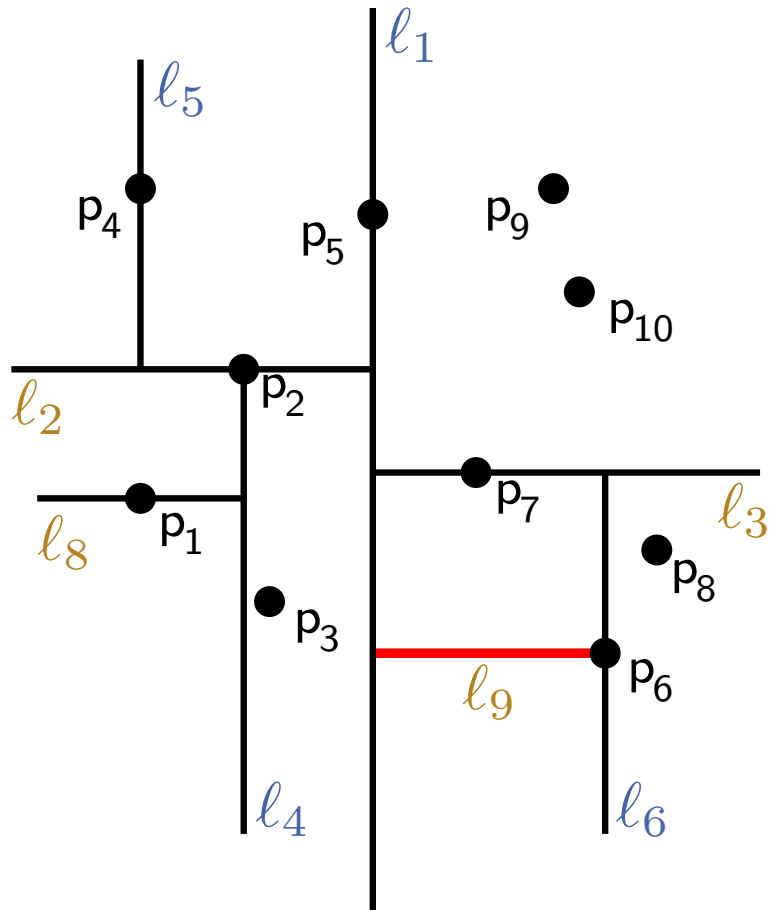
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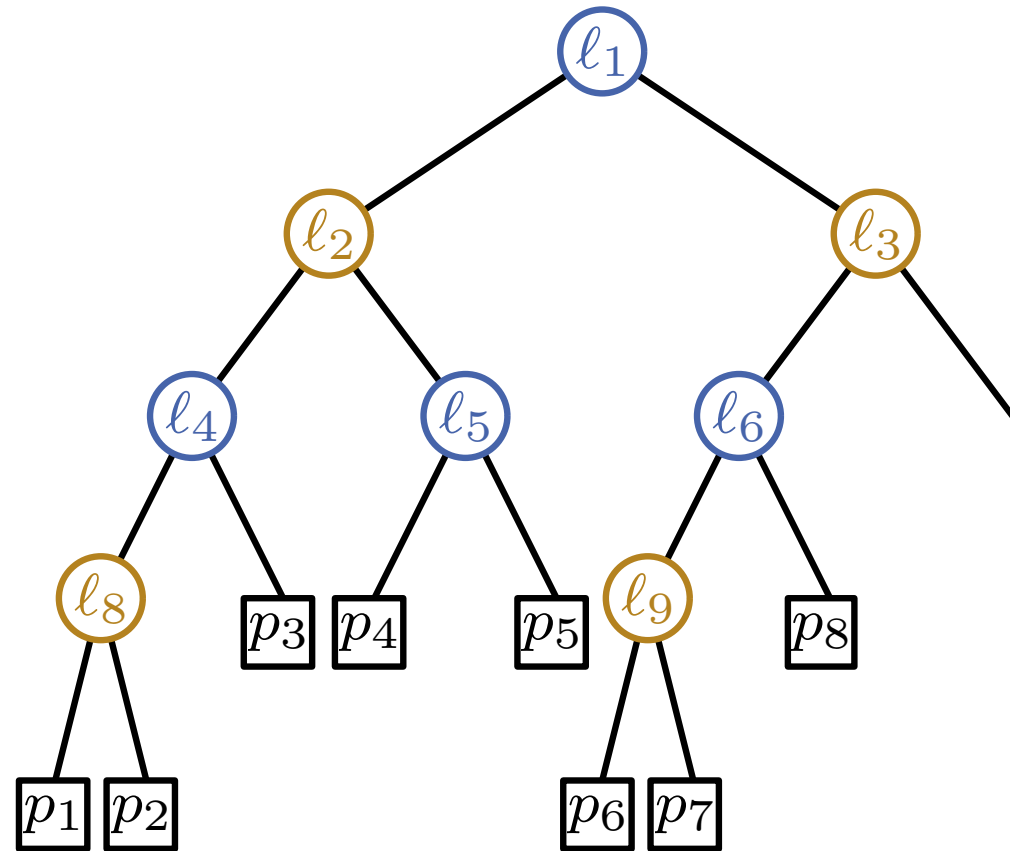
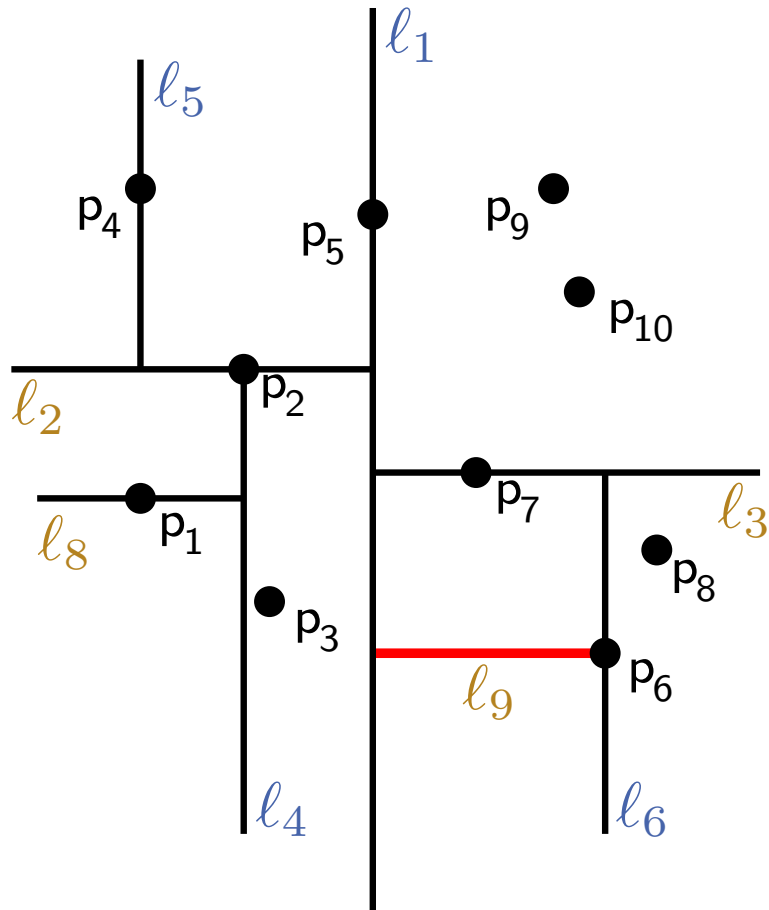
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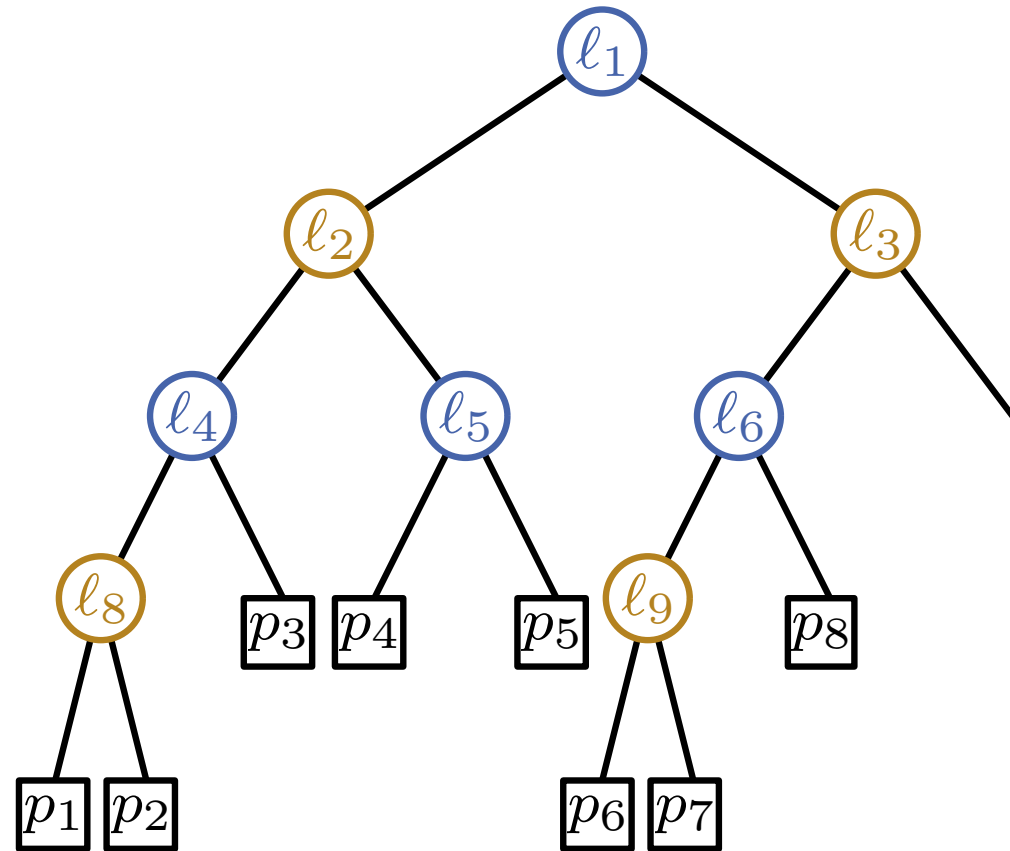
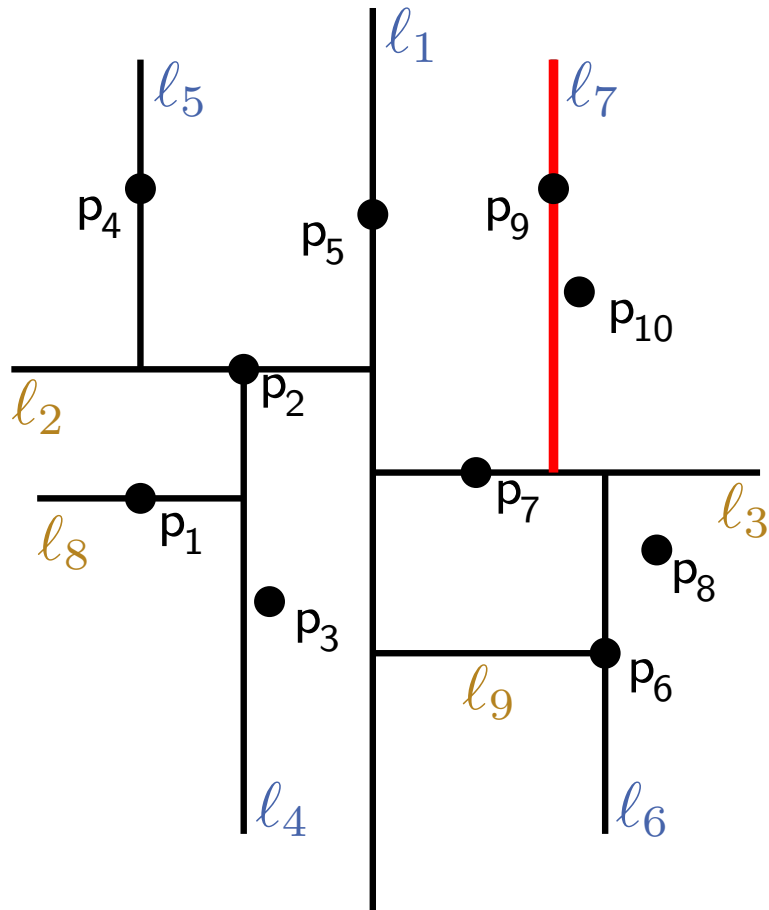
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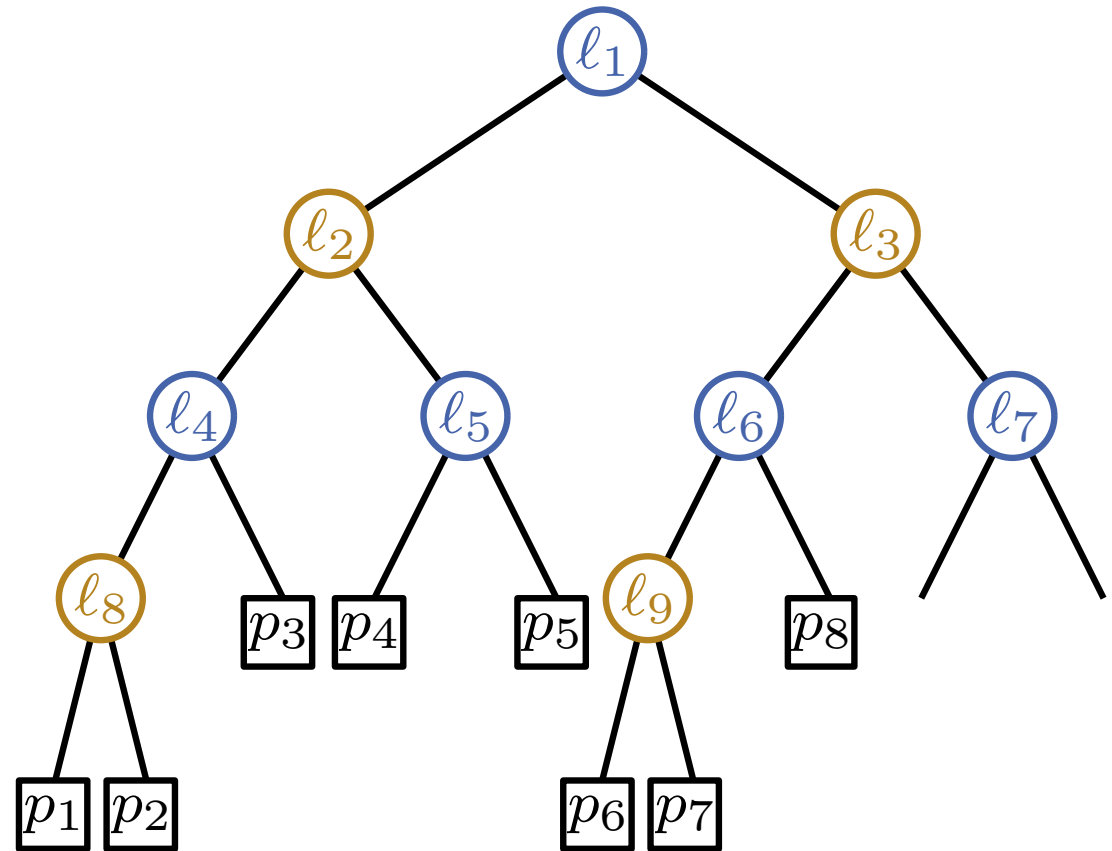
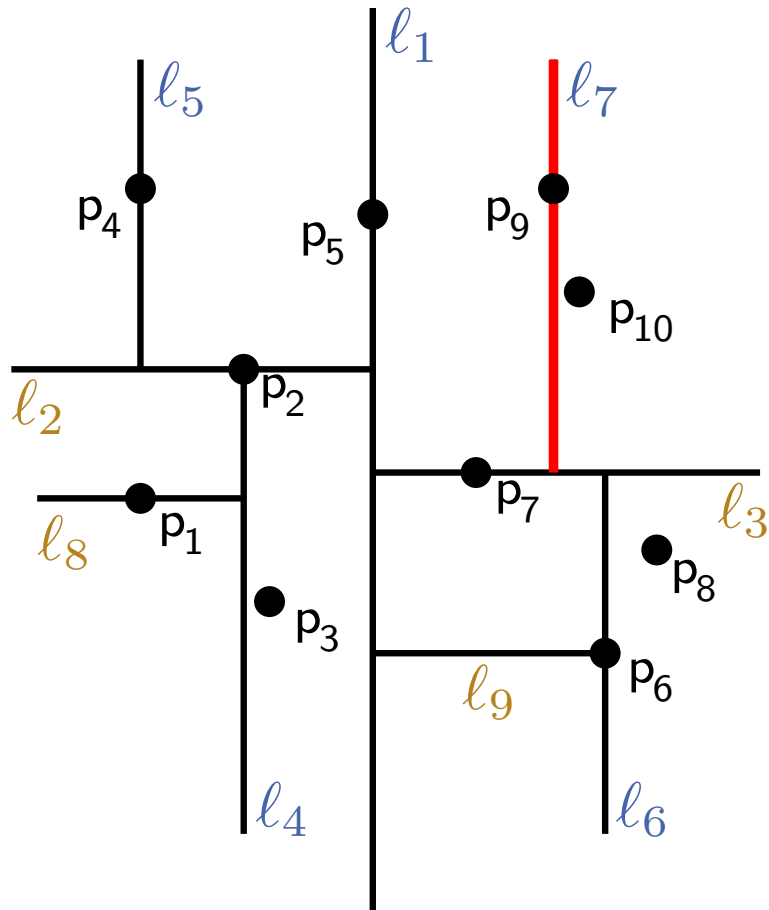
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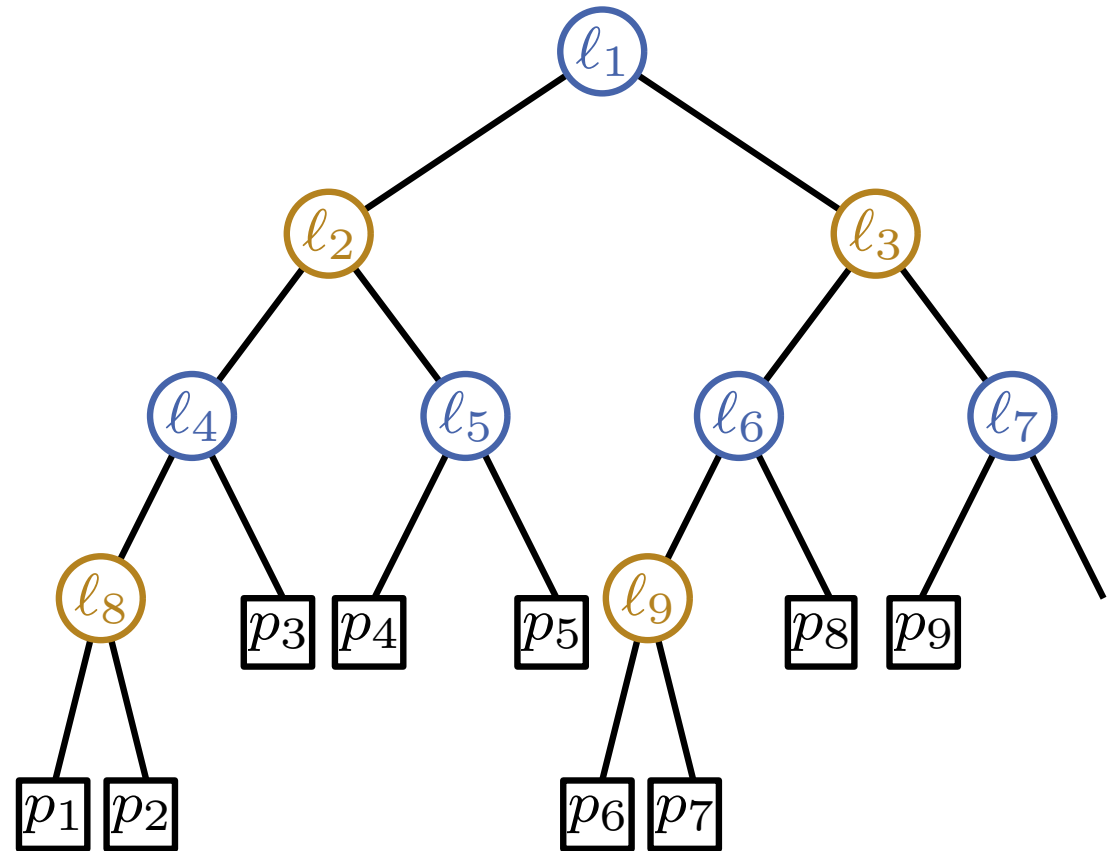
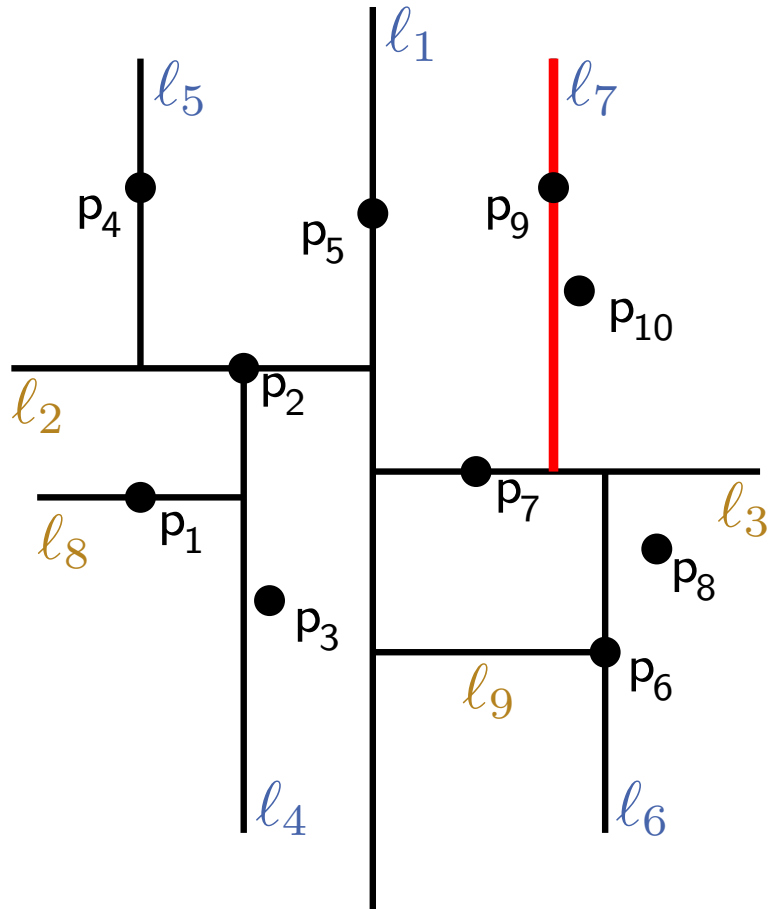
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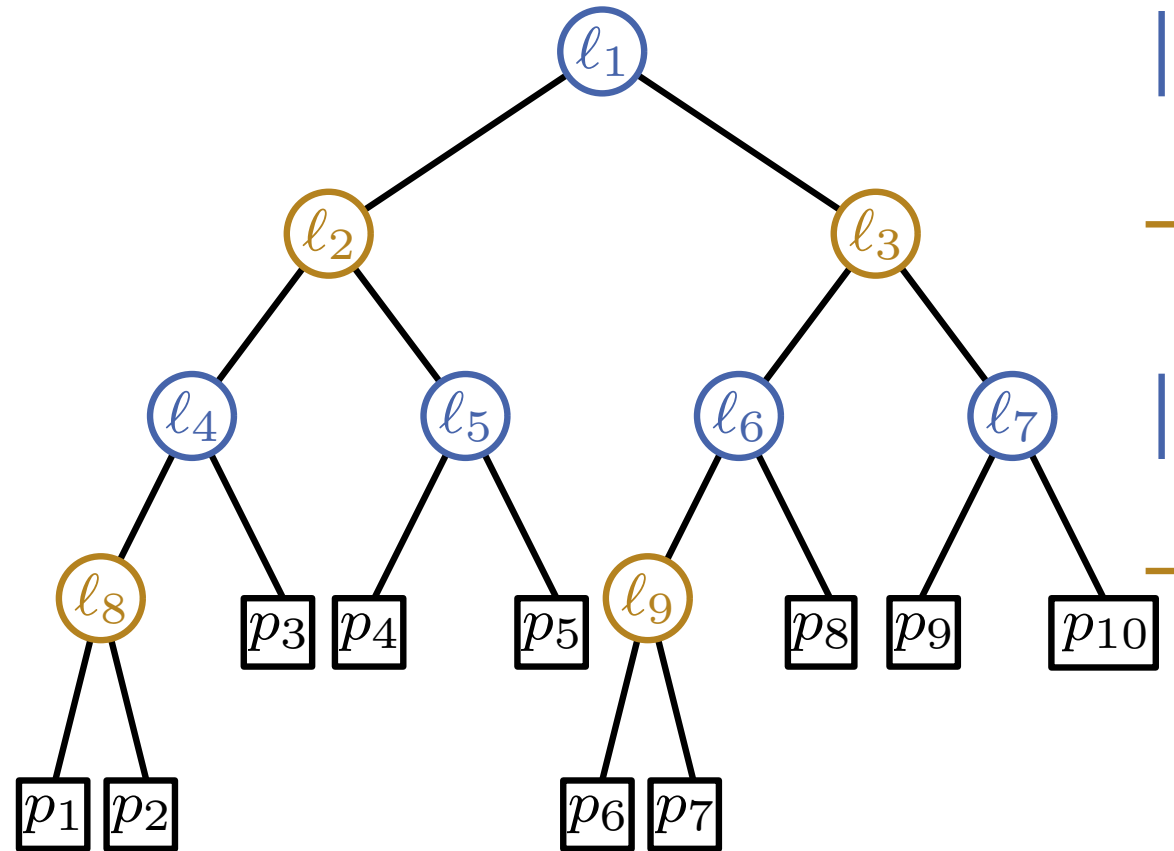
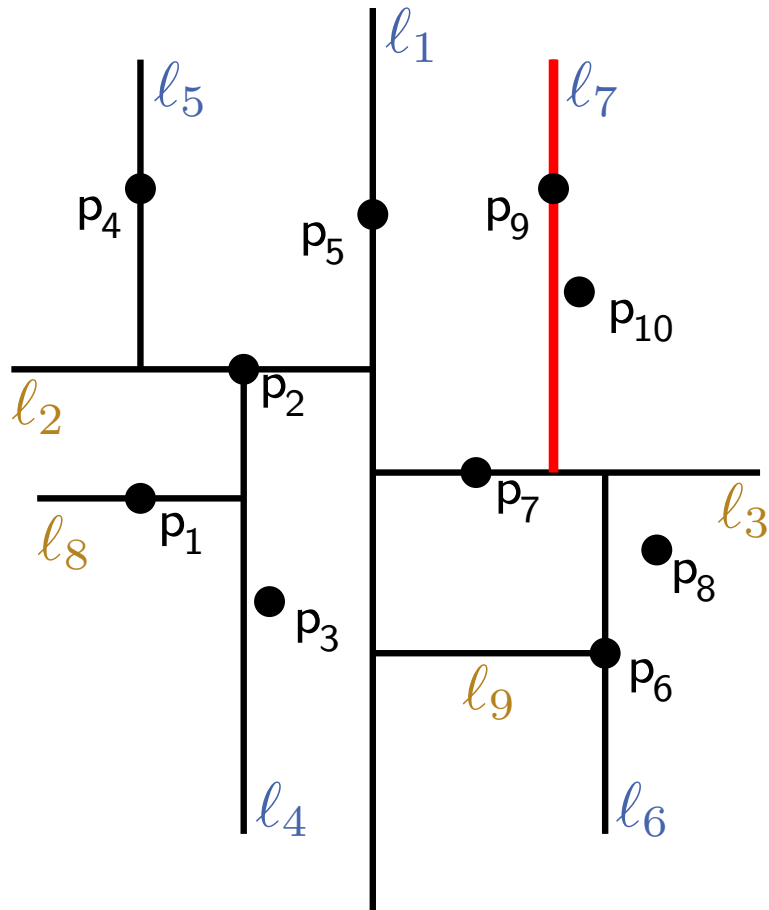
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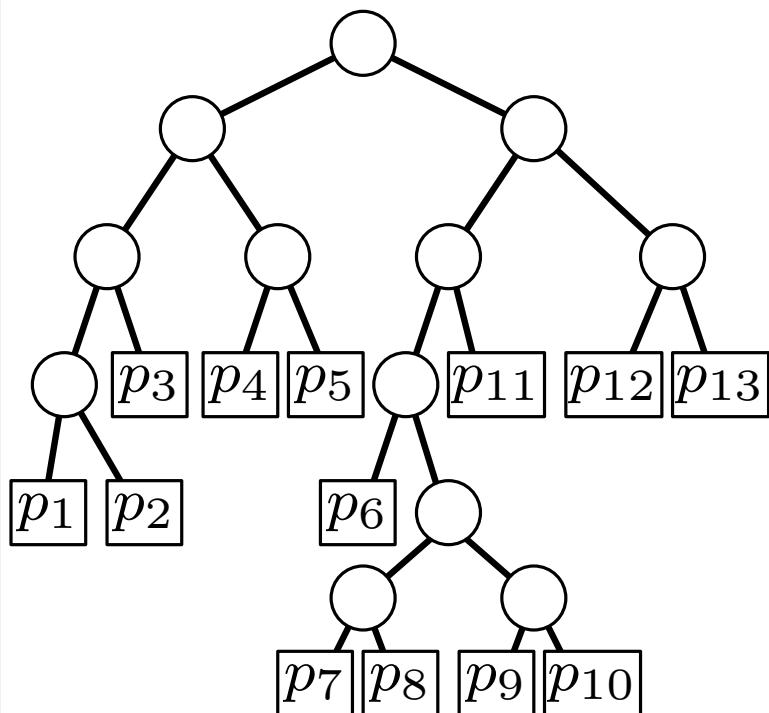
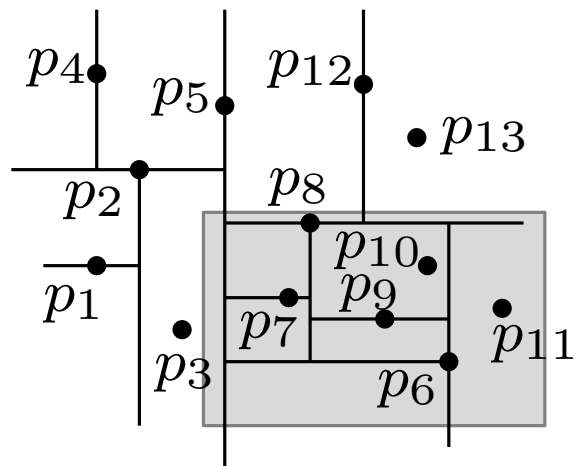
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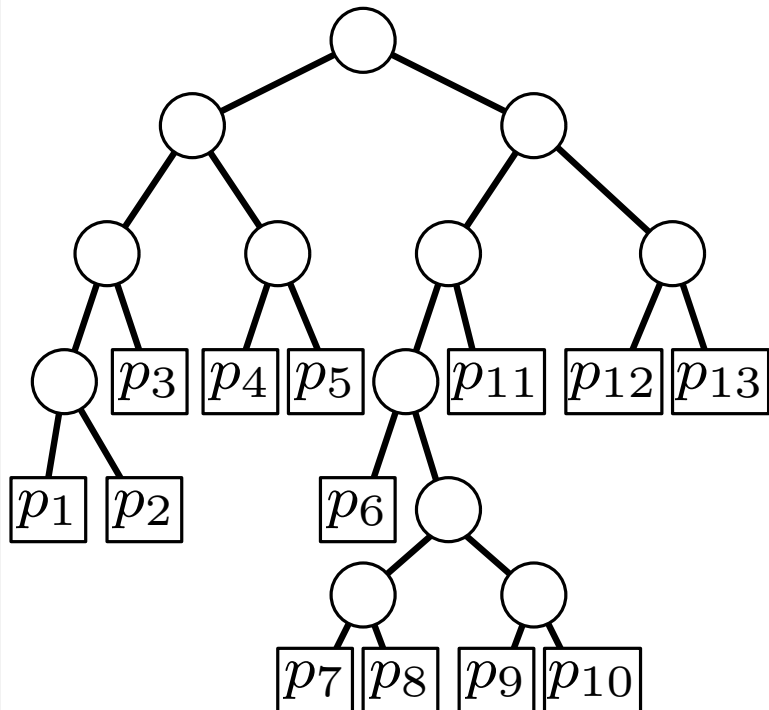
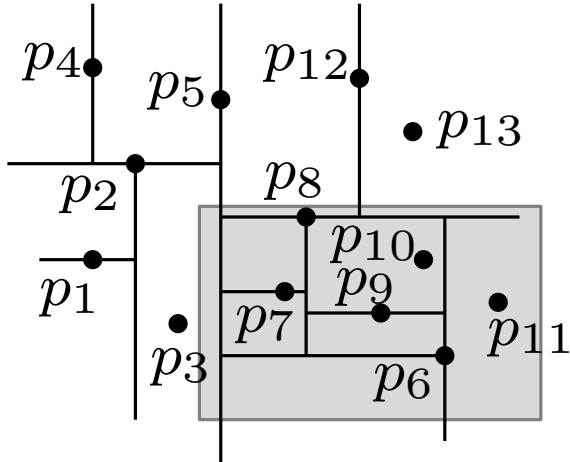
kd-Trees: Example



Range Queries in a kd -Tree



Range Queries in a kd -Tree



SearchKdTree(v, R)

if v leaf **then**

| report point p in v when $p \in R$

else

if region(lc(v)) $\subseteq R$ **then**

| ReportSubtree(lc(v))

else

if region(lc(v)) $\cap R \neq \emptyset$ **then**

| SearchKdTree(lc(v), R)

if region(rc(v)) $\subseteq R$ **then**

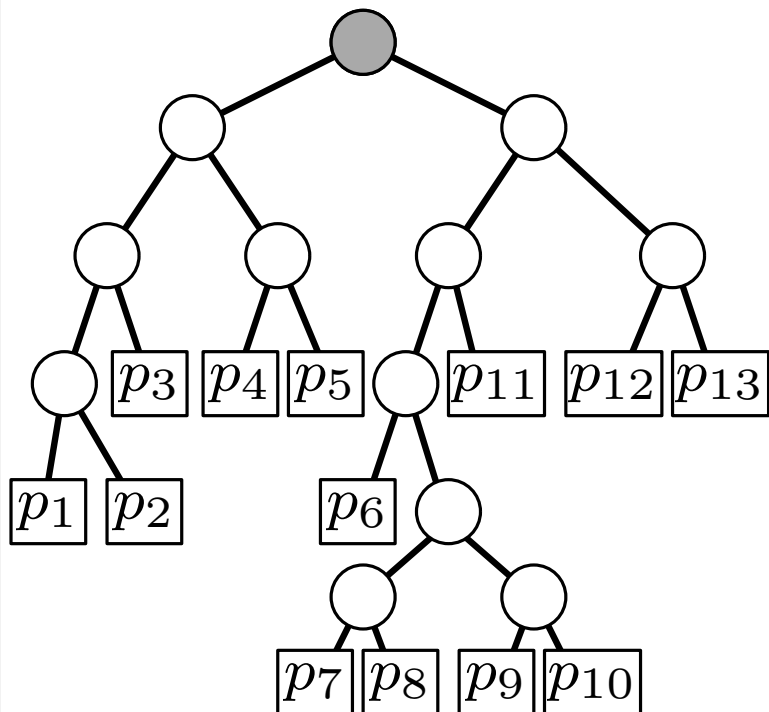
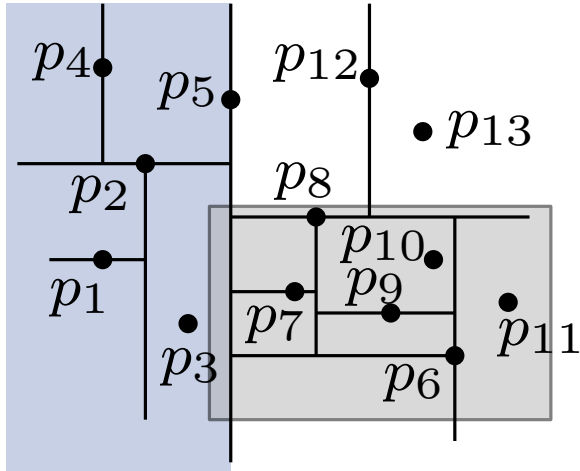
| ReportSubtree(rc(v))

else

if region(rc(v)) $\cap R \neq \emptyset$ **then**

| SearchKdTree(rc(v), R)

Range Queries in a kd -Tree



SearchKdTree(v, R)

if v leaf **then**

| report point p in v when $p \in R$

else

if $\text{region}(\text{lc}(v)) \subseteq R$ **then**

| ReportSubtree($\text{lc}(v)$)

else

if $\text{region}(\text{lc}(v)) \cap R \neq \emptyset$ **then**

| SearchKdTree($\text{lc}(v), R$)

if $\text{region}(\text{rc}(v)) \subseteq R$ **then**

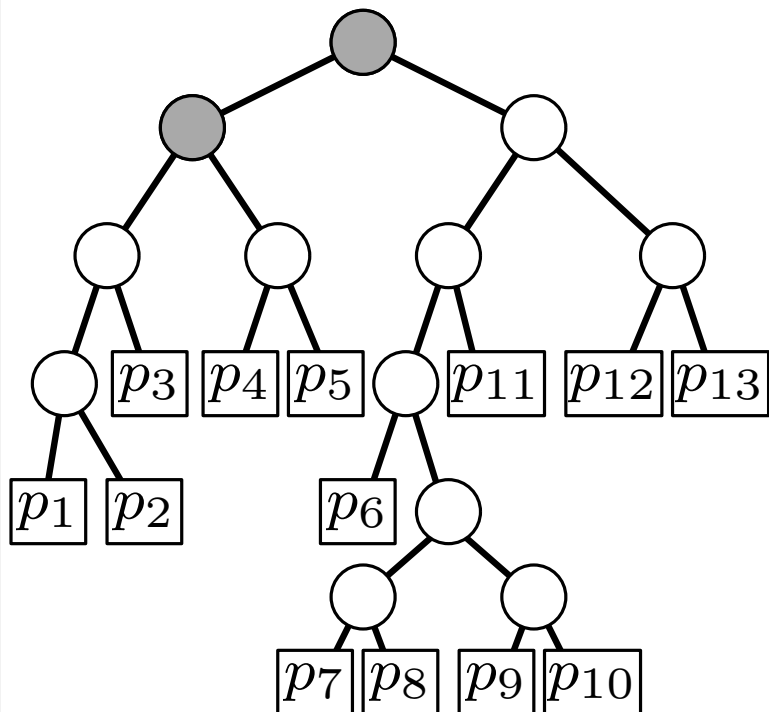
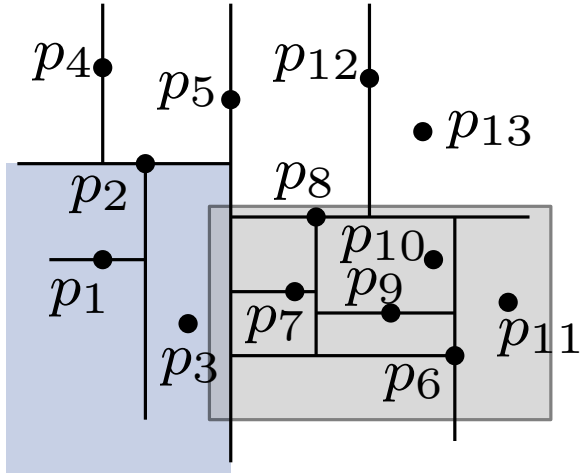
| ReportSubtree($\text{rc}(v)$)

else

if $\text{region}(\text{rc}(v)) \cap R \neq \emptyset$ **then**

| SearchKdTree($\text{rc}(v), R$)

Range Queries in a kd -Tree



SearchKdTree(v, R)

if v leaf **then**

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else

if region(lc(v)) $\subseteq R$ **then**

 | ReportSubtree(lc(v))

else

if region(lc(v)) $\cap R \neq \emptyset$ **then**

 | SearchKdTree(lc(v), R)

if region(rc(v)) $\subseteq R$ **then**

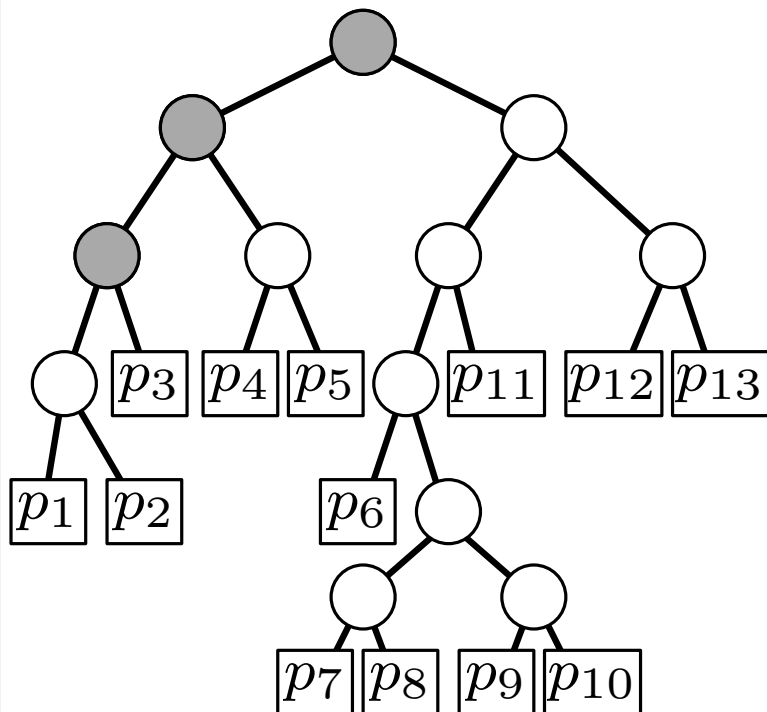
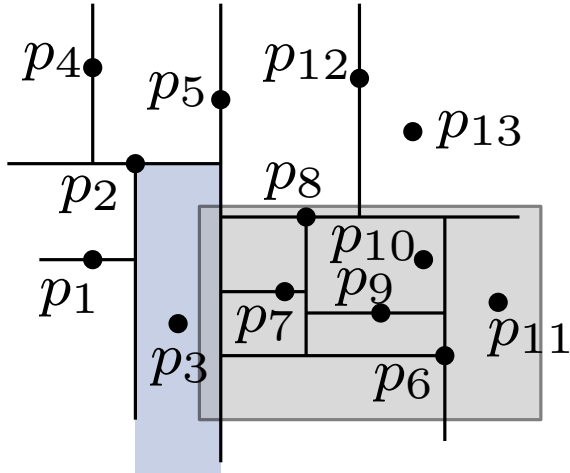
 | ReportSubtree(rc(v))

else

if region(rc(v)) $\cap R \neq \emptyset$ **then**

 | SearchKdTree(rc(v), R)

Range Queries in a kd -Tree



SearchKdTree(v, R)

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 report point p in v when $p \in R$

else

if region(lc(v)) $\subseteq R$ **then**

 ReportSubtree(lc(v))

else

if region(lc(v)) $\cap R \neq \emptyset$ **then**

 SearchKdTree(lc(v), R)

if region(rc(v)) $\subseteq R$ **then**

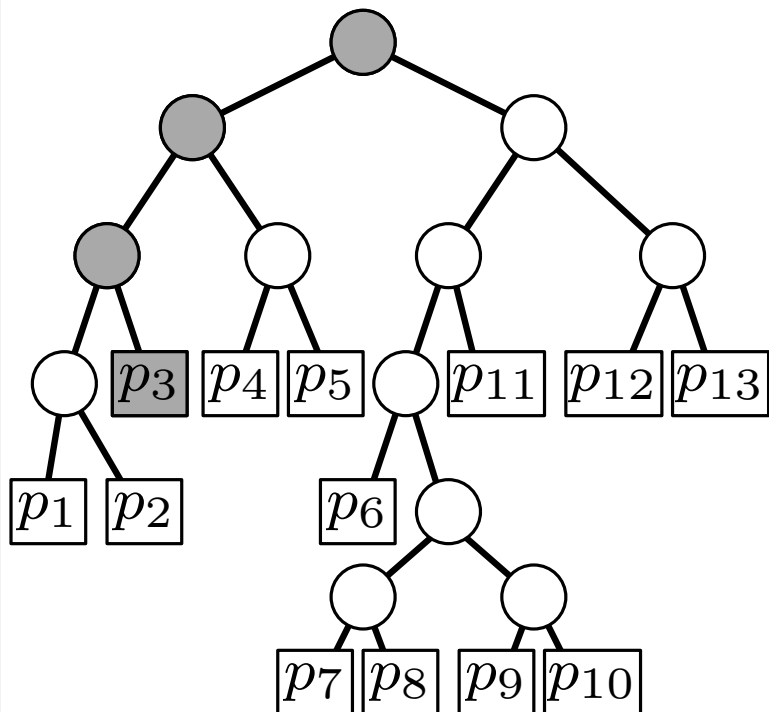
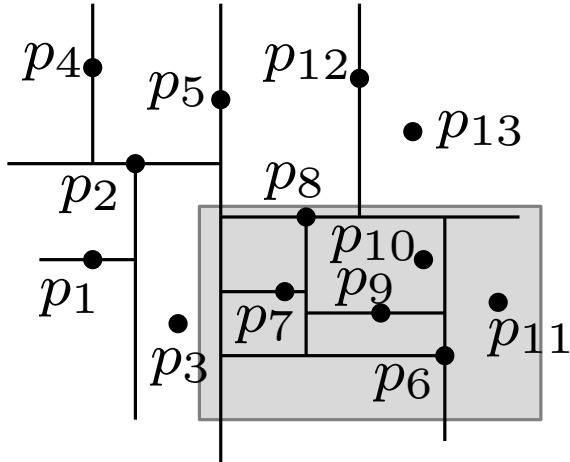
 ReportSubtree(rc(v))

else

if region(rc(v)) $\cap R \neq \emptyset$ **then**

 SearchKdTree(rc(v), R)

Range Queries in a kd -Tree



SearchKdTree(v, R)

if v leaf **then**

 report point p in v when $p \in R$

else

if region($lc(v)$) $\subseteq R$ **then**

 ReportSubtree($lc(v)$)

else

if region($lc(v)$) $\cap R \neq \emptyset$ **then**

 SearchKdTree($lc(v), R$)

if region($rc(v)$) $\subseteq R$ **then**

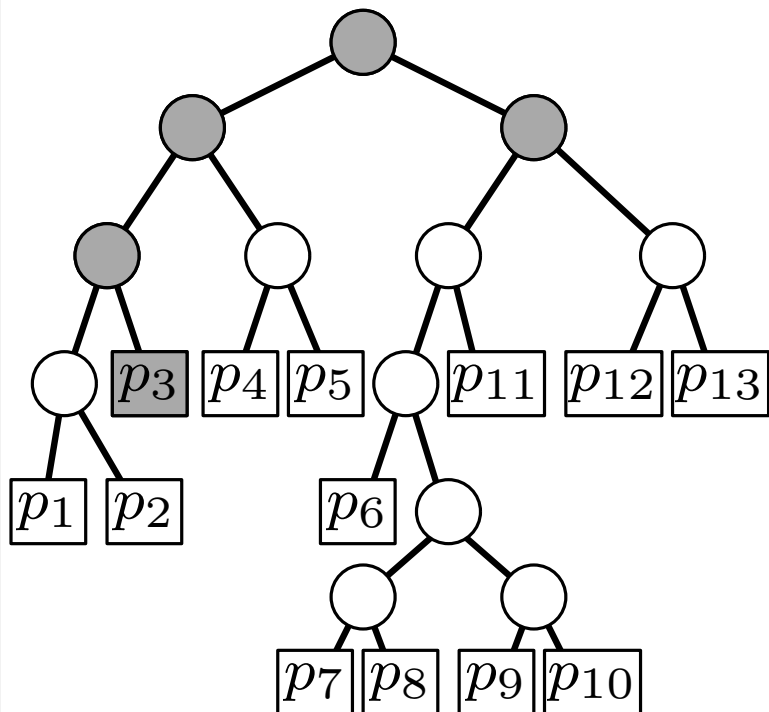
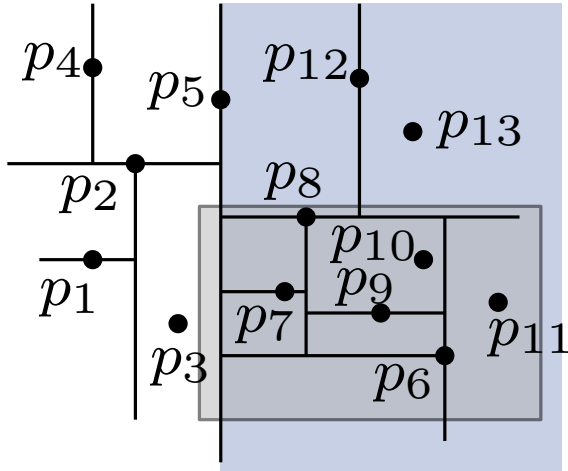
 ReportSubtree($rc(v)$)

else

if region($rc(v)$) $\cap R \neq \emptyset$ **then**

 SearchKdTree($rc(v), R$)

Range Queries in a kd -Tree



SearchKdTree(v, R)

if v leaf **then**

 report point p in v when $p \in R$

else

if region($lc(v)$) $\subseteq R$ **then**

 ReportSubtree($lc(v)$)

else

if region($lc(v)$) $\cap R \neq \emptyset$ **then**

 SearchKdTree($lc(v), R$)

if region($rc(v)$) $\subseteq R$ **then**

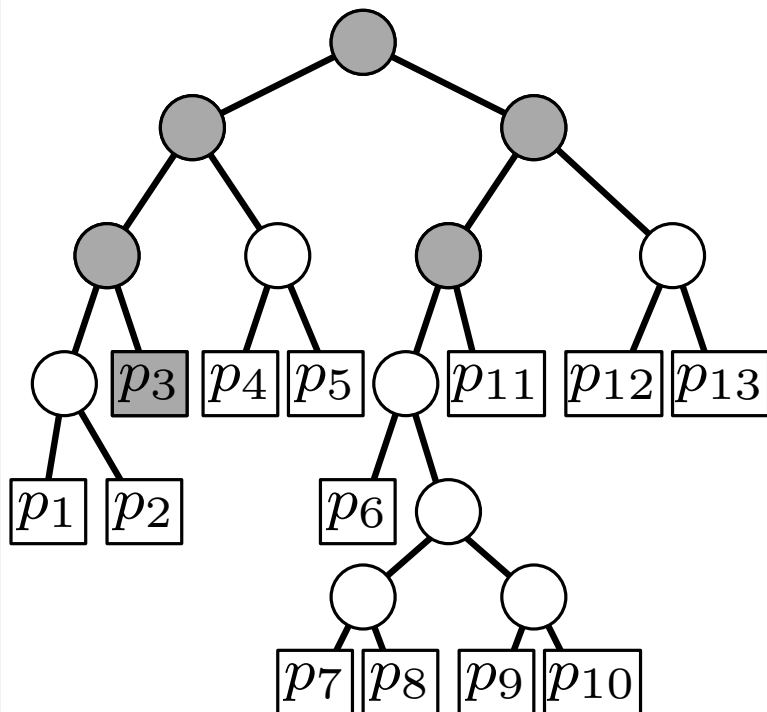
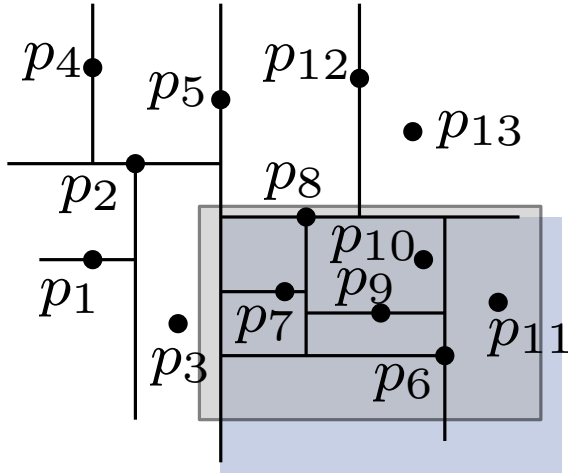
 ReportSubtree($rc(v)$)

else

if region($rc(v)$) $\cap R \neq \emptyset$ **then**

 SearchKdTree($rc(v), R$)

Range Queries in a kd -Tree



SearchKdTree(v, R)

if v leaf **then**

| report point p in v when $p \in R$

else

if $\text{region}(\text{lc}(v)) \subseteq R$ **then**

| ReportSubtree($\text{lc}(v)$)

else

if $\text{region}(\text{lc}(v)) \cap R \neq \emptyset$ **then**

| SearchKdTree($\text{lc}(v), R$)

if $\text{region}(\text{rc}(v)) \subseteq R$ **then**

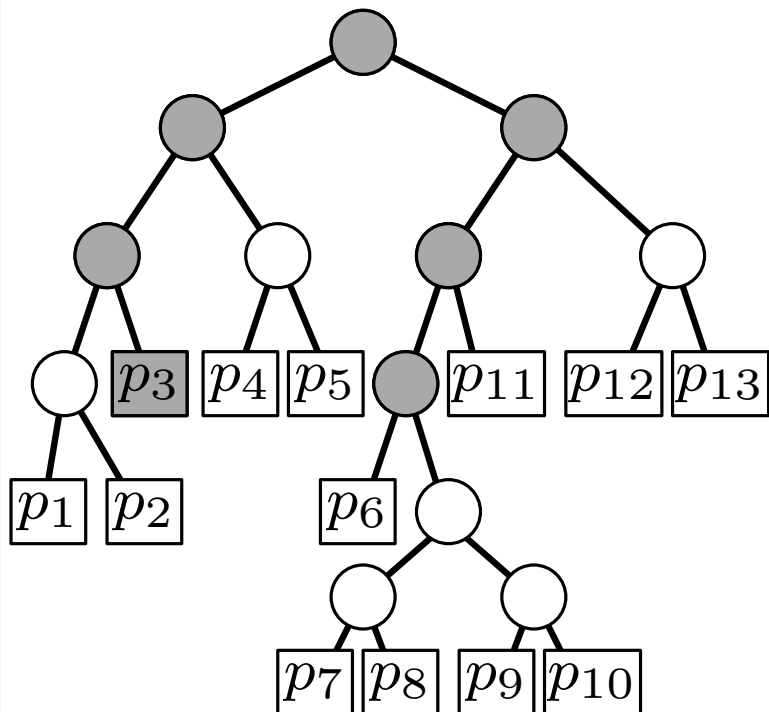
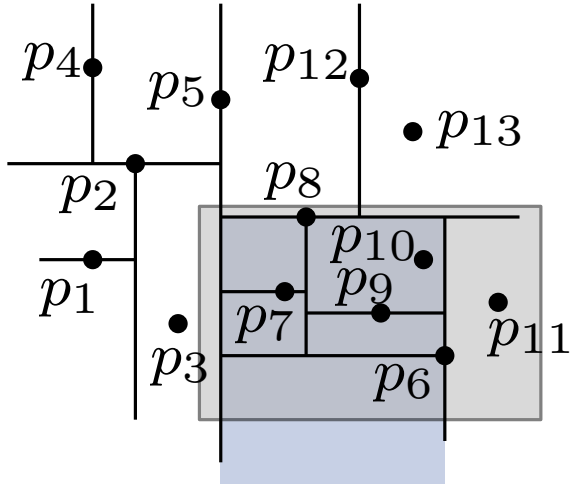
| ReportSubtree($\text{rc}(v)$)

else

if $\text{region}(\text{rc}(v)) \cap R \neq \emptyset$ **then**

| SearchKdTree($\text{rc}(v), R$)

Range Queries in a kd -Tree



SearchKdTree(v, R)

if v leaf **then**

 report point p in v when $p \in R$

else

if region($lc(v)$) $\subseteq R$ **then**

 ReportSubtree($lc(v)$)

else

if region($lc(v)$) $\cap R \neq \emptyset$ **then**

 SearchKdTree($lc(v), R$)

if region($rc(v)$) $\subseteq R$ **then**

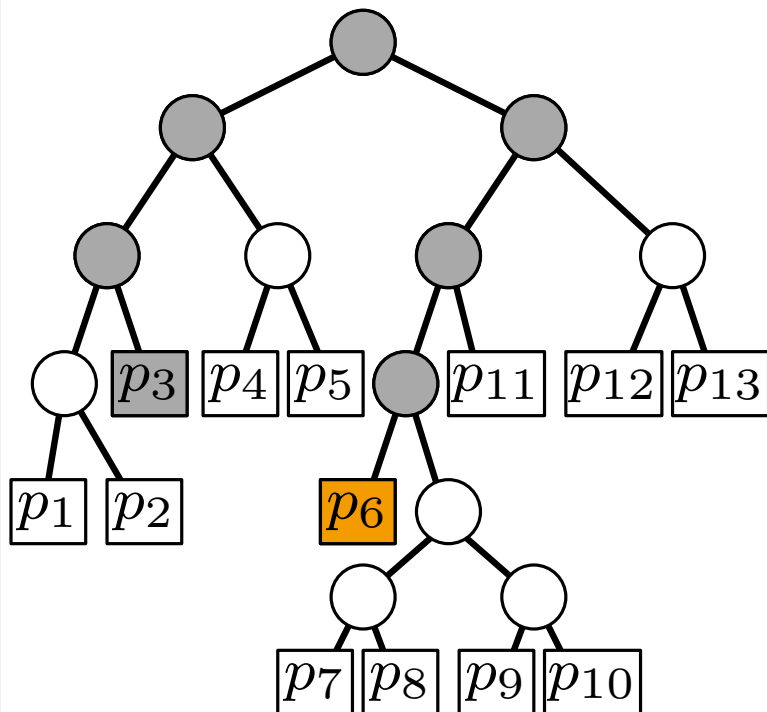
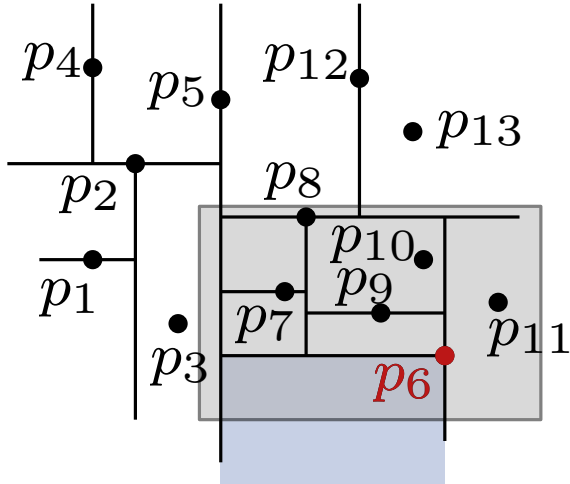
 ReportSubtree($rc(v)$)

else

if region($rc(v)$) $\cap R \neq \emptyset$ **then**

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Range Queries in a kd -Tree



SearchKdTree(v, R)

if v leaf **then**

 report point p in v when $p \in R$

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if region($lc(v)$) $\subseteq R$ **then**

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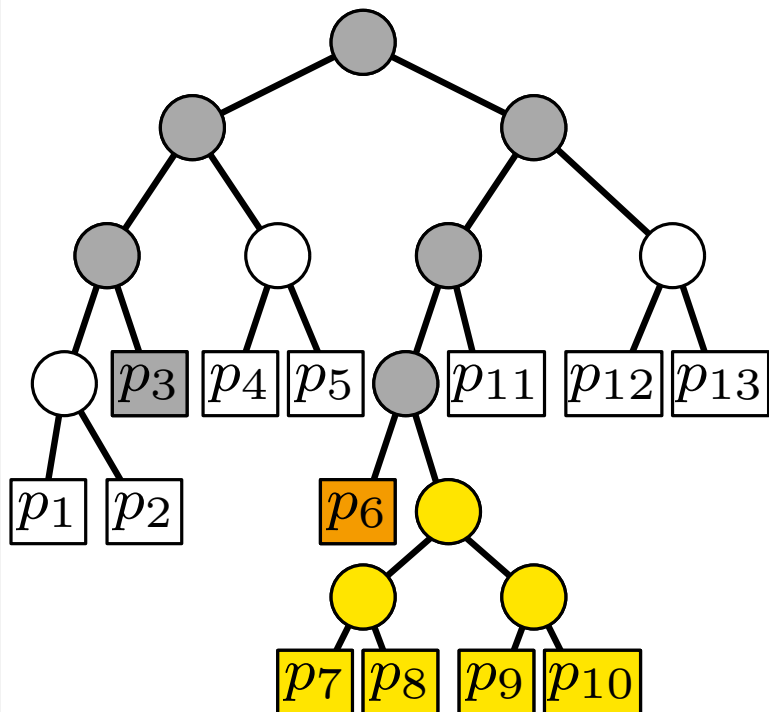
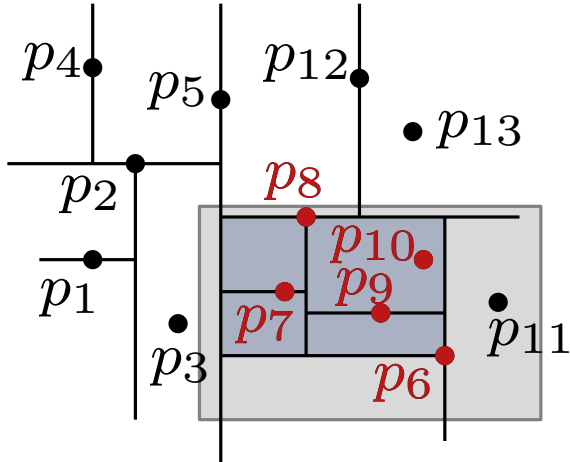
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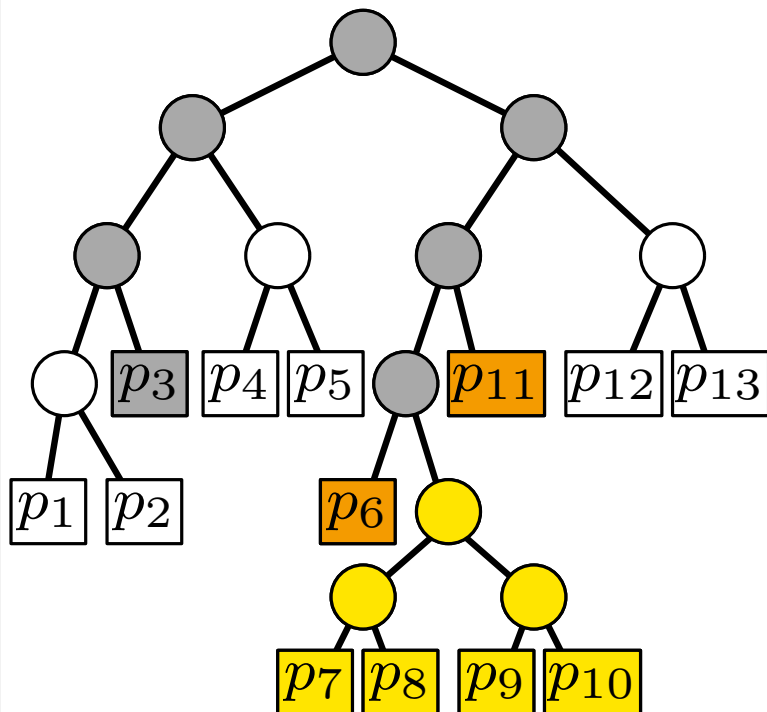
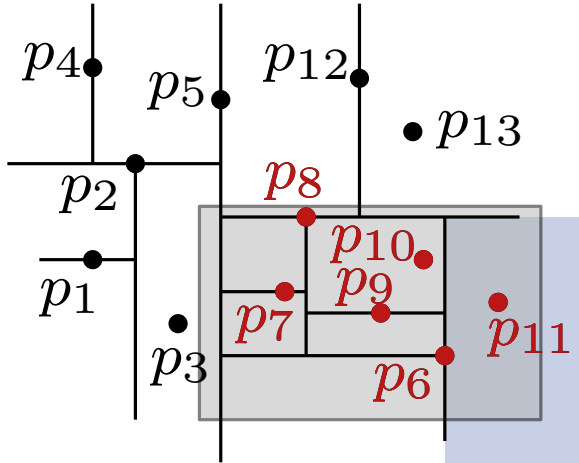
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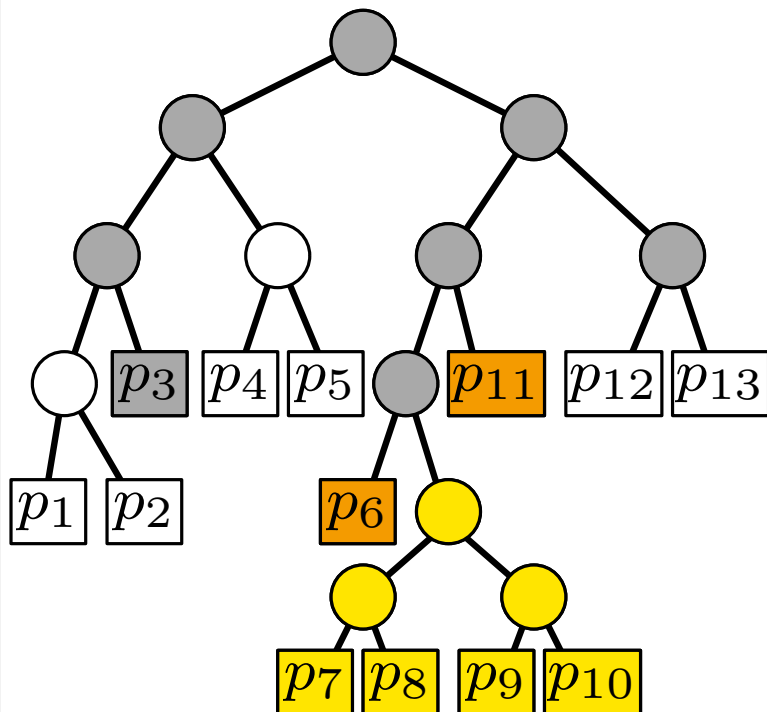
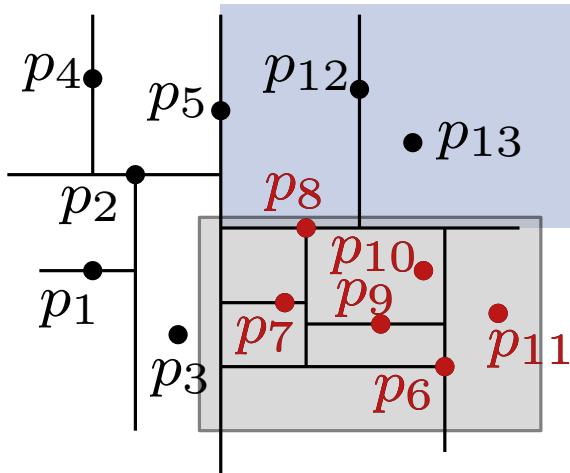
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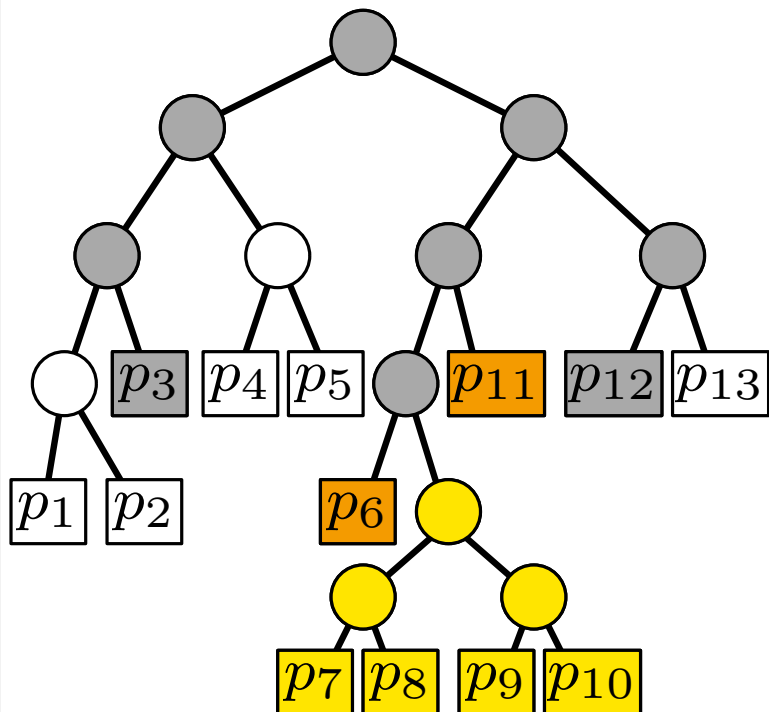
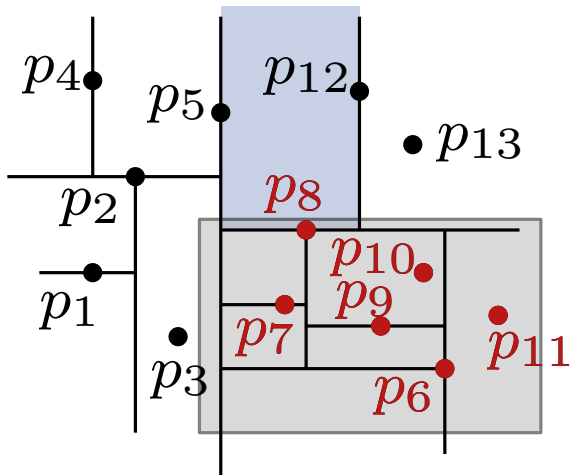
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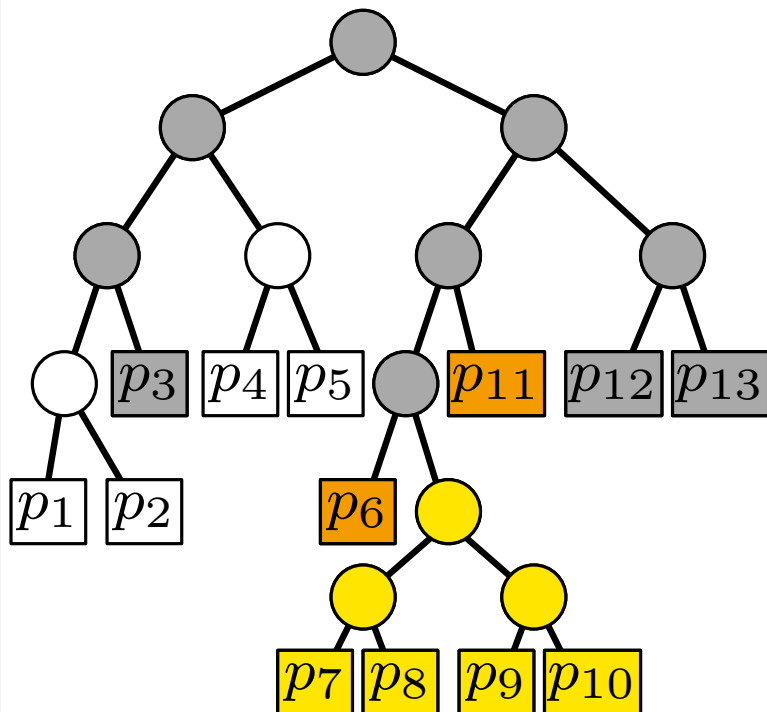
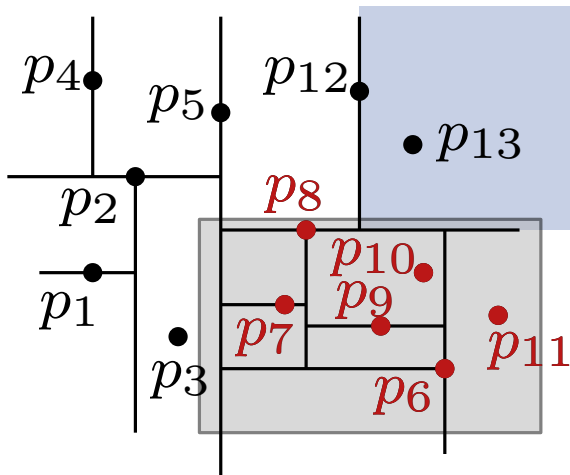
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Range Queries in a kd -Tree



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Exercise 1

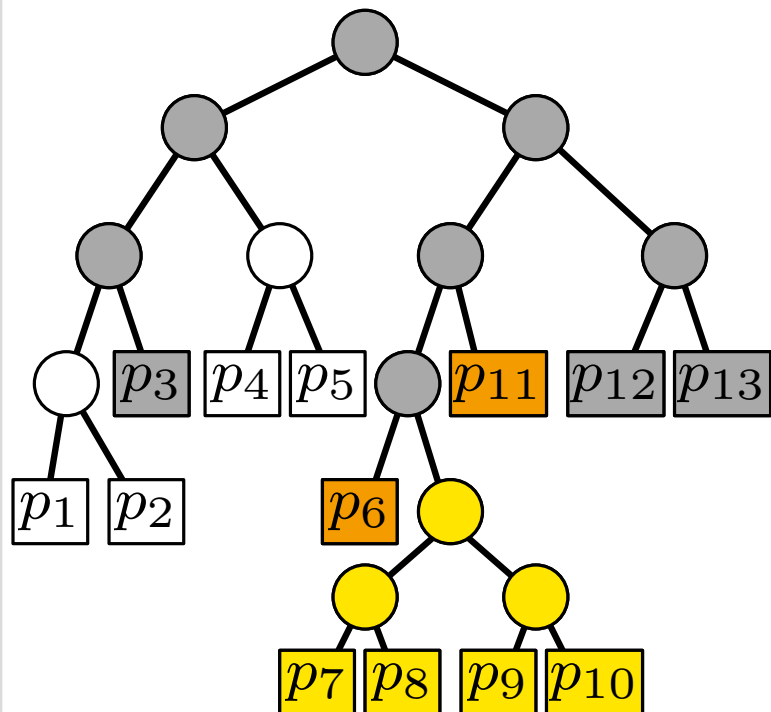
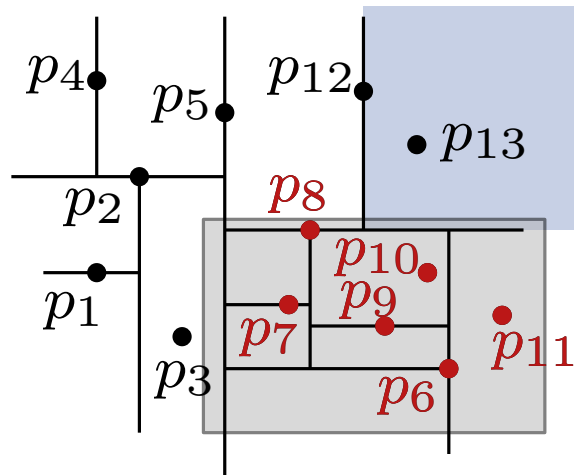
Claim: Queries in $O(\sqrt{n} + k)$ time

$Q(n)$ = Number of checked regions.

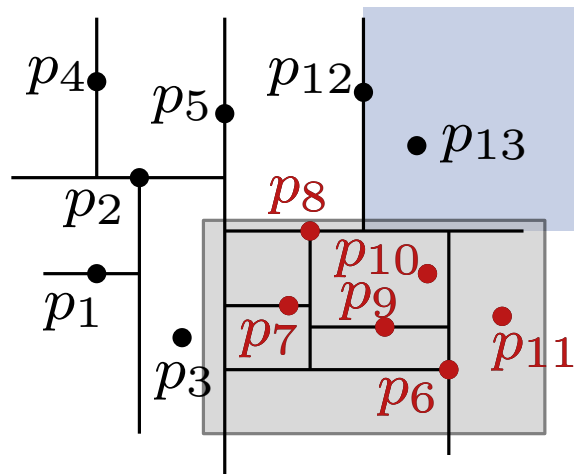
a) Show the following recurrence.

$$Q(n) = \begin{cases} \mathcal{O}(1) & , \text{ for } n = 1 \\ 2 + 2Q(n/4) & , \text{ for } n > 1 \end{cases}$$

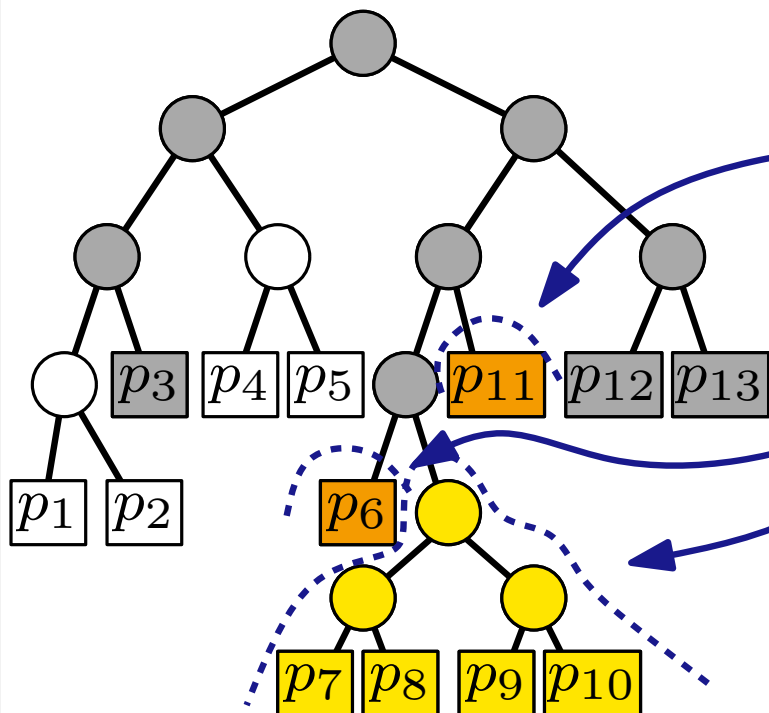
Range Queries in kd -Trees



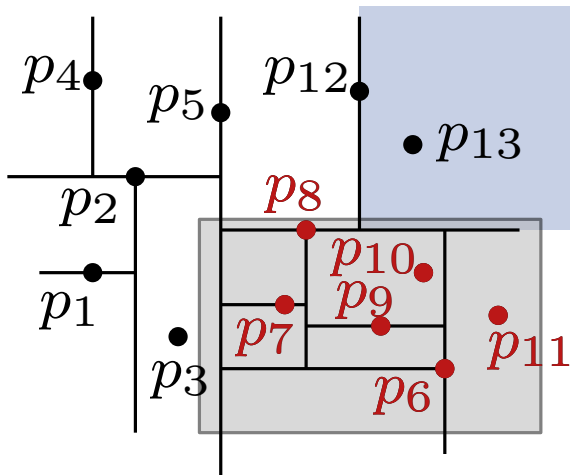
Range Queries in kd -Trees



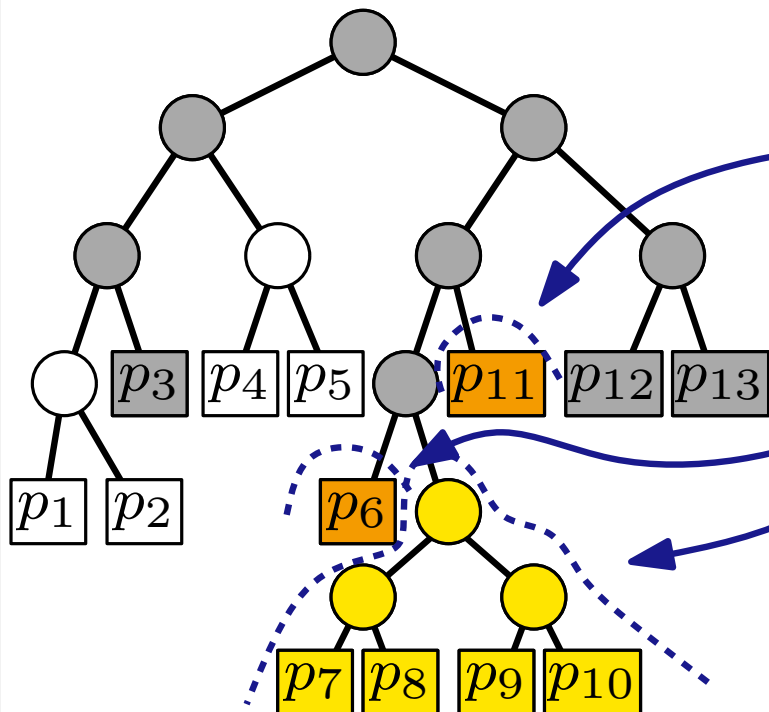
ReportSubtree in $\mathcal{O}(k)$



Range Queries in kd -Trees

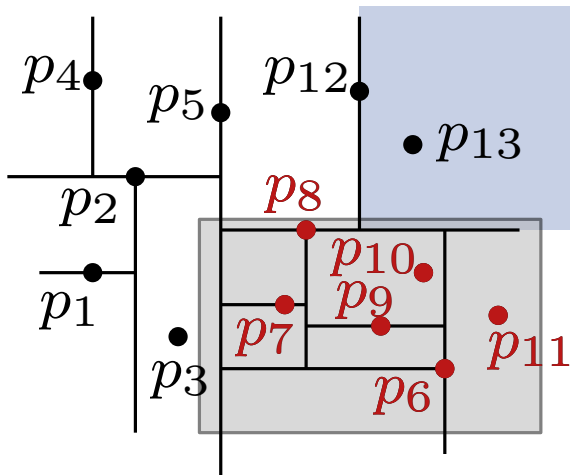


ReportSubtree in $\mathcal{O}(k)$

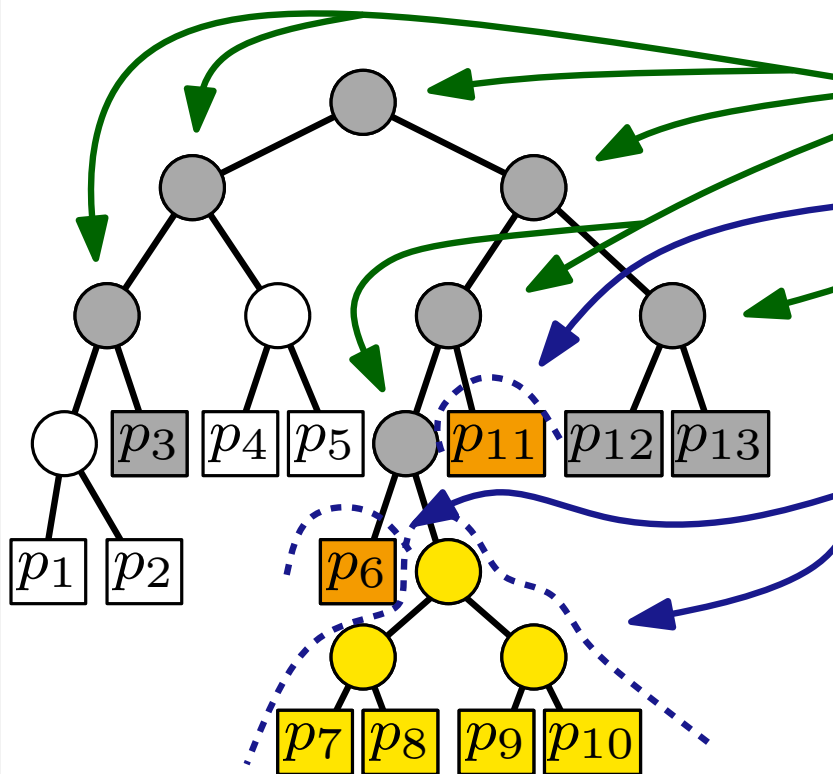


How many nodes do we consider?
Each node corresponds with one recursion step.

Range Queries in kd -Trees

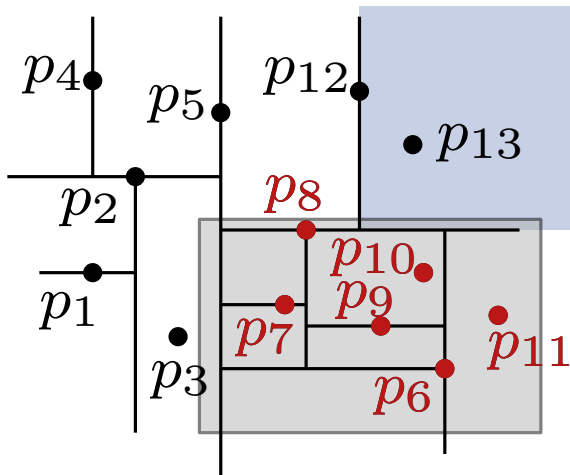


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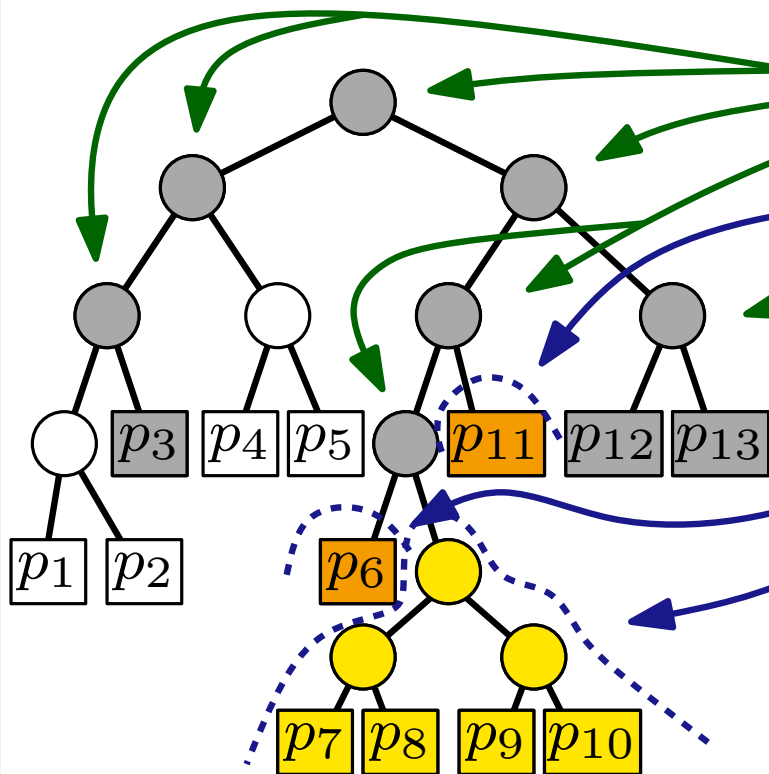


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Range Queries in kd -Trees



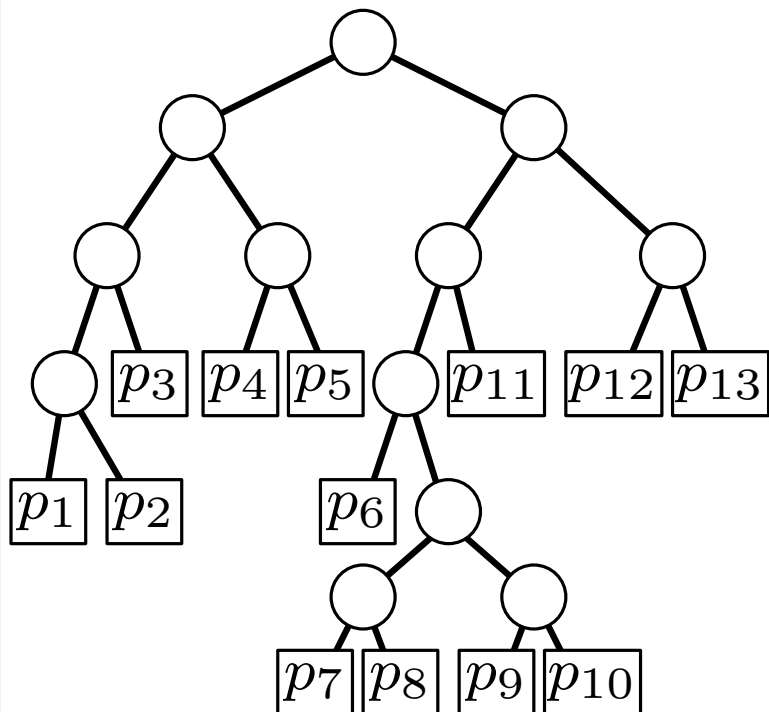
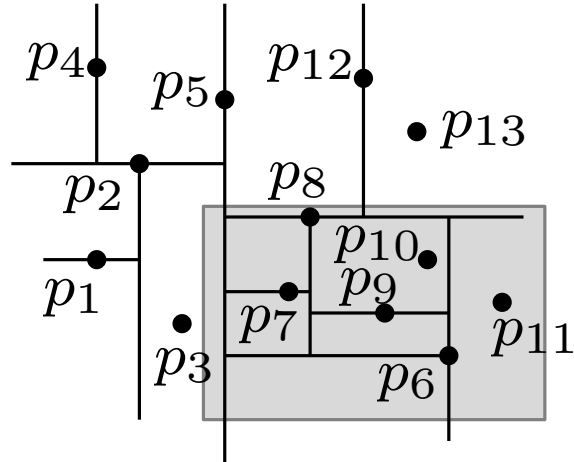
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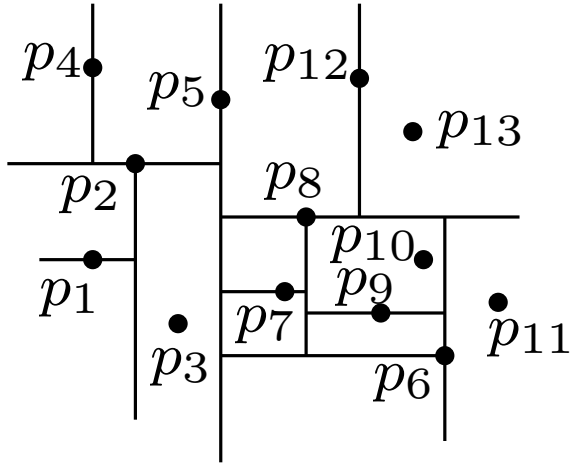
How many nodes do we consider?
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each node \triangleq intersected region

Range Queries in kd -Trees

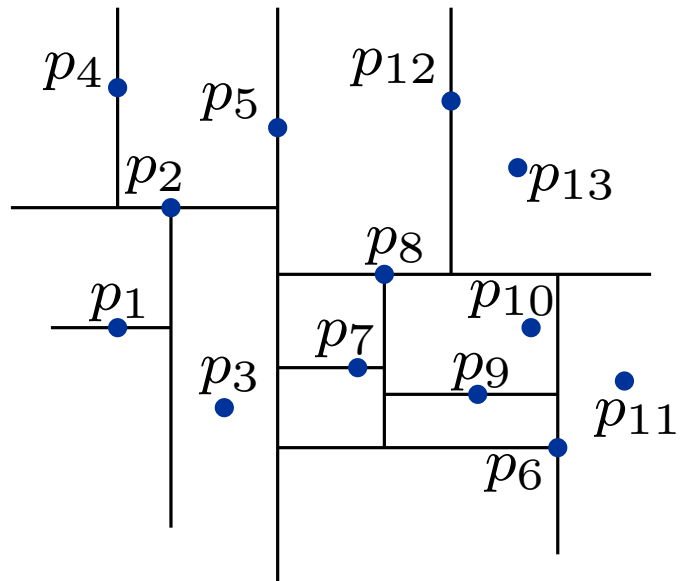


Range Queries in kd -Trees

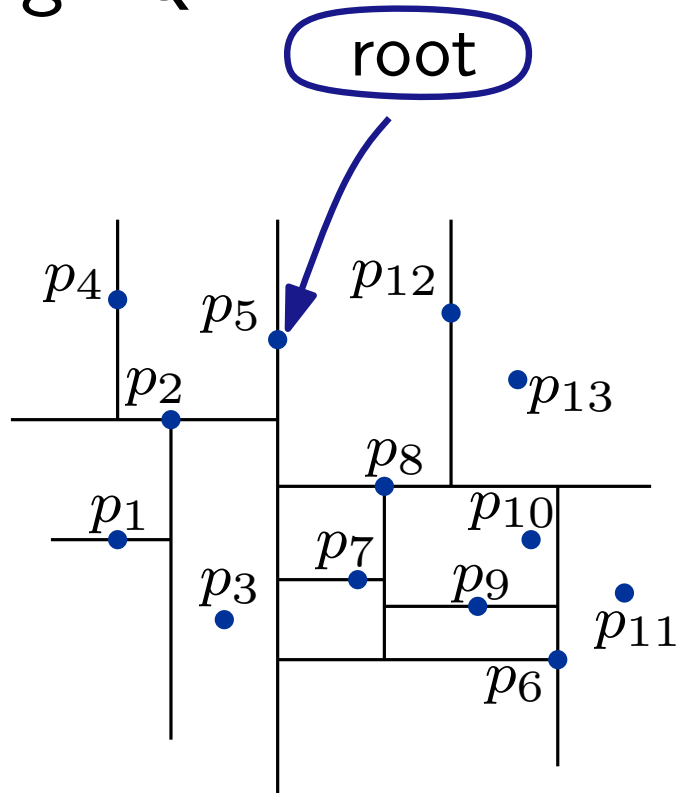


How many regions are intersected by a vertical line?

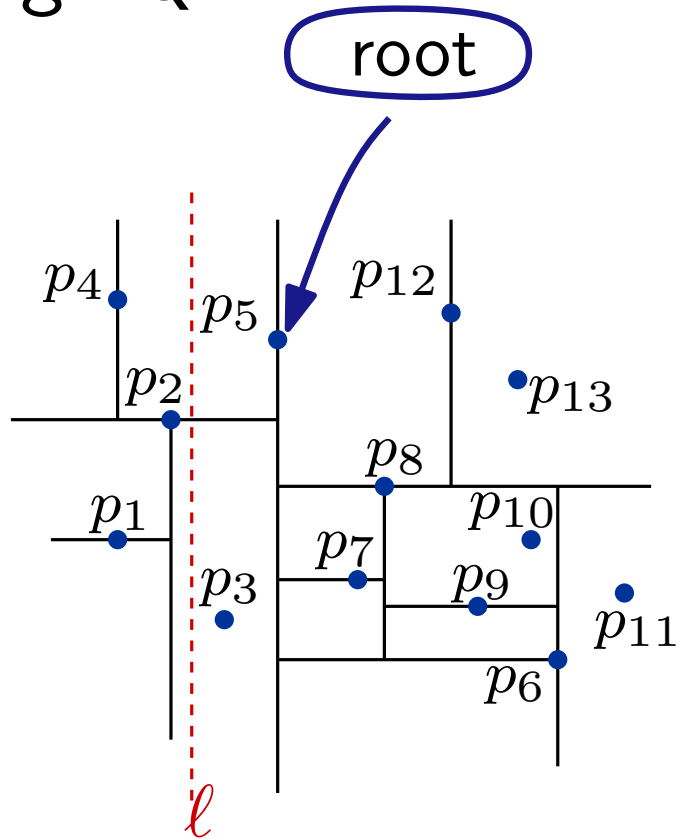
Range Queries in kd -Trees



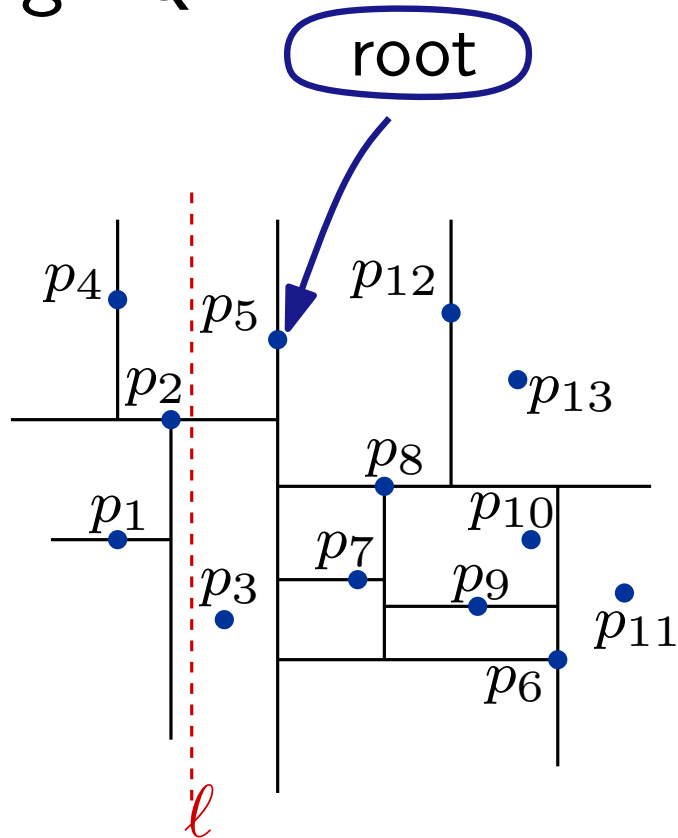
Range Queries in *kd*-Trees



Range Queries in kd -Trees



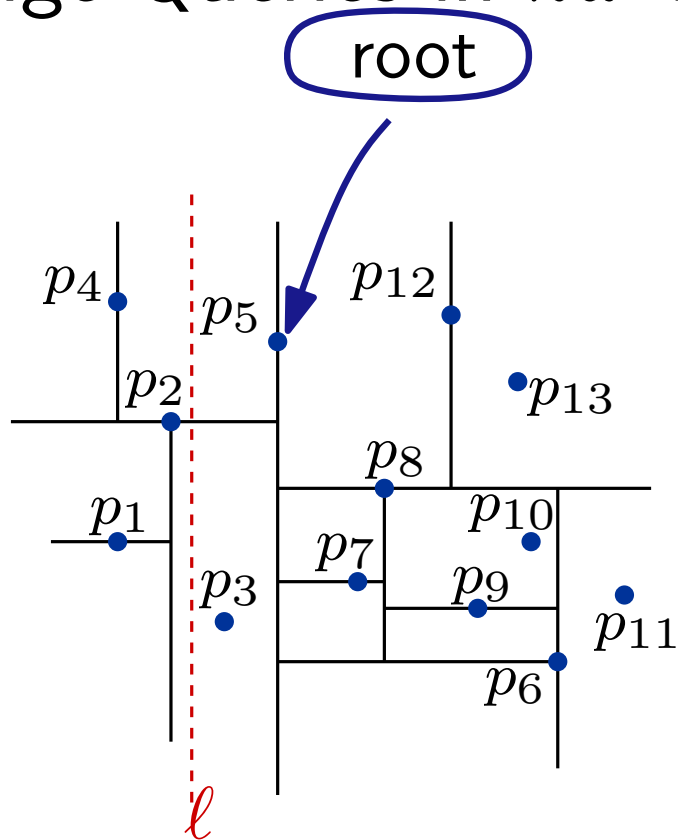
Range Queries in *kd*-Trees



Conjecture:

$$Q(n) = 1 + Q(n/2)$$

Range Queries in kd -Trees



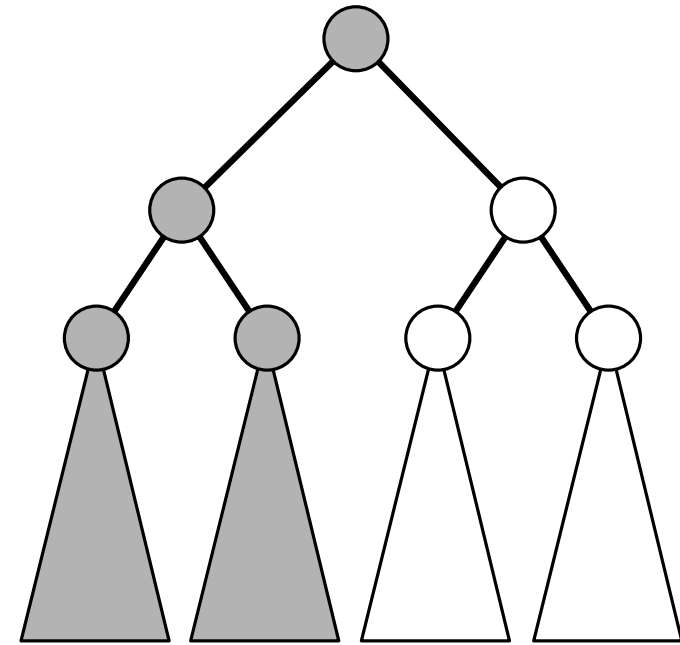
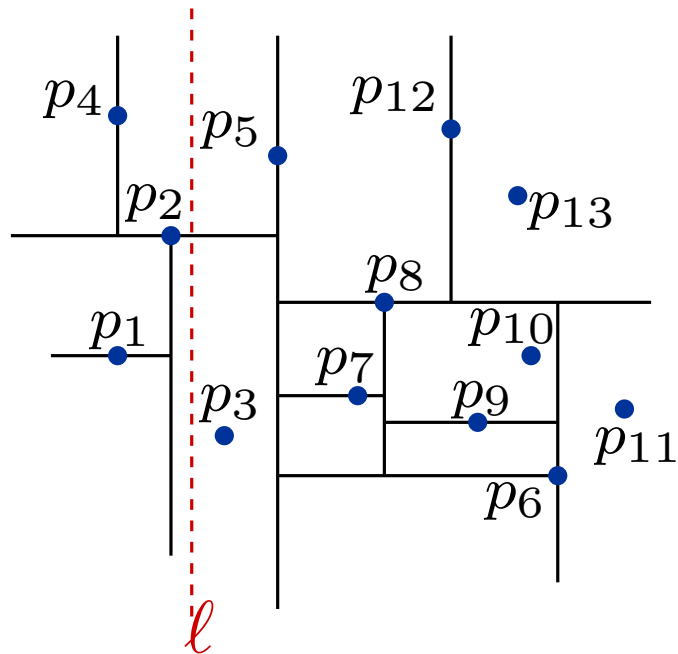
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Problem?

l intersects both children of left child of root

Range Queries in kd -Trees



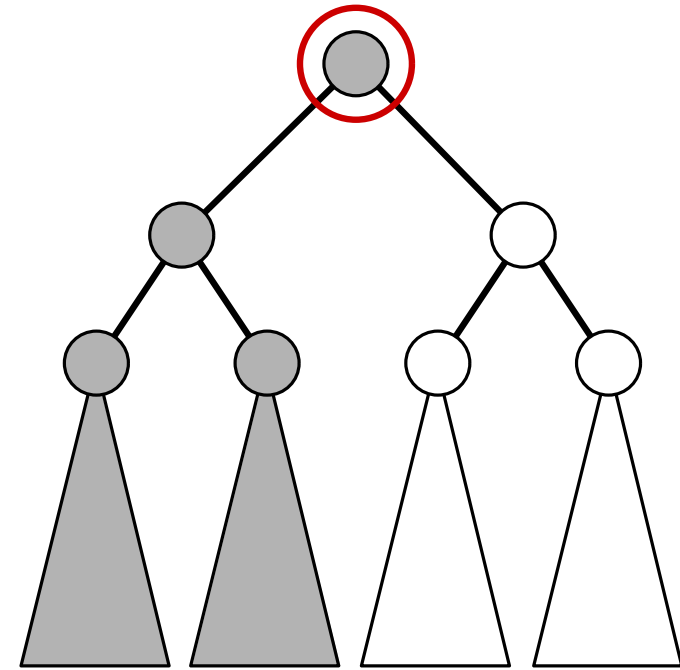
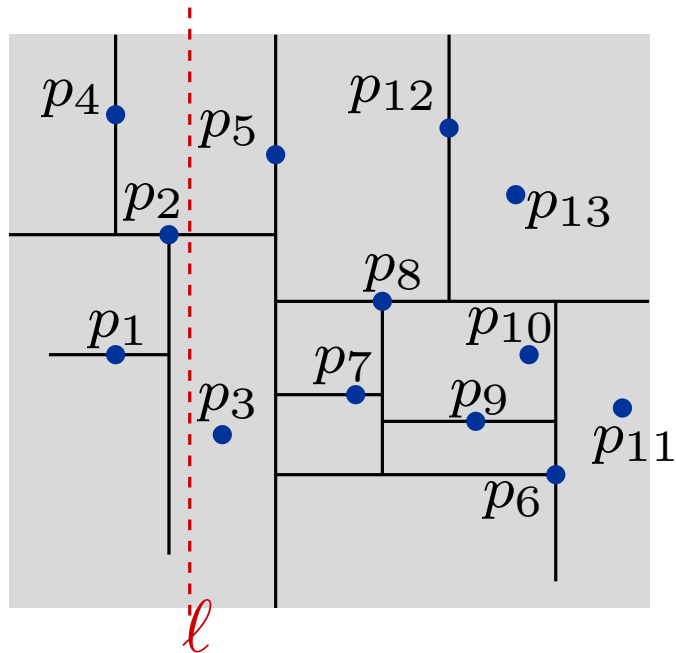
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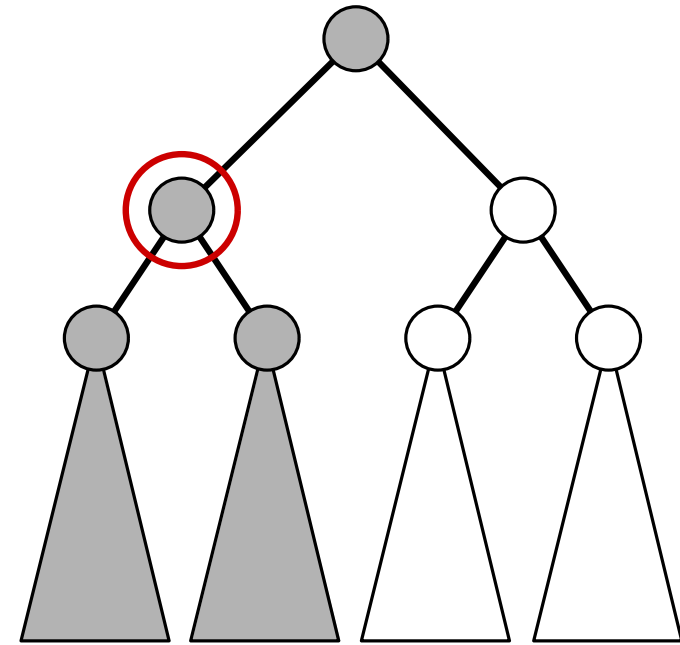
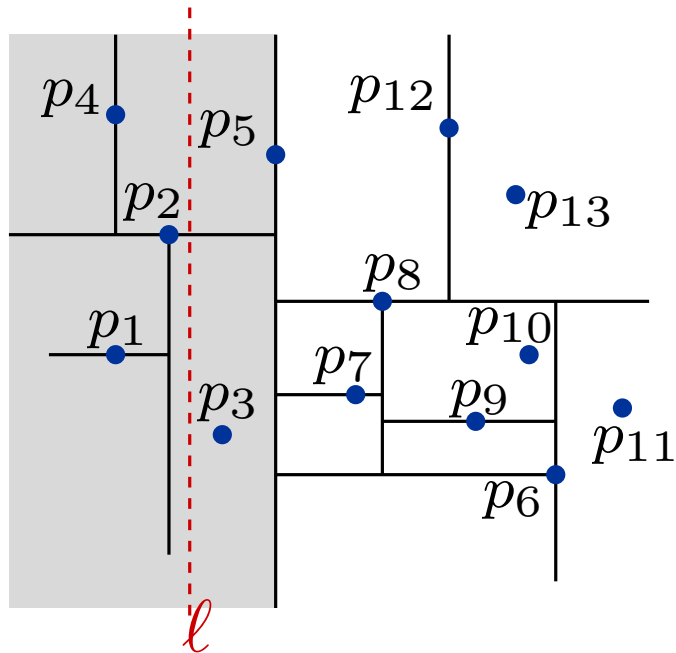
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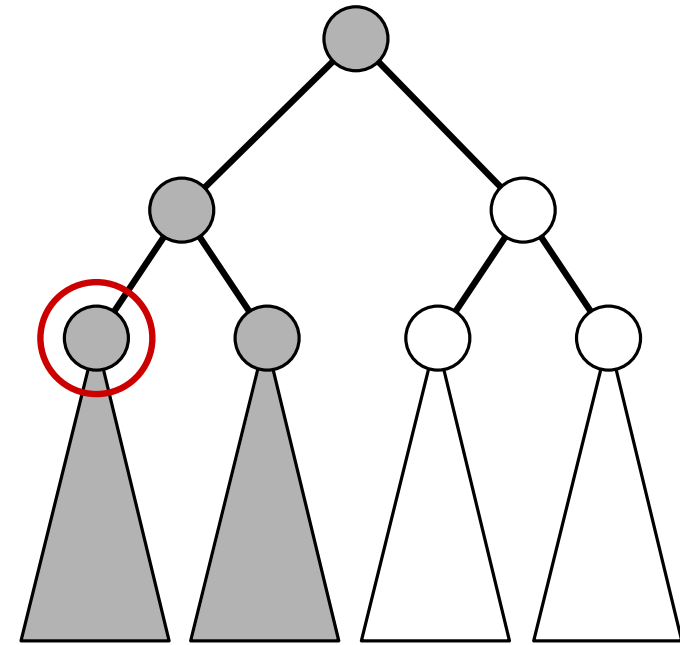
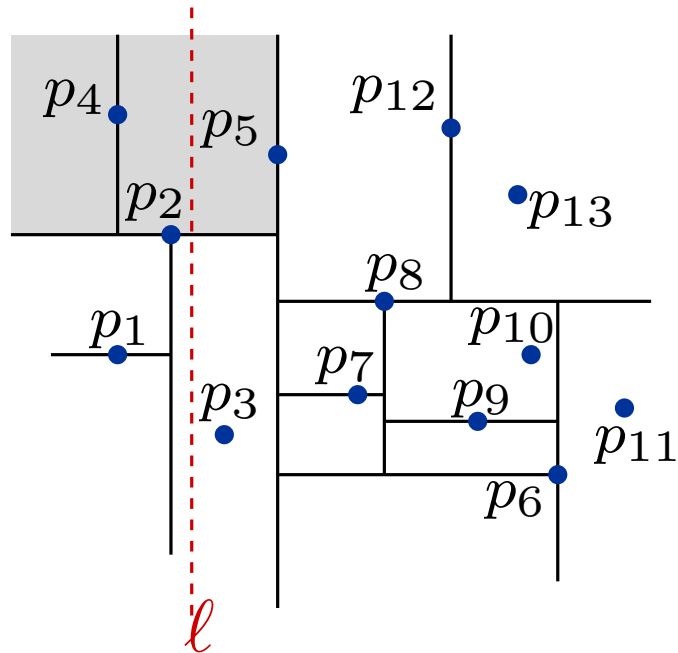
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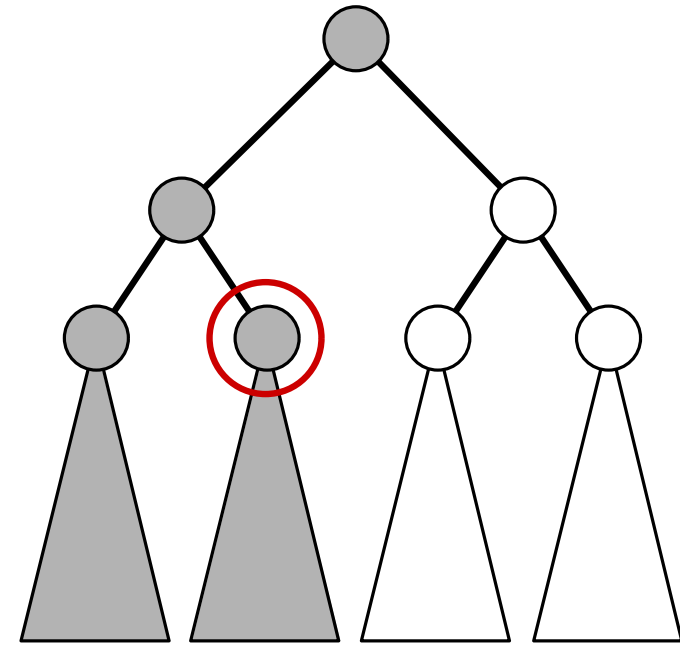
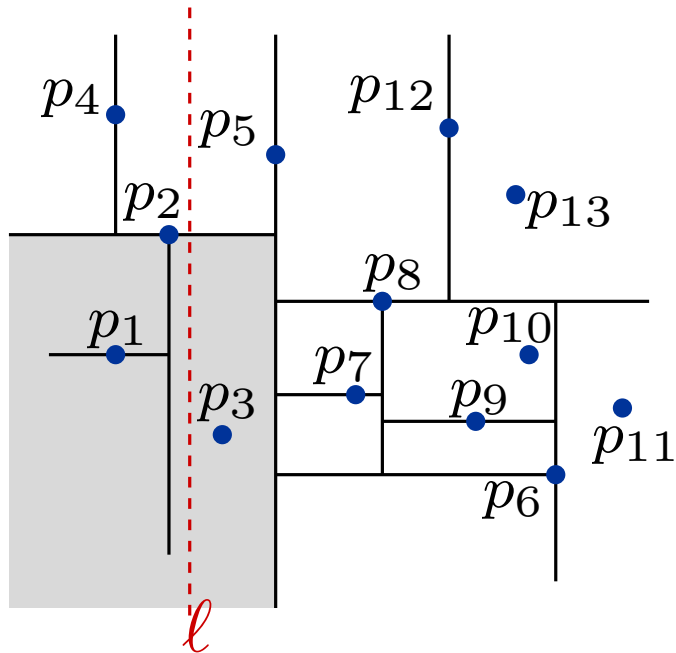
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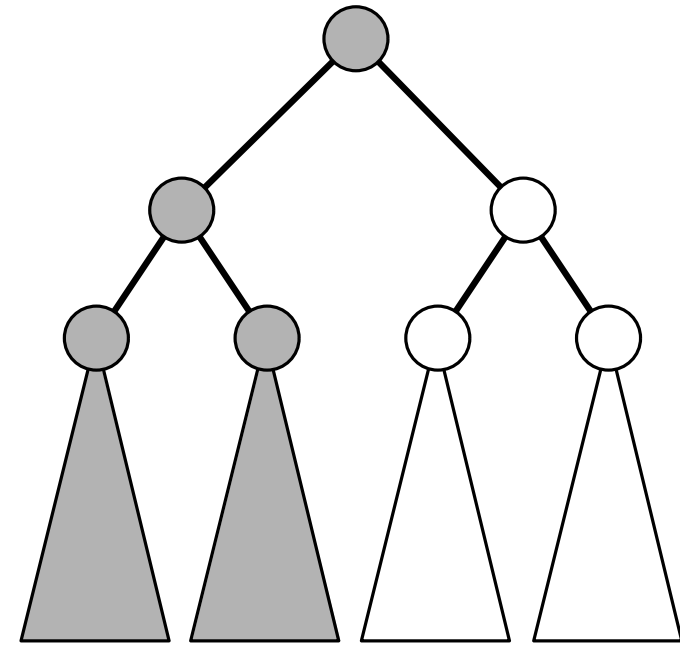
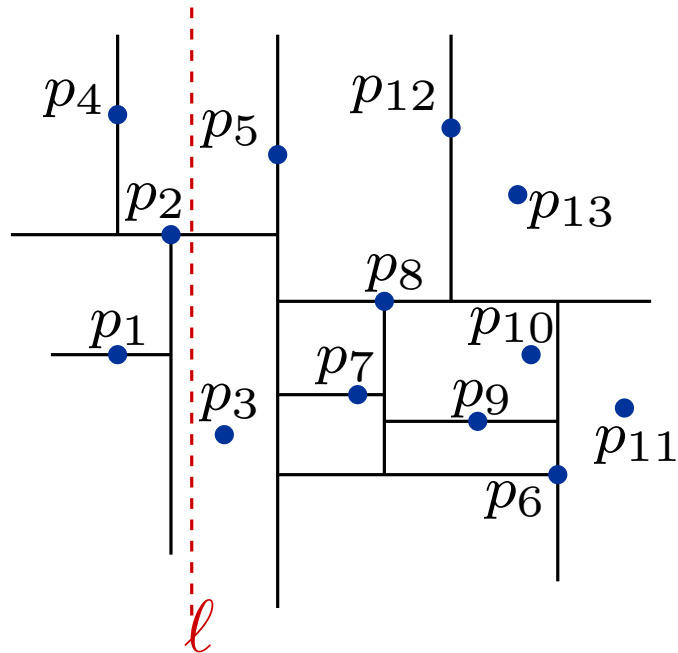
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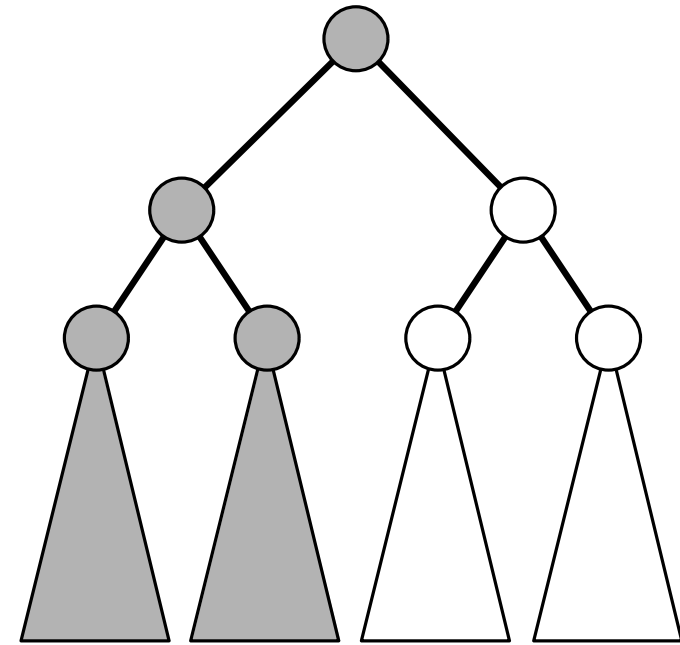
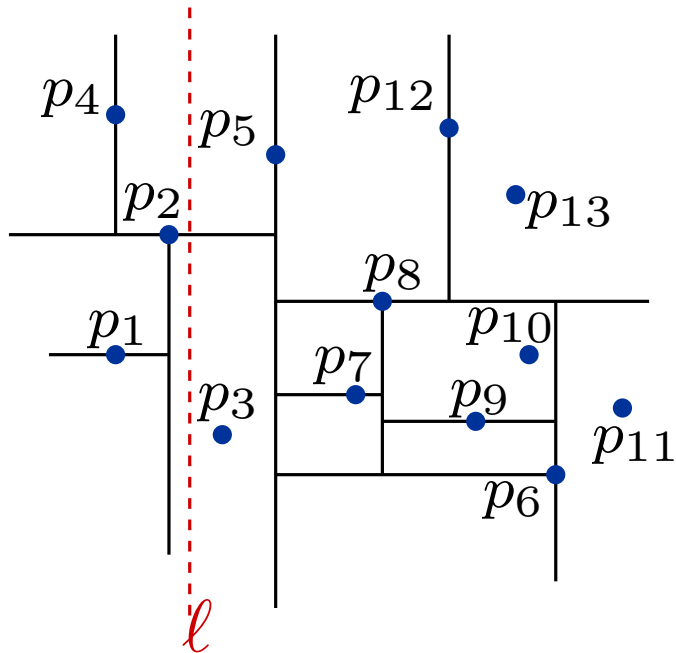
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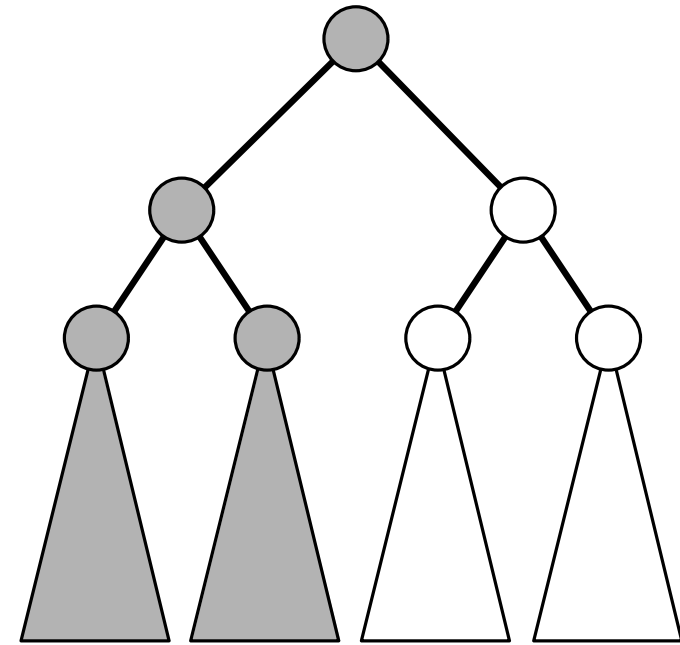
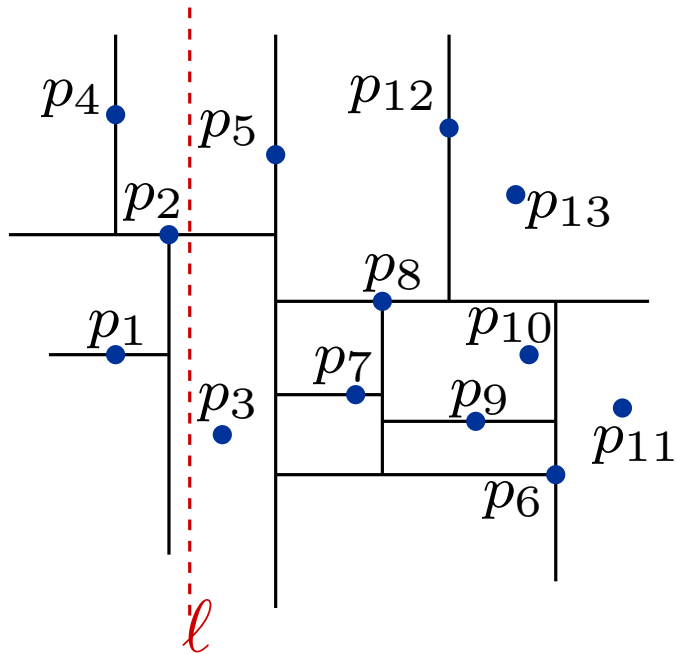
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Enforce same situation!

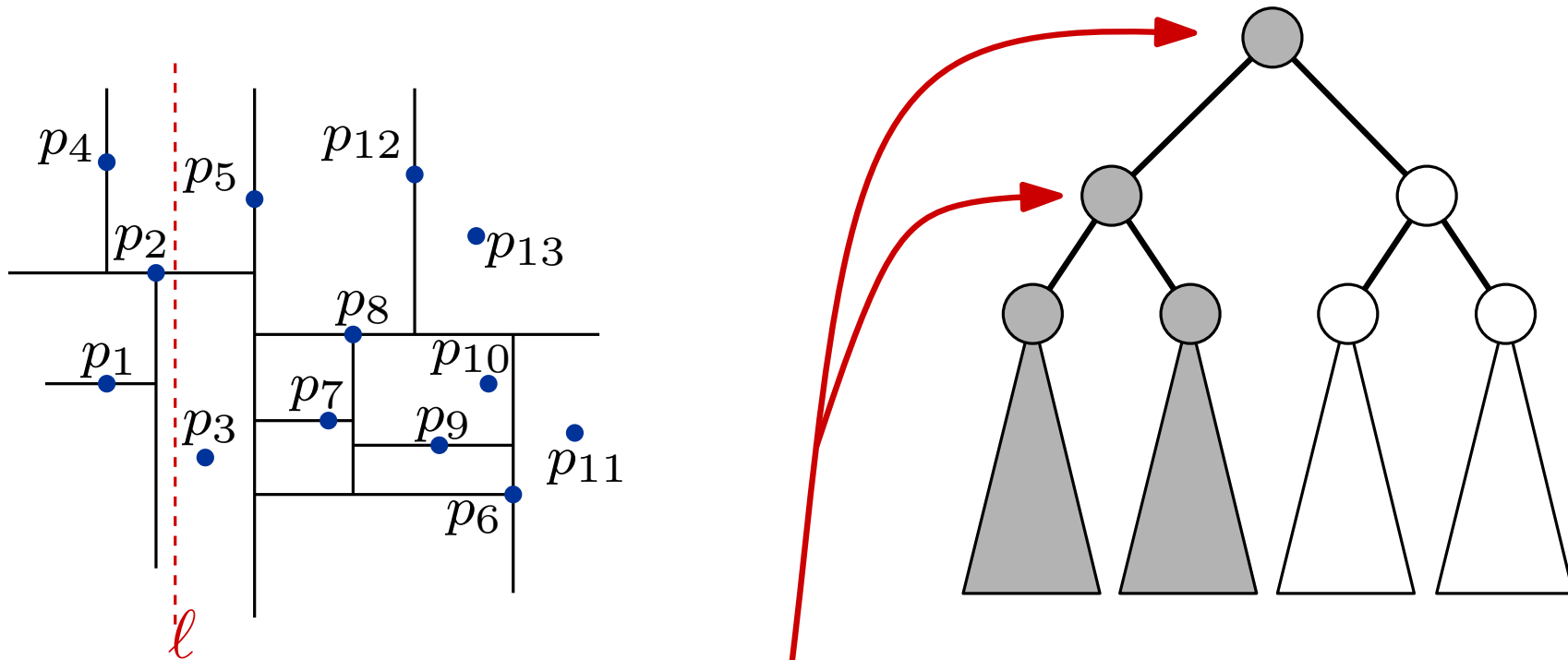
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$$Q(n) = \begin{cases} \mathcal{O}(1) & , \text{ for } n = 1 \\ 2 + 2Q(n/4) & , \text{ for } n > 1 \end{cases}$$

$Q(n)$ = number of intersected regions of a kd -tree whose root contains a vertical splitting line.

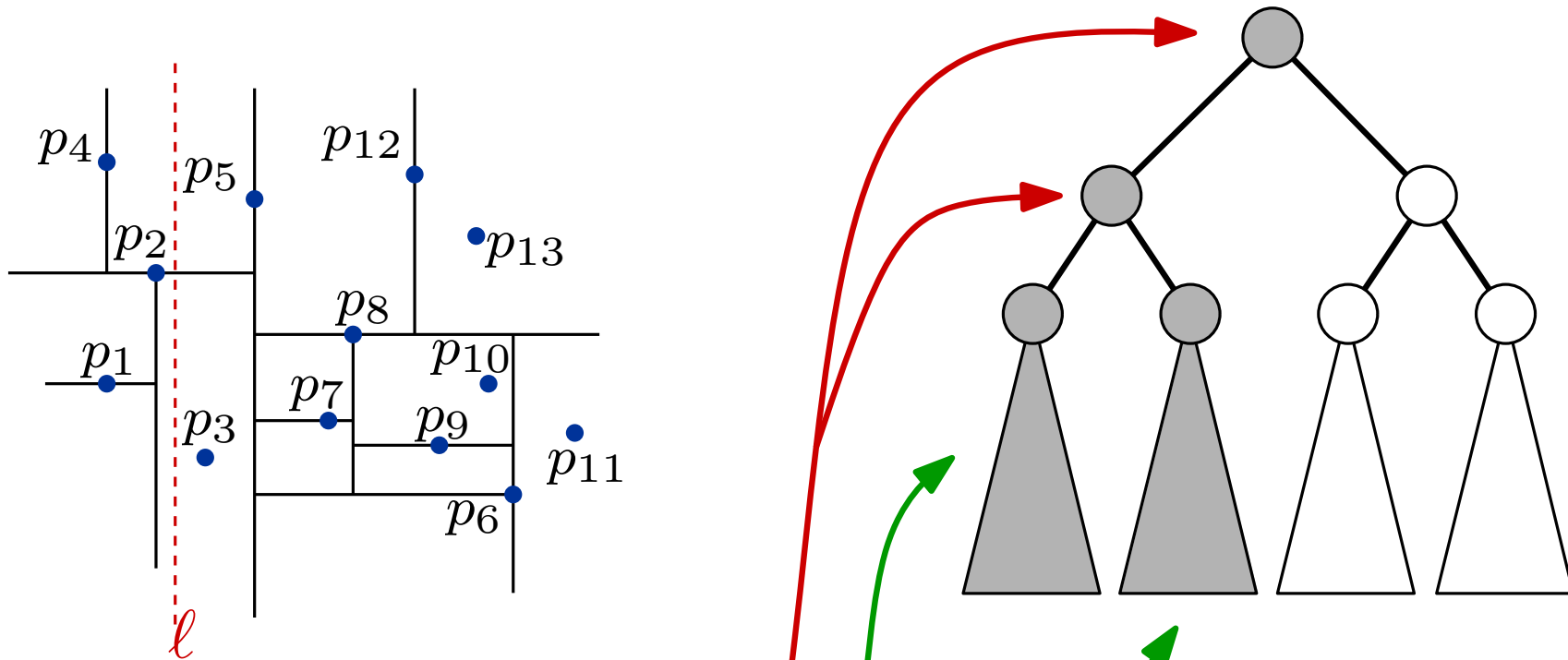
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Exercise 1

Claim: Queries in $O(\sqrt{n} + k)$ time

$Q(n)$ = Number of checked regions.

a) Show the following recurrence.

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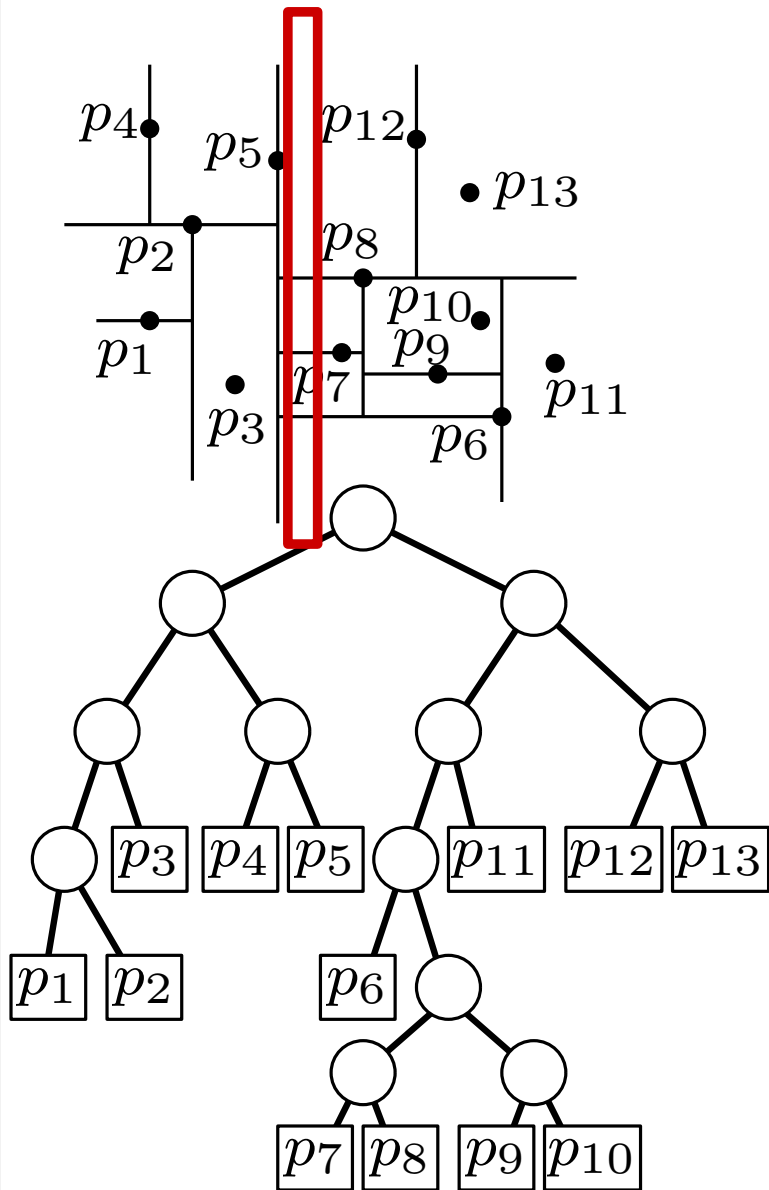
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c) $\Omega(\sqrt{n})$ lower bound for range queries in kd -trees



SearchKdTree(v, R)

if v leaf **then**

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else

if region($lc(v)$) $\subseteq R$ **then**

| ReportSubtree($lc(v)$)

else

if region($lc(v)$) $\cap R \neq \emptyset$ **then**

| SearchKdTree($lc(v), R$)

if region($rc(v)$) $\subseteq R$ **then**

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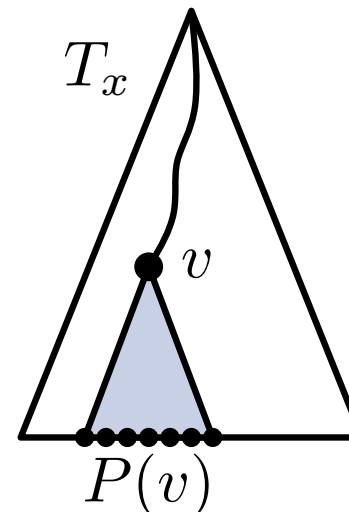
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Range Trees

Idea: Use 1-dimensional search trees on two levels:

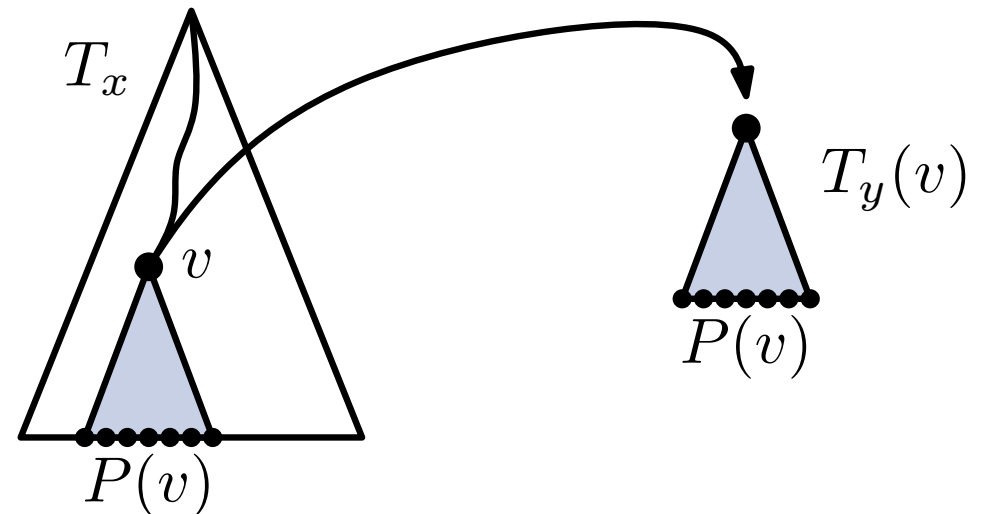
- a 1d search tree T_x on x -coordinates



Range Trees

Idea: Use 1-dimensional search trees on two levels:

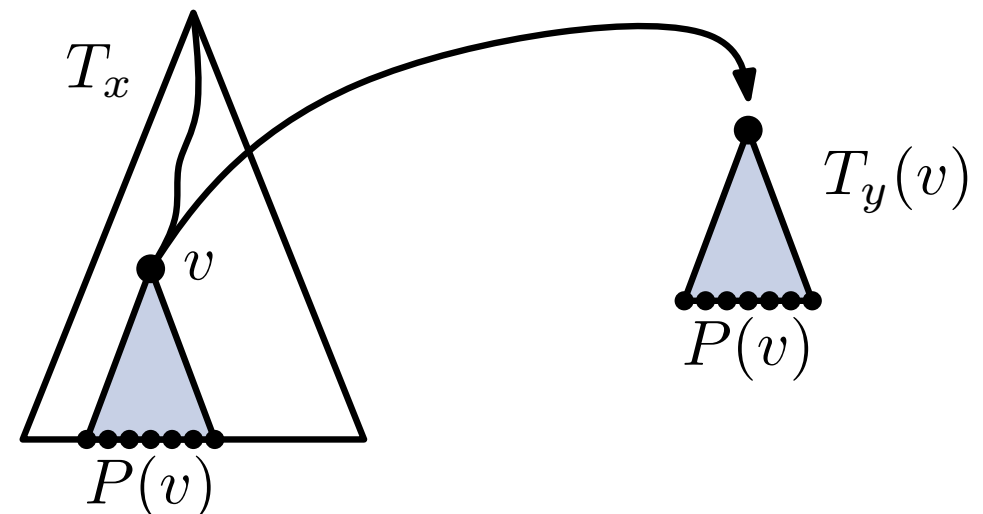
- a 1d search tree T_x on x -coordinates
- in each node v of T_x a 1d search tree $T_y(v)$ stores the canonical subset $P(v)$ on y -coordinates



Range Trees

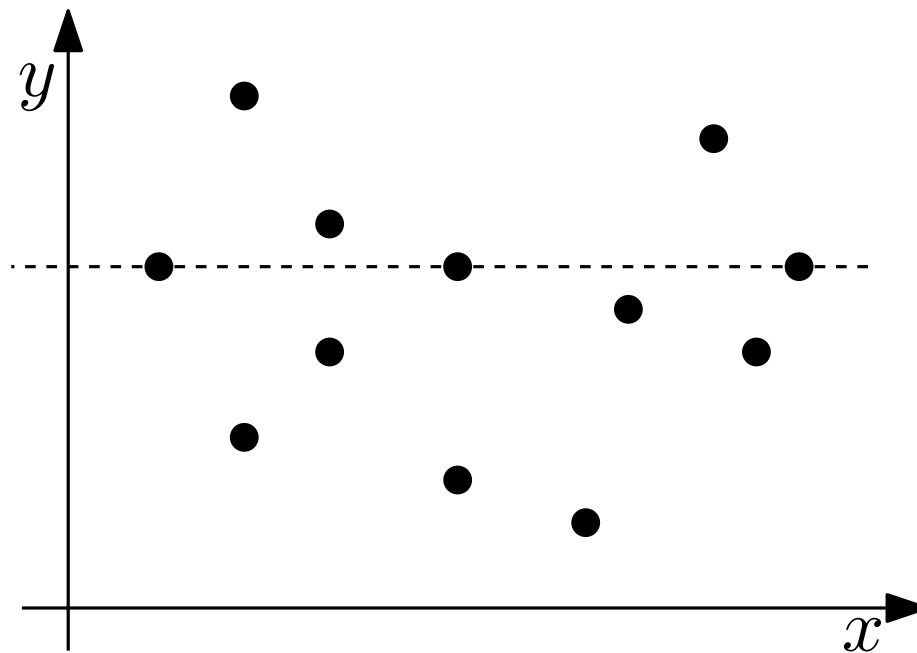
Idea: Use 1-dimensional search trees on two levels:

- a 1d search tree T_x on x -coordinates
- in each node v of T_x a 1d search tree $T_y(v)$ stores the canonical subset $P(v)$ on y -coordinates
- Compute the points by x -query in T_x and subsequent y -queries in the auxiliary structures T_y for the subtrees in T_x



Exercise 2

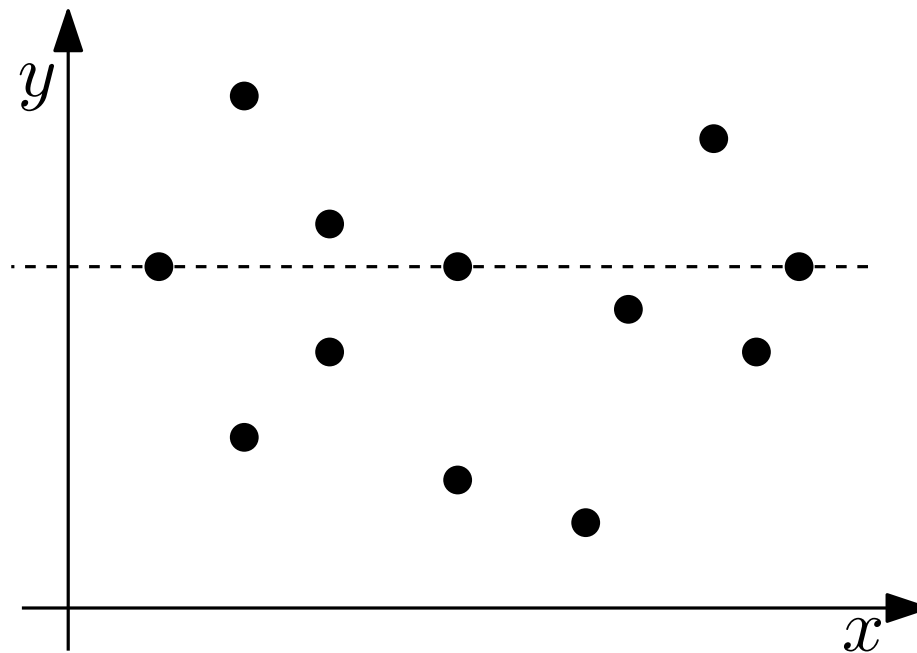
'partial match queries'



Report all points with $y = 7$.

Exercise 2

'partial match queries'

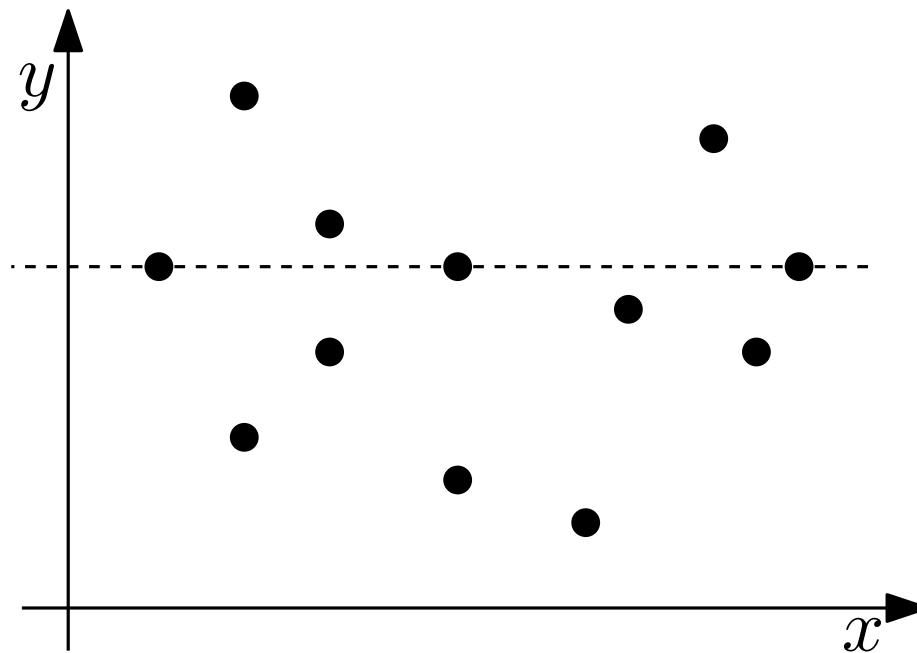


Report all points with $y = 7$.

a) How to apply kd -trees?

Exercise 2

'partial match queries'

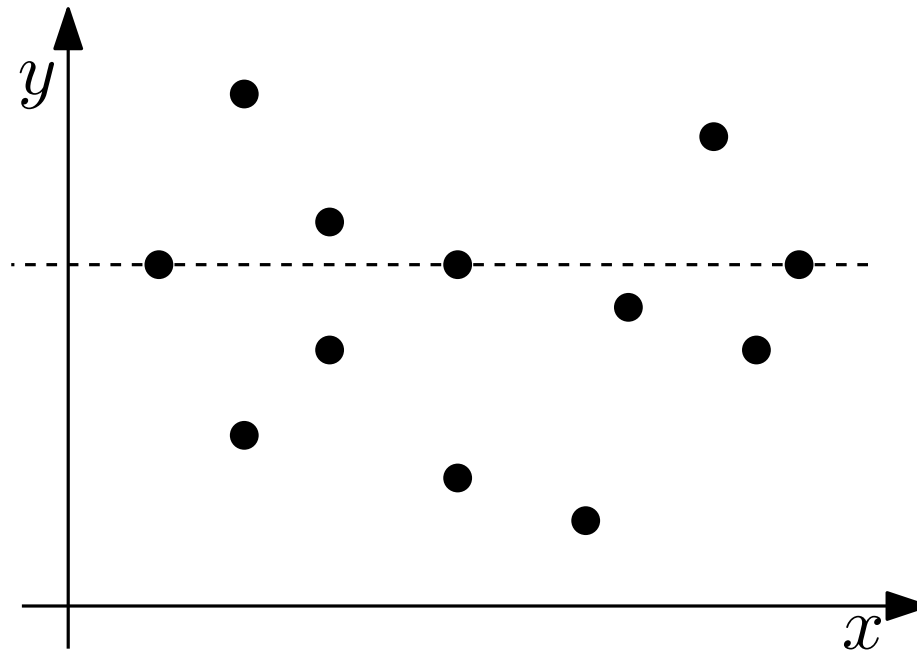


Report all points with $y = 7$.

b) How to apply range-trees?

Exercise 2

'partial match queries'

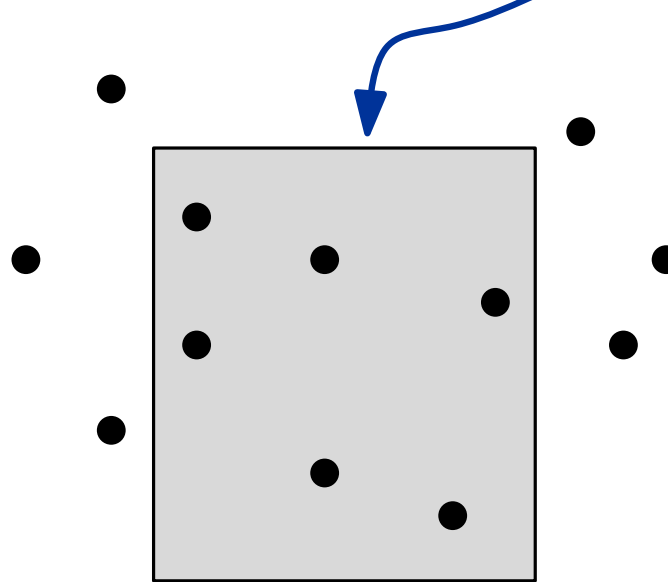


Report all points with $y = 7$.

c) Find: Datatstructure that solves problem in $\mathcal{O}(\log n + k)$ time and $\mathcal{O}(n)$ storage.

Exercise 3

How many points lie in that **rectangle**?

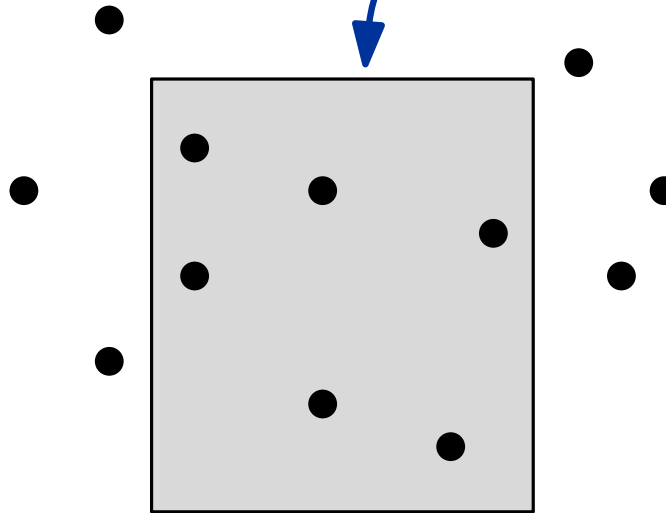


range counting query

Requirement: Without additive constant $\mathcal{O}(k)$ in running time.

Exercise 3

How many points lie in that **rectangle**?



range counting query

Requirement: Without additive constant $\mathcal{O}(k)$ in running time.

a) Adapt 1-dim range-tree for range counting queries in $\mathcal{O}(\log n)$.

Exercise 3

1dRangeQuery(T, x, x')

$v_{\text{split}} \leftarrow \text{FindSplitNode}(T, x, x')$
if v_{split} ist Blatt **then** prüfe v_{split}

else

$v \leftarrow \text{lc}(v_{\text{split}})$

while v kein Blatt **do**

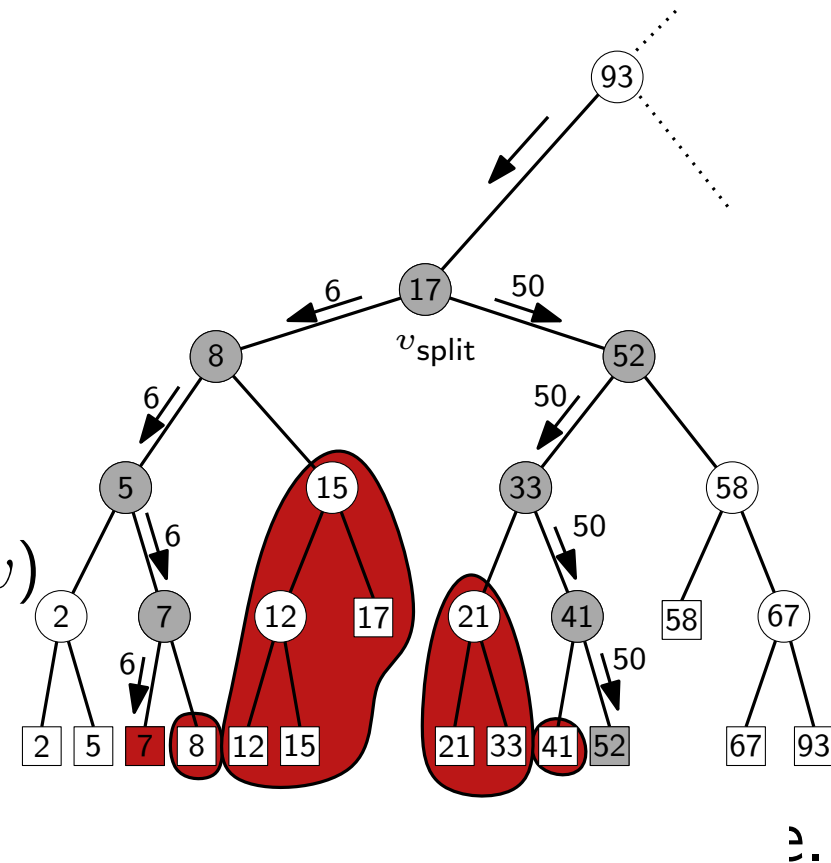
if $x \leq x_v$ **then**

 | ReportSubtree($\text{rc}(v)$); $v \leftarrow \text{lc}(v)$

else $v \leftarrow \text{rc}(v)$

 prüfe v

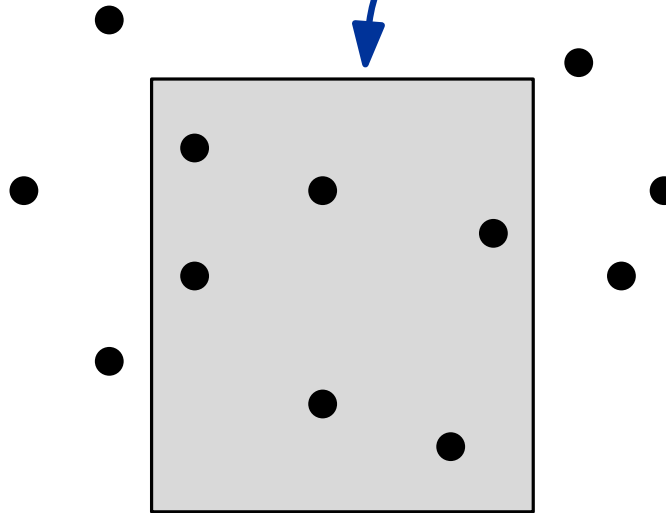
 // analog für x' und $\text{rc}(v_{\text{split}})$



a) Adapt 1-dim range-tree for range counting queries in $\mathcal{O}(\log n)$.

Exercise 3

How many points lie in that **rectangle**?

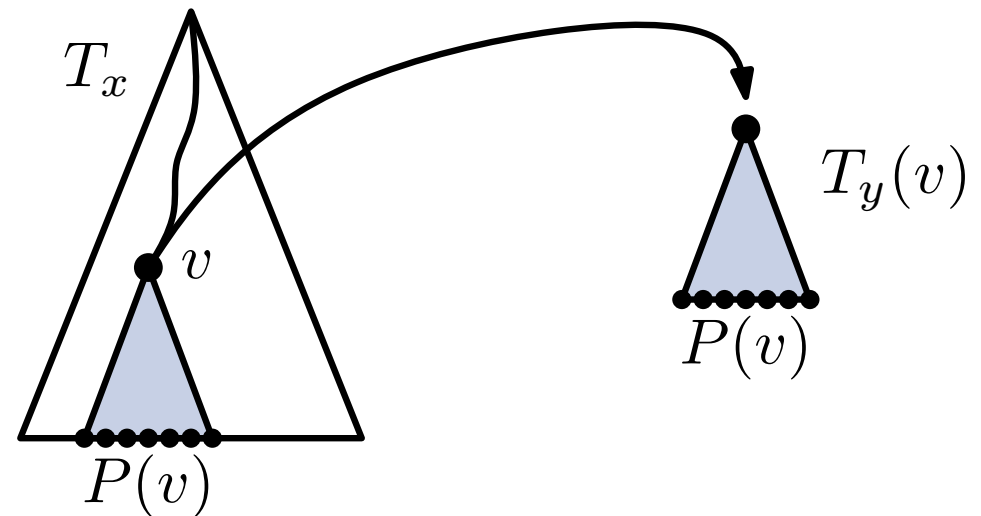


range counting query

Requirement: Without additive constant $\mathcal{O}(k)$ in running time.

b) How to solve the d -dimensional problem.

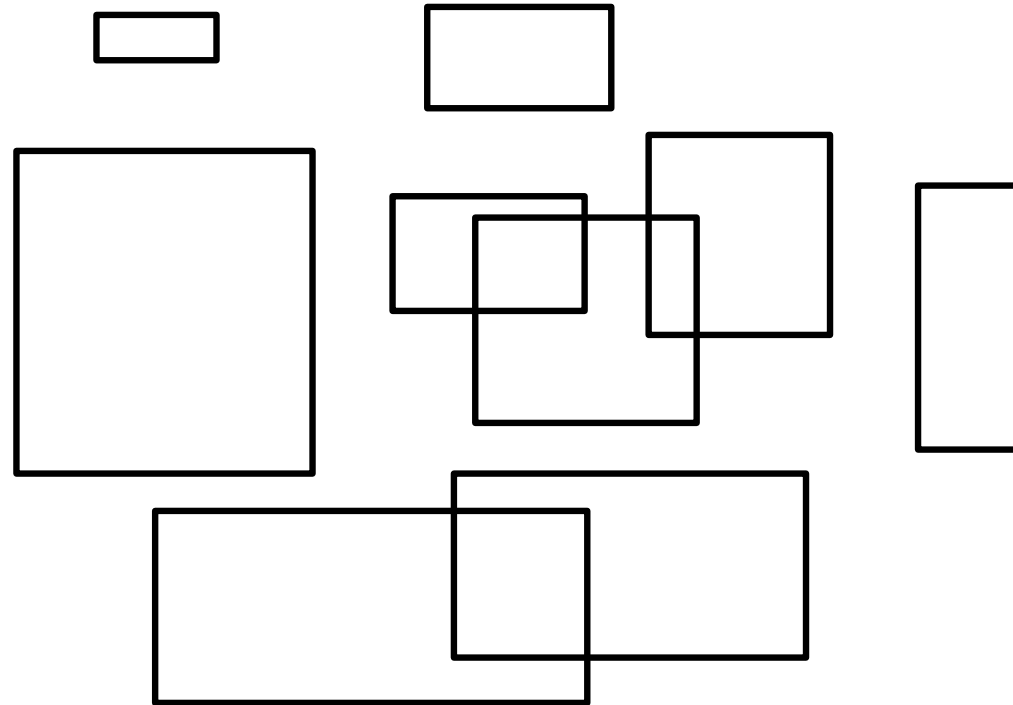
2dim Range-Trees:



Requirement: Without additive constant $\mathcal{O}(k)$ in running time.

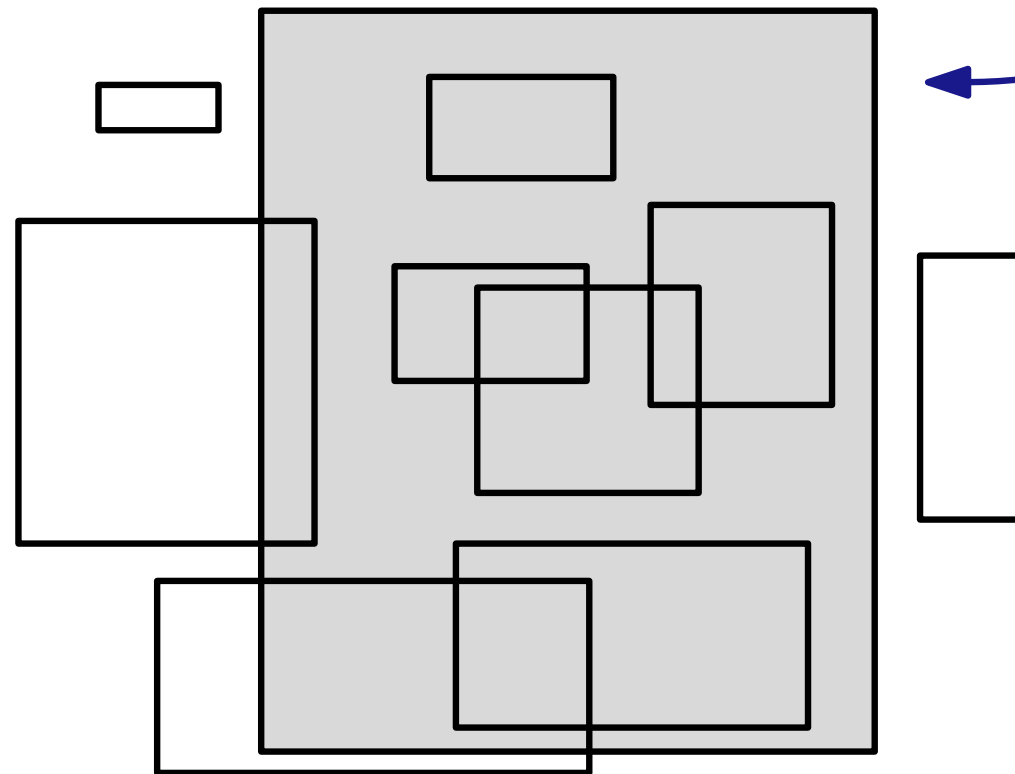
b) How to solve the d -dimensional problem.

Exercise 4



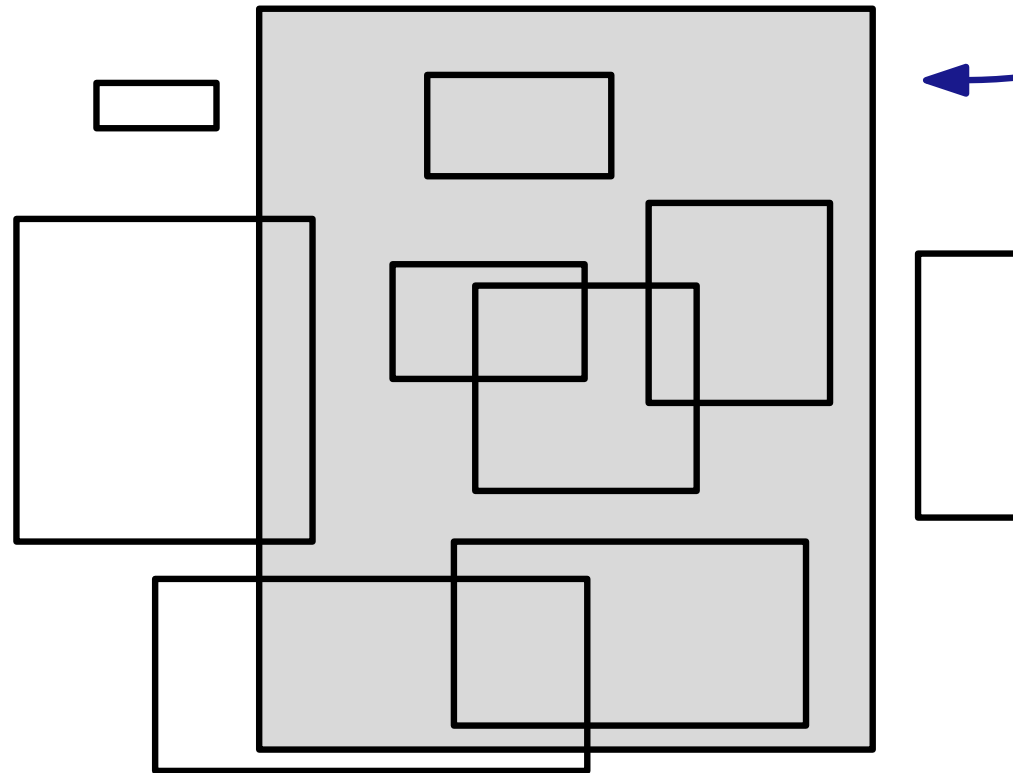
Exercise 4

Which rectangles completely lie in this rectangle?



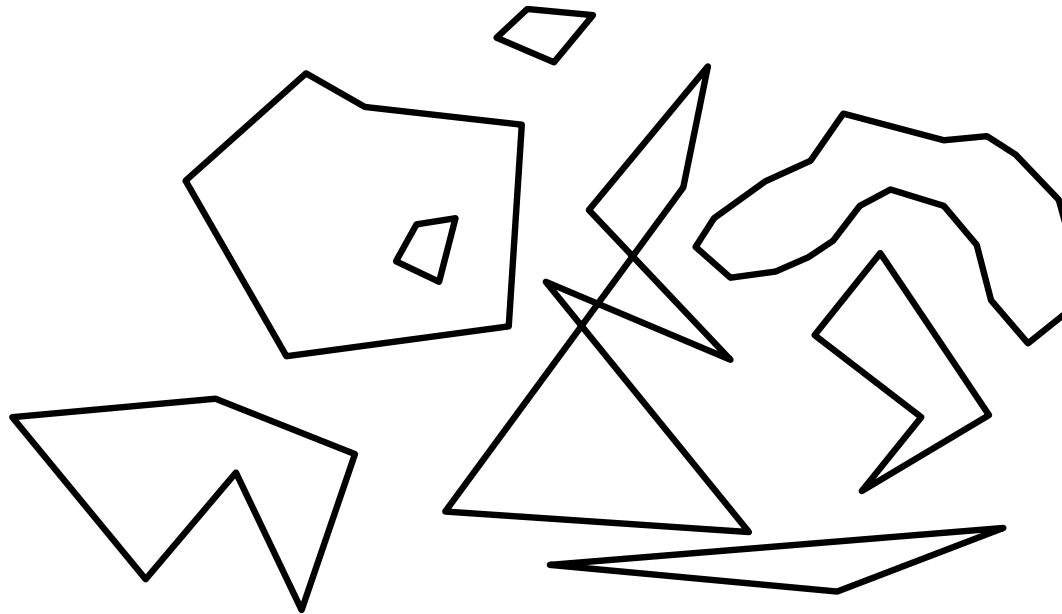
Exercise 4

Which rectangles completely lie in this rectangle?



Data structure with $\mathcal{O}(n \log^3 n)$ storage and $\mathcal{O}(\log^4 n + k)$ query time.

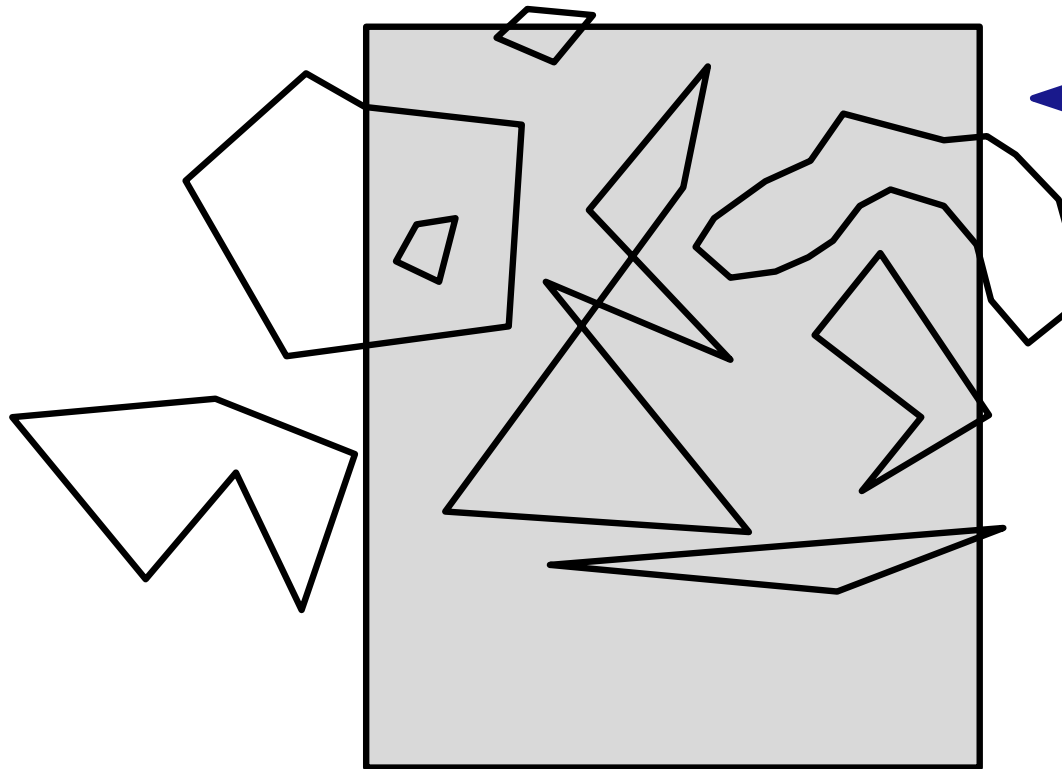
Exercise 4



Data structure with $\mathcal{O}(n \log^3 n)$ storage and $\mathcal{O}(\log^4 n + k)$ query time.

Exercise 4

Which polygons completely lie in this rectangles?



Data structure with $\mathcal{O}(n \log^3 n)$ storage and $\mathcal{O}(\log^4 n + k)$ query time.