Drawing Trees with Perfect Angular Resolution and Polynomial Area

Christian A. Duncan · Quinnipiac University David Eppstein · University of California Irvine Michael T. Goodrich · University of California Irvine Stephen G. Kobourov · University of Arizona Tucson *Martin Nöllenburg* · KIT

Vorlesung Algorithmen zur Visualisierung von Graphen · 05.02.2013





crossing-free edges



crossing-free edgeseasy-to-follow edges



crossing-free edges
good angular resolution
easy-to-follow edges



crossing-free edges good angular resolution easy-to-follow edges small space consumption



crossing-free edgeseasy-to-follow edges

- good angular resolution
- small space consumption



Our results

Any tree has a drawing with

- crossing-free edges
- perfect angular resolution
- polynomial area

	unordered trees	ordered trees
straight edges		×

Our results

Any tree has a drawing with

- crossing-free edges
- perfect angular resolution
- polynomial area

	unordered trees	ordered trees
straight edges		\mathbf{X}
?		?? ??????????????????????????????????</td

Inspiration from fine arts



Mark Lombardi "Pat Robertson, Beurt Servaas, and the UPI Takeover Battle, ca. 1985-91"

Edges in Mark Lombardi's network drawings

- easy-to-follow circular arcs
- generalization of straight-line edges

Inspiration from fine arts



Mark Lombardi "Pat Robertson, Beurt Servaas, and the UPI Takeover Battle, ca. 1985-91"

Edges in Mark Lombardi's network drawings

- easy-to-follow circular arcs
- generalization of straight-line edges

Draw edges as circular arcs!

Our results

Any tree has a drawing with

- crossing-free edges
- perfect angular resolution
- polynomial area

	unordered trees	ordered trees
straight edges		
Lombardi edges		

Related work

Straight-line drawings of trees

old topic in graph drawing

[Wetherell & Shannon, 1979]

optimize area but not angular resolution



[Wetherell & Shannon, 1979]



[Garg, Goodrich, Tamassia, 1994]

[Garg & Rusu, 2004]

Related work

Straight-line drawings of trees

- old topic in graph drawing
- optimize area but not angular resolution

Angular-resolution-aware tree drawings

- circular drawings for rooted trees
- bubble drawings for ordered trees
- balloon drawings for (un)ordered trees

[Melançon & Herman, 1998]

[Wetherell & Shannon, 1979]

[Grivet et al., 2004]

[Lin & Yen, 2007]

closer to our goal but no guarantee of all constraints



C. Duncan \cdot D. Eppstein \cdot M. Goodrich \cdot S. Kobourov \cdot M. Nöllenburg

Related work

Straight-line drawings of trees

- old topic in graph drawing
 - optimize area but not angular resolution

[Wetherell & Shannon, 1979]

Angular-resolution-aware tree drawings

- circular drawings for rooted trees
- bubble drawings for ordered trees
- balloon drawings for (un)ordered trees
- closer to our goal but no guarantee of all constraints

Drawing graphs with smooth curves

circular arcs for planar graphs with bounded angular resolution

[Cheng et al., 2001]

force-directed curvilinear drawings to improve angular resolution

[Finkel & Tamassia, 2004]

[Melançon & Herman, 1998]

[Grivet et al., 2004]

[Lin & Yen, 2007]

Overview

Any tree has a drawing with

- crossing-free edges
- perfect angular resolution
- polynomial area

	unordered trees	ordered trees
straight edges		1
Lombardi edges		2

Ordered trees and straight-line edges

Fibonacci caterpillars

There is an infinite family of trees that require exponential area in any straight-line drawing with perfect angular resolution.

Ordered trees and straight-line edges

Fibonacci caterpillars

There is an infinite family of trees that require exponential area in any straight-line drawing with perfect angular resolution.



Overview

Any tree has a drawing with

- crossing-free edges
- perfect angular resolution
- polynomial area

	unordered trees	ordered trees
straight edges		
Lombardi edges		2

Heavy path decomposition (I)

Definition

- choose arbitrary root \boldsymbol{r} of tree \boldsymbol{T}
- u is the **heavy child** of v if subtree T_u is largest among children of v
- all other children of v are **light children** in a set L(v)
- edge (u, v) from heavy child u to parent v is a heavy edge
- edges from light children to parent v are **light edges**



Heavy path decomposition (I)

Definition

- choose arbitrary root \boldsymbol{r} of tree \boldsymbol{T}
- u is the **heavy child** of v if subtree T_u is largest among children of v
- all other children of v are **light children** in a set L(v)
- edge (u, v) from heavy child u to parent v is a heavy edge
- edges from light children to parent v are **light edges**



Heavy path decomposition (II)

Definition

The set of heavy edges induces the **heavy path decomposition** (HPD) of T into heavy paths and singleton nodes. [Harel & Tarjan, 1984]

Property

The HPD induces a decomposition tree H(T) of height $h \leq \log_2 n$.



Drawing ordered trees

Sketch of the algorithm

- draw each heavy path P of T within a disk of polynomial area
- each heavy path at level $j \geq 1$ of H(T) is a light child of a heavy path at level j-1
- $\bullet\,$ given drawings of all heavy paths at level j recursively construct drawings of all heavy paths at level j-1



Input

- heavy path $P = (v_1, v_2, \ldots, v_k)$ rooted at v_k
- required angles $\alpha_i = c \cdot \frac{2\pi}{\deg(v_i)}$ between $v_{i-1}v_i$ and v_iv_{i+1} ($c \in \mathbb{N}$)
- disks D_i containing v_i and all subtrees of light children of v_i

place leaf v_1 and disk D_1 in the center

- heavy path $P = (v_1, v_2, \ldots, v_k)$ rooted at v_k
- required angles $\alpha_i = c \cdot \frac{2\pi}{\deg(v_i)}$ between $v_{i-1}v_i$ and v_iv_{i+1} ($c \in \mathbb{N}$)
- disks D_i containing v_i and all subtrees of light children of v_i



- heavy path $P = (v_1, v_2, \ldots, v_k)$ rooted at v_k
- required angles $\alpha_i = c \cdot \frac{2\pi}{\deg(v_i)}$ between $v_{i-1}v_i$ and v_iv_{i+1} ($c \in \mathbb{N}$)
- disks D_i containing v_i and all subtrees of light children of v_i



• heavy path
$$P = (v_1, v_2, \ldots, v_k)$$
 rooted at v_k

- required angles $\alpha_i = c \cdot \frac{2\pi}{\deg(v_i)}$ between $v_{i-1}v_i$ and v_iv_{i+1} ($c \in \mathbb{N}$)
- disks D_i containing v_i and all subtrees of light children of v_i



• heavy path
$$P = (v_1, v_2, \ldots, v_k)$$
 rooted at v_k

- required angles $\alpha_i = c \cdot \frac{2\pi}{\deg(v_i)}$ between $v_{i-1}v_i$ and v_iv_{i+1} ($c \in \mathbb{N}$)
- disks D_i containing v_i and all subtrees of light children of v_i



- heavy path $P = (v_1, v_2, \dots, v_k)$ rooted at v_k
- required angles $\alpha_i = c \cdot \frac{2\pi}{\deg(v_i)}$ between $v_{i-1}v_i$ and v_iv_{i+1} ($c \in \mathbb{N}$)
- disks D_i containing v_i and all subtrees of light children of v_i



- heavy path $P = (v_1, v_2, \ldots, v_k)$ rooted at v_k
- required angles $\alpha_i = c \cdot \frac{2\pi}{\deg(v_i)}$ between $v_{i-1}v_i$ and v_iv_{i+1} ($c \in \mathbb{N}$)
- disks D_i containing v_i and all subtrees of light children of v_i



Step 2: Drawing light children

Distinguish two cases

Given a node v of a heavy path draw its light children in the given order within disk D. The two heavy edges incident to v divide D into

- small zone with opening angle $\leq \pi$
- large zone with opening angle $>\pi$



Choose the right disk radii

Definition

For heavy path node v at level j of HPD ${\cal H}(T)$ define disk radius

$$r_v = 4^{h-j} (1 + \sum_{u \in L(v)} |T_u|).$$



Choose the right disk radii

Definition

For heavy path node v at level j of HPD ${\cal H}(T)$ define disk radius

$$r_v = 4^{h-j} (1 + \sum_{u \in L(v)} |T_u|).$$

Induction hypothesis

A heavy path P with root v at level j of H(T) is contained in a disk of radius $R_v = 2 \cdot 4^{h-j} |T_v|$.



C. Duncan · D. Eppstein · M. Goodrich · S. Kobourov · N. Nöllenburg

Choose the right disk radii

Definition

For heavy path node v at level j of HPD ${\cal H}(T)$ define disk radius

$$r_v = 4^{h-j} (1 + \sum_{u \in L(v)} |T_u|).$$

Induction hypothesis

A heavy path P with root v at level j of H(T) is contained in a disk of radius $R_v=2\cdot 4^{h-j}|T_v|.$

Lemma

Every light child of a heavy path node v at level j is the root of a heavy path at level j + 1. Hence

$$\sum_{u \in L(v)} R_u = \sum_{u \in L(v)} (2 \cdot 4^{h-j-1} |T_u|) = \frac{1}{2} \cdot 4^{h-j} \sum_{u \in L(v)} |T_u| \le \frac{r_v}{2}.$$

C. Duncan \cdot D. Eppstein \cdot M. Goodrich \cdot S. Kobourov \cdot M. Nöllenburg

























Place light children in large zone



placement similar to the small zone: split large zone into two small parts and apply same method

C. Duncan · D. Eppstein · M. Goodrich · S. Kobourov · M. Nöllenburg

Main result

Theorem

Given an ordered tree T with n nodes our algorithm finds a drawing of T with crossing-free Lombardi edges and perfect angular resolution within a disk of radius $2n^3$.

Main result

Theorem

Given an ordered tree T with n nodes our algorithm finds a drawing of T with crossing-free Lombardi edges and perfect angular resolution within a disk of radius $2n^3$.

Proof:

- inductive construction places every heavy path P at level j with root node v within a disk of radius $R=2\cdot 4^{h-j}|T_v|$
- heavy path at level 0 corresponds to full tree ${\cal T}$
- height of the HPD is $h \leq \log_2 n$
- radius of disk containing T is $R=2\cdot 4^{\log_2 n}n=2\cdot n^3$



Summary

Any tree has a drawing with

- crossing-free edges
- perfect angular resolution
- polynomial area

	unordered trees	ordered trees
straight edges		\mathbf{X}
Lombardi edges		

Summary

Any tree has a drawing with

- crossing-free edges
- perfect angular resolution
- polynomial area

	unordered trees	ordered trees
straight edges		×
Lombardi edges		

Open questions

- area bound unlikely to be tight
- find simpler algorithms for special classes of trees (e.g. bounded degree)

